

Representing and comparing probabilities with kernels: Part 3

Arthur Gretton

Gatsby Computational Neuroscience Unit,
University College London

MLSS Madrid, 2018

Training GANs with MMD

What is a Generative Adversarial Network (GAN)?

- **Generator** (student)



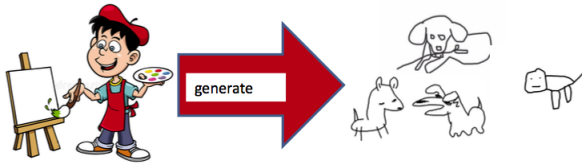
- Task: **critic** must teach **generator** to draw images (here dogs)



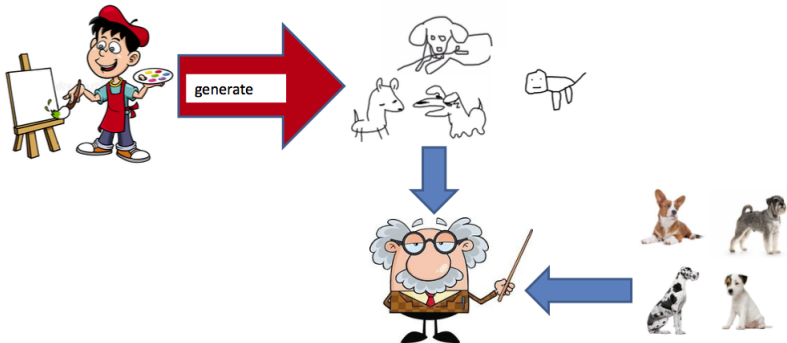
- **Critic** (teacher)



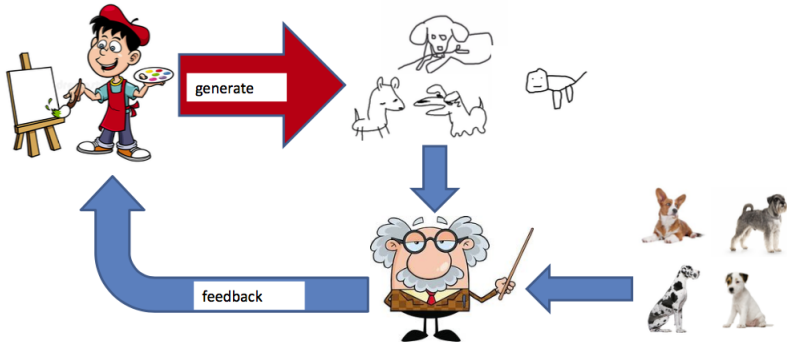
What is a Generative Adversarial Network (GAN)?



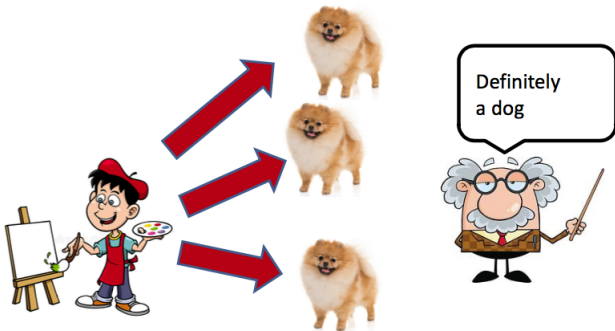
What is a Generative Adversarial Network (GAN)?



What is a Generative Adversarial Network (GAN)?



Why is classification not enough?



Classification **not** enough!
Need to compare **sets**

(otherwise student can just produce the **same dog** over and over)

MMD for GAN critic

Can you use **MMD** as a **critic** to train GANs?

From ICML 2015:

Generative Moment Matching Networks

Yujia Li¹

Kevin Swersky¹

Richard Zemel^{1,2}

YUJIALI@CS.TORONTO.EDU

KSWERSKY@CS.TORONTO.EDU

ZEMEL@CS.TORONTO.EDU

¹Department of Computer Science, University of Toronto, Toronto, ON, CANADA

²Canadian Institute for Advanced Research, Toronto, ON, CANADA

From UAI 2015:

Training generative neural networks via Maximum Mean Discrepancy optimization

Gintare Karolina Dziugaite
University of Cambridge

Daniel M. Roy
University of Toronto

Zoubin Ghahramani
University of Cambridge

MMD for GAN critic

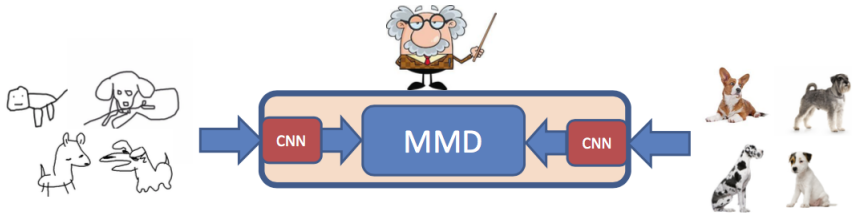
Can you use **MMD** as a critic to train GANs?



Need better image features.

How to improve the critic witness

- Add convolutional features!
- The **critic** (teacher) also needs to be trained.
- How to regularise?



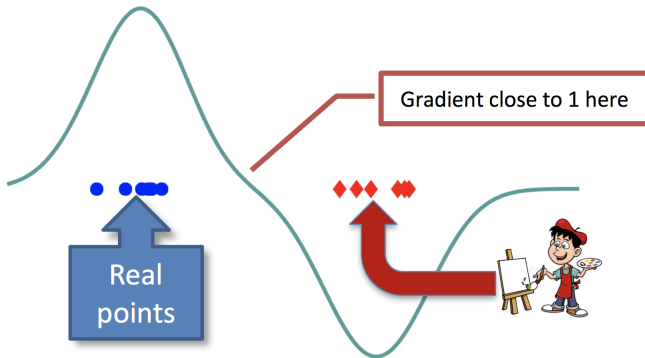
MMD GAN Li et al., [NIPS 2017]

Coulomb GAN Unterthiner et al., [ICLR 2018]

WGAN-GP

Wasserstein GAN Arjovsky et al. [ICML 2017]

WGAN-GP Gukrajani et al. [NIPS 2017]



WGAN-GP

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- Given a generator G_θ with parameters θ to be trained.
Samples $Y \sim G_\theta(Z)$ where $Z \sim R$



- Given critic features h_ψ with parameters ψ to be trained. f_ψ
a **linear function** of h_ψ .

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WGAN-GP gradient penalty:

$$\max_{\psi} \mathbf{E}_{X \sim P} f_{\psi}(X) - \mathbf{E}_{Z \sim R} f_{\psi}(G_{\theta}(Z)) + \lambda \mathbf{E}_{\tilde{X}} \left(\left\| \nabla_{\tilde{X}} f_{\theta}(\tilde{X}) \right\| - 1 \right)^2$$

where

$$\tilde{X} = \gamma x_i + (1 - \gamma) G_{\psi}(z_j)$$

$$\gamma \sim \mathcal{U}([0, 1]) \quad x_i \in \{x_{\ell}\}_{\ell=1}^m \quad z_j \in \{z_{\ell}\}_{\ell=1}^n$$

The (W)MMD


Train **MMD critic** features with the **witness function gradient penalty**

Binkowski, Sutherland, Arbel, G. [ICLR 2018], Bellemare et al. [2017] for energy distance:

$$\max_{\psi} \text{MMD}^2(h_{\psi}(X), h_{\psi}(G_{\theta}(Z))) + \lambda \mathbf{E}_{\tilde{X}} \left(\left\| \nabla_{\tilde{X}} f_{\psi}(\tilde{X}) \right\| - 1 \right)^2$$

where

$$f_{\psi}(\cdot) = \frac{1}{m} \sum_{i=1}^m k(h_{\psi}(x_i), \cdot) - \frac{1}{n} \sum_{j=1}^n k(h_{\psi}(G_{\theta}(z_j)), \cdot)$$

 **New**

$$\tilde{X} = \gamma x_i + (1 - \gamma) G_{\psi}(z_j)$$

$$\gamma \sim \mathcal{U}([0, 1]) \quad x_i \in \{x_{\ell}\}_{\ell=1}^m \quad z_j \in \{z_{\ell}\}_{\ell=1}^n$$

Remark by Bottou et al. (2017): gradient penalty modifies the function class. So critic is not an MMD in RKHS \mathcal{F} .

MMD for GAN critic: revisited

From ICLR 2018:

DEMYSTIFYING MMD GANS

Mikołaj Bińkowski*

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Imperial College London

mikbinkowski@gmail.com

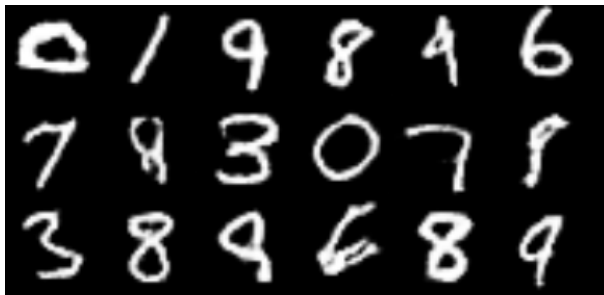
Dougal J. Sutherland, Michael Arbel & Arthur Gretton

Gatsby Computational Neuroscience Unit

University College London

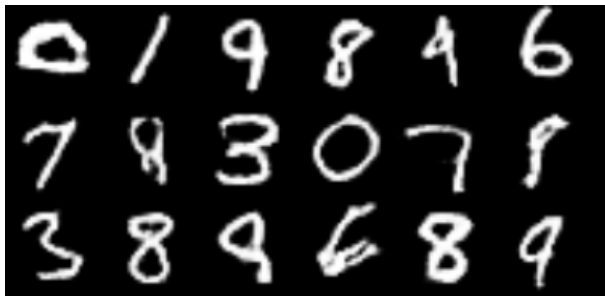
{dougal, michael.n.arbel, arthur.gretton}@gmail.com

MMD for GAN critic: revisited



Samples are better!

MMD for GAN critic: revisited



Samples are better!

Can we do better still?

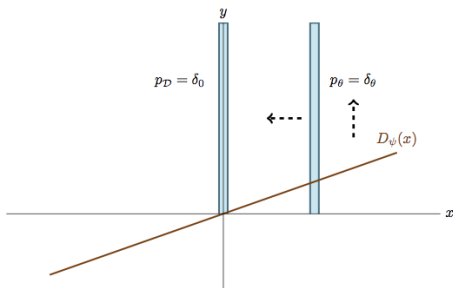
Convergence issues for WGAN-GP penalty

WGAN-GP style gradient penalty **may not converge near solution**

Nagarajan and Kolter [NIPS 2017], Mescheder et al. [ICML 2018], Balduzzi et al. [ICML 2018]

The Dirac-GAN

$$P = \delta_0 \quad Q = \delta_\theta \quad f_\psi(x) = \psi \cdot x$$



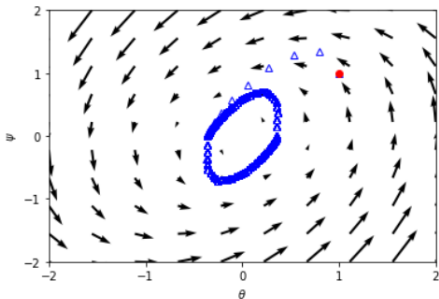
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A better gradient penalty

- New MMD GAN witness regulariser (just accepted, NIPS 2018)

Arbel, Sutherland, Binkowski, G. [NIPS 2018]

- Based on [semi-supervised learning](#) regulariser Bousquet et al. [NIPS 2004]

- Related to [Sobolev GAN](#) Mroueh et al. [ICLR 2018]

arXiv.org > stat > arXiv:1805.11565

Statistics > Machine Learning

On gradient regularizers for MMD GANs

Michael Arbel, Dougal J. Sutherland, [Mikołaj Bińkowski](#), Arthur Gretton

(Submitted on 29 May 2018)

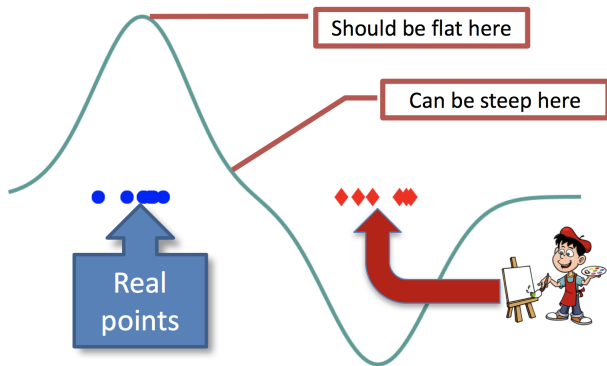
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Modified witness function:

$$\widetilde{MMD} := \sup_{\|f\|_S \leq 1} [\mathbb{E}_P f(X) - \mathbb{E}_Q f(Y)]$$

where

$$\|f\|_S^2 = \underbrace{\|f\|_{L_2(P)}^2}_{\text{L}_2 \text{ norm control}} + \underbrace{\|\nabla f\|_{L_2(P)}^2}_{\text{Gradient control}} + \lambda \underbrace{\|f\|_k^2}_{\text{RKHS smoothness}}$$

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The diagram shows three boxes below the equation, each with an upward-pointing arrow indicating its contribution to the norm:

- L₂ norm control**: Points to the $\|f\|_{L_2(P)}^2$ term.
- Gradient control**: Points to the $\|\nabla f\|_{L_2(P)}^2$ term.
- RKHS smoothness**: Points to the $\lambda \|f\|_k^2$ term.

Problem: not computationally feasible: $O(n^3)$ per iteration.

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The scaled MMD:

$$SMMD = \sigma_{k,P,\lambda} MMD$$

where

$$\sigma_{k,P,\lambda} = \left(\lambda + \int k(x, x) dP(x) + \sum_{i=1}^d \int \partial_i \partial_{i+d} k(x, x) dP(x) \right)^{-1/2}$$

Replace expensive constraint with cheap upper bound:

$$\|f\|_S^2 \leq \sigma_{k,P,\lambda}^{-1} \|f\|_k^2$$

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Idea: rather than regularise the critic or witness function, regularise features directly

Evaluation and experiments

Evaluation of GANs

The inception score? Salimans et al. [NIPS 2016]

Based on the classification output $p(y|x)$ of the inception model Szegedy et al. [ICLR 2014],

$$E_X \exp KL(P(y|X) || P(y)).$$

High when:

- predictive label distribution $P(y|x)$ has low entropy (good quality images)
- label entropy $P(y)$ is high (good variety).

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Problem: relies on a trained classifier! Can't be used on new categories (celeb, bedroom...)

Evaluation of GANs

The Frechet inception distance? Heusel et al. [NIPS 2017]

Fits Gaussians to features in the inception architecture (pool3 layer):

$$FID(P, Q) = \|\mu_P - \mu_Q\|^2 + \text{tr}(\Sigma_P) + \text{tr}(\Sigma_Q) - 2\text{tr}\left((\Sigma_P \Sigma_Q)^{\frac{1}{2}}\right)$$

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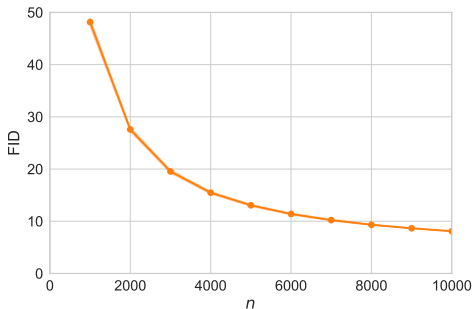
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where μ_P and Σ_P are the feature mean and covariance of P

Problem: bias. For finite samples can consistently give incorrect answer.

- Bias demo, CIFAR-10 train vs test



Evaluation of GANs

The FID can give the **wrong answer in theory**.

Assume m samples from P and $n \rightarrow \infty$ samples from Q .

Given two alternatives:

$$P_1 \sim \mathcal{N}(0, (1 - m^{-1})^2) \quad P_2 \sim \mathcal{N}(0, 1) \quad Q \sim \mathcal{N}(0, 1).$$

Clearly,

$$FID(P_1, Q) = \frac{1}{m^2} > FID(P_2, Q) = 0$$

Given m samples from P_1 and P_2 ,

$$FID(\widehat{P}_1, Q) < FID(\widehat{P}_2, Q).$$

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Evaluation of GANs

The FID can give the **wrong answer in practice**.

Let $d = 2048$, and define

$$P_1 = \text{relu}(\mathcal{N}(0, I_d)) \quad P_2 = \text{relu}(\mathcal{N}(1, .8\Sigma + .2I_d)) \quad Q = \text{relu}(\mathcal{N}(1, I_d))$$

where $\Sigma = \frac{4}{d} CC^T$, with C a $d \times d$ matrix with iid standard normal entries.

For a random draw of C :

$$FID(P_1, Q) \approx 1123.0 > 1114.8 \approx FID(P_2, Q)$$

With $m = 50\,000$ samples,

$$FID(\widehat{P}_1, Q) \approx 1133.7 < 1136.2 \approx FID(\widehat{P}_2, Q)$$

At $m = 100\,000$ samples, the ordering of the estimates is correct.

This behavior is similar for other random draws of C .

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The kernel inception distance (KID)

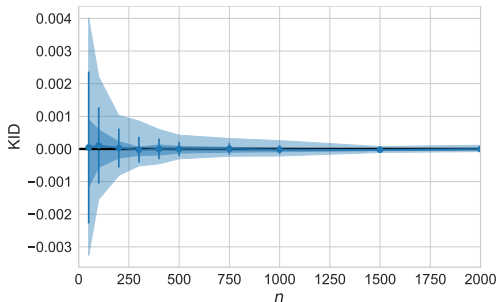
The Kernel inception distance Binkowski, Sutherland, Arbel, G. [ICLR 2018]

Measures similarity of the samples' representations in the inception architecture (pool3 layer)

MMD with kernel

$$k(x, y) = \left(\frac{1}{d} x^\top y + 1 \right)^3.$$

- Checks match for feature means, variances, skewness
- **Unbiased** : eg CIFAR-10 train/test



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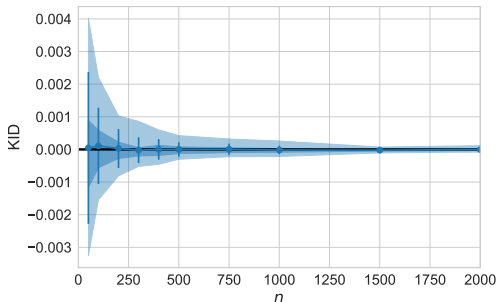
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...“but isn't KID is computationally costly?”

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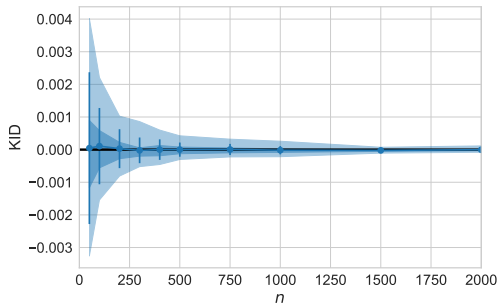
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...“but isn’t KID is computationally costly?”

“Block” KID implementation is cheaper than FID: see paper
(or use [Tensorflow implementation](#))!

The kernel inception distance (KID)

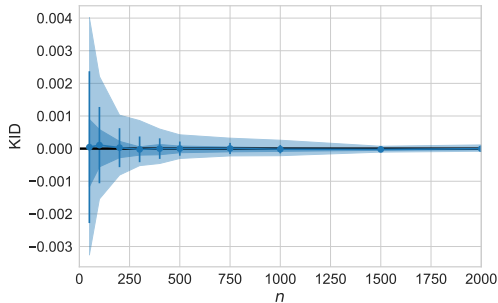
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Also used for automatic learning rate adjustment: if $KID(\hat{P}_{t+1}, Q)$ not significantly better than $KID(\hat{P}_t, Q)$ then reduce learning rate.

[Bounliphone et al. ICLR 2016]

Benchmarks for comparison (all from ICLR 2018)

SPECTRAL NORMALIZATION FOR GENERATIVE ADVERSARIAL NETWORKS

Takeru Miyato¹, Toshiki Kataoka¹, Masanori Koyama², Yuichi Yoshida³

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1Preferred Networks, Inc. 2Ritsumeikan University 3National Institute of Informatics

We
combine
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MMD

DEMYSTIFYING MMD GANS

Mikołaj Białkowski¹

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Dougal J. Sutherland¹, Michael Arbel & Arthur Gretton

Gatsby Computational Neuroscience Unit

Imperial College London

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Our ICLR
2018
paper

SOBOLEV GAN

Youssef Mroueh¹, Chun-Liang Li^{2,*}, Tom Sercu^{1,*}, Anant Raj^{3,*} & Yu Cheng¹

[†] IBM Research AI

^o Carnegie Mellon University

[◊] Max Planck Institute for Intelligent Systems

* denotes Equal Contribution

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tom.sercu@ibm.com, anant.raj@tuebingen.mpg.de

BOUNDARY-SEEKING GENERATIVE ADVERSARIAL NETWORKS

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Yoshua Bengio

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Results: what does MMD buy you?

- **Critic** features from **DCGAN**: an f -filter critic has f , $2f$, $4f$ and $8f$ convolutional filters in layers 1-4. LSUN 64×64 .



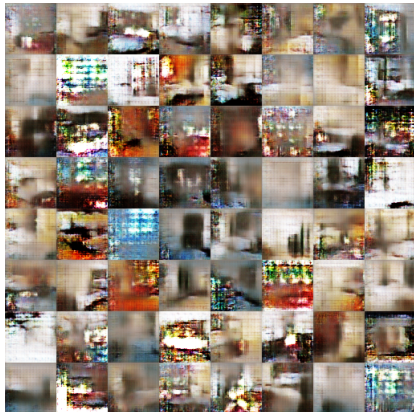
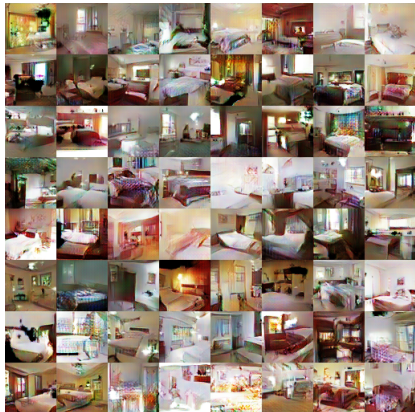
MMD GAN samples, $f = 64$,
FID=32, KID=3



WGAN samples, $f = 64$,
FID=41, KID=4 ^{19/71}

Results: what does MMD buy you?

- **Critic** features from **DCGAN**: an f -filter critic has f , $2f$, $4f$ and $8f$ convolutional filters in layers 1-4. LSUN 64×64 .

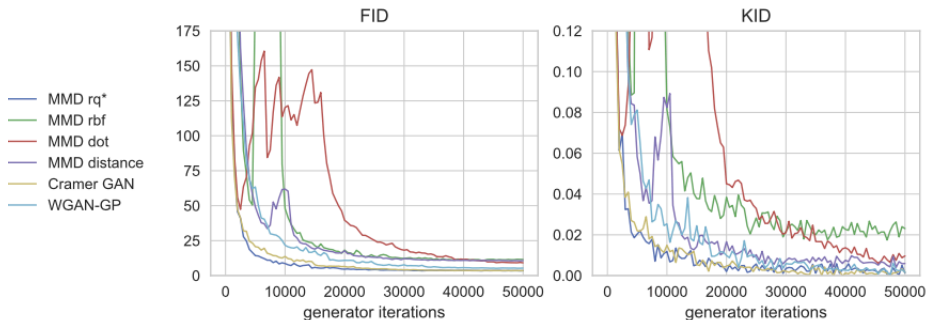


MMD GAN samples, $f = 16$,
FID=86, KID=9

WGAN samples, $f = 16$,
 $f = 64$, FID=293, KID=37^{19/71}

The kernel inception distance (KID)

Faster training: performance scores vs generator iterations on MNIST



Results: celebrity faces 160×160

KID (FID)

scores:

■ Sobolev GAN:

14 (20)

■ SN-GAN:

18 (28)

■ Old MMD
GAN:

13 (21)

■ SMMD GAN:

6 (12)

202 599 face images, re-
sized and cropped to 160
× 160



Results: imagenet 64×64

KID (FID)

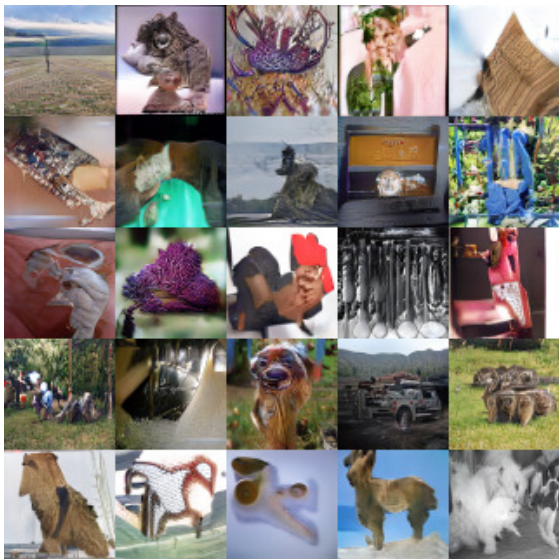
scores:

■ **BGAN:**
47 (44)

■ **SN-GAN:**
44 (48)

■ **SMMD GAN:**
35 (37)

ILSVRC2012 (ImageNet)
dataset, 1 281 167 im-
ages, resized to 64 × 64.
Around 20 000 classes.



Results: imagenet 64×64

KID (FID)
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■ BGAN:
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ILSVRC2012 (ImageNet)
dataset, 1 281 167 im-
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Around 20 000 classes.



Summary

- MMD critic gives **state-of-the-art performance for GAN training** (FID and KID)
 - use convolutional input features
 - train with **new gradient regulariser**
- Faster training, simpler critic network
- **Reasons for good performance:**
 - Unlike WGAN-GP, MMD loss still a valid critic when features not optimal
 - Kernel features do some of the “work”, so simpler h_ψ features possible.
 - Better gradient/feature regulariser gives better critic

Code for “Demystifying MMD GANs,” ICLR 2018, including KID score: <https://github.com/mbinkowski/MMD-GAN>

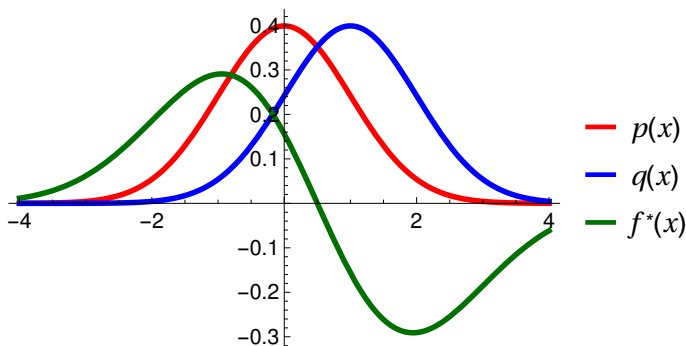
Code for new SMMD:

<https://github.com/MichaelArbel/Scaled-MMD-GAN>

Testing against a probabilistic model

Statistical model criticism

$$MMD(P, Q) = \|f^*\|^2 = \sup_{\|f\|_{\mathcal{F}} \leq 1} [E_Q f - E_P f]$$



$f^*(x)$ is the witness function

Can we compute MMD with samples from Q and a **model** P ?

Problem: usually can't compute $E_P f$ in closed form.

Stein idea

To get rid of $E_p f$ in

$$\sup_{\|f\|_{\mathcal{F}} \leq 1} [E_q f - E_p f]$$

we define the **Stein operator**

$$[T_p f](x) = \frac{1}{p(x)} \frac{d}{dx} (f(x)p(x))$$

Then

$$E_P T_P f = 0$$

subject to appropriate boundary conditions. (Oates, Girolami, Chopin, 2016)

Stein idea: proof

$$\begin{aligned} E_p [T_p f] &= \int \left[\frac{1}{p(x)} \frac{d}{dx} (f(x)p(x)) \right] p(x) dx \\ &= \int \left[\frac{d}{dx} (f(x)p(x)) \right] dx \\ &= [f(x)p(x)]_{-\infty}^{\infty} \\ &= 0 \end{aligned}$$

Stein idea: proof

$$\begin{aligned} E_p [T_p f] &= \int \left[\frac{1}{\cancel{p(x)}} \frac{d}{dx} (f(x)p(x)) \right] \cancel{p(x)} dx \\ &= \int \left[\frac{d}{dx} (f(x)p(x)) \right] dx \\ &= [f(x)p(x)]_{-\infty}^{\infty} \\ &= 0 \end{aligned}$$

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Kernel Stein Discrepancy

Stein operator

$$T_p f = \frac{1}{p(x)} \frac{d}{dx} (f(x)p(x))$$

Kernel Stein Discrepancy (KSD)

$$KSD(p, q, \mathcal{F}) = \sup_{\|g\|_{\mathcal{F}} \leq 1} E_q T_p g - E_p T_p g$$

Kernel Stein Discrepancy

Stein operator

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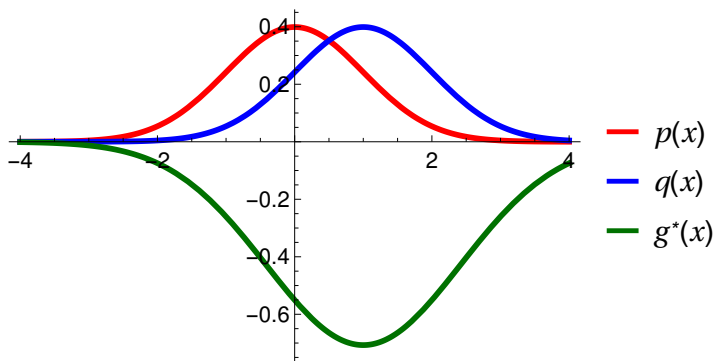
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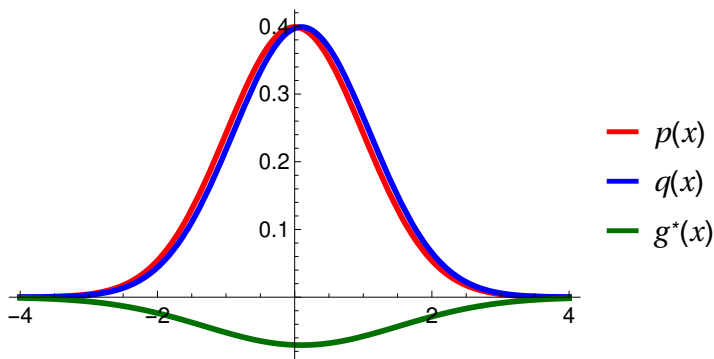
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Kernel stein discrepancy

Closed-form expression for KSD: given $Z, Z' \sim q$, then
(Chwialkowski, Strathmann, G., ICML 2016) (Liu, Lee, Jordan ICML 2016)

$$\text{KSD}(p, q, \mathcal{F}) = E_q h_p(Z, Z')$$

where

$$\begin{aligned} h_p(x, y) := & \partial_x \log p(x) \partial_x \log p(y) k(x, y) \\ & + \partial_y \log p(y) \partial_x k(x, y) \\ & + \partial_x \log p(x) \partial_y k(x, y) \\ & + \partial_x \partial_y k(x, y) \end{aligned}$$

and k is RKHS kernel for \mathcal{F}

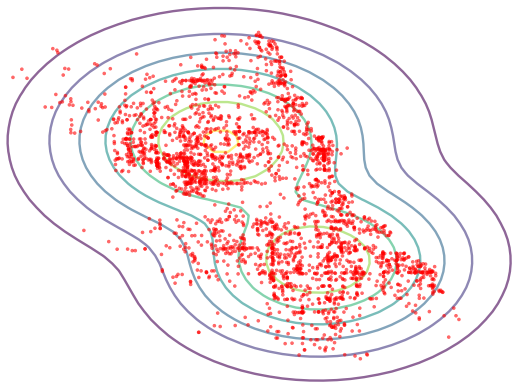
Only depends on kernel and $\partial_x \log p(x)$. Do not need to normalize p , or sample from it.

Statistical model criticism



Chicago crime data

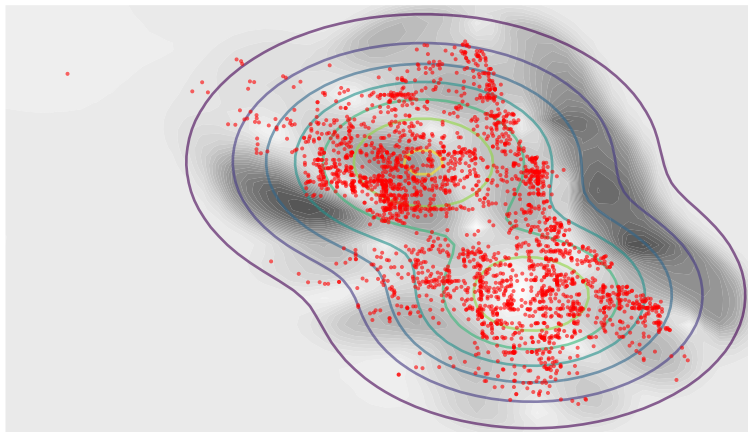
Statistical model criticism



Chicago crime data

Model is Gaussian mixture with **two** components.

Statistical model criticism

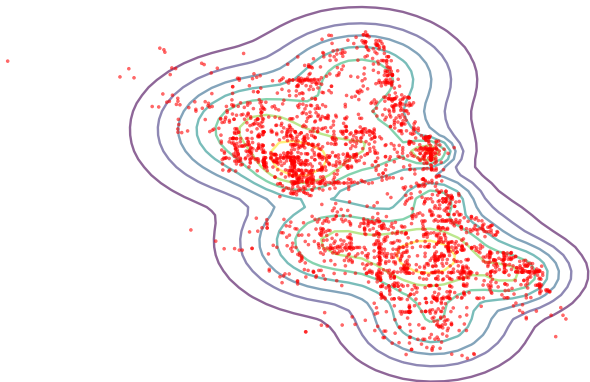


Chicago crime data

Model is Gaussian mixture with **two** components

Stein witness function

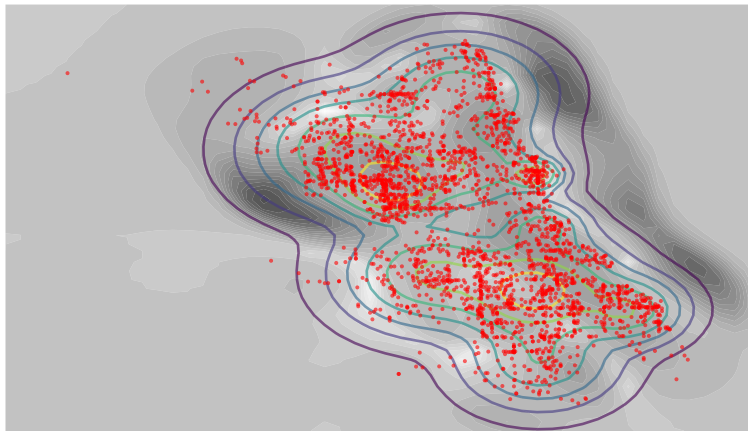
Statistical model criticism



Chicago crime data

Model is Gaussian mixture with **ten** components.

Statistical model criticism



Chicago crime data

Model is Gaussian mixture with **ten** components

Stein witness function

Code: https://github.com/karlnapf/kernel_goodness_of_fit

Kernel stein discrepancy

Further applications:

- Evaluation of approximate MCMC methods.

(Chwialkowski, Strathmann, G., ICML 2016; Gorham, Mackey, ICML 2017)

What kernel to use?

- The inverse multiquadric kernel,

$$k(x, y) = \left(c + \|x - y\|_2^2 \right)^\beta$$

for $\beta \in (-1, 0)$.

arXiv.org > stat > arXiv:1703.01717

Statistics > Machine Learning

Measuring Sample Quality with Kernels

Jackson Gorham, Lester Mackey




ICML 2017

(Submitted on 6 Mar 2017 (v1), last revised 3 Aug 2017 (this version, v6))

Testing statistical dependence

Dependence testing

- Given: Samples from a distribution $P_{X,Y}$
- Goal: Are X and Y independent?

X	Y
	A large animal who slings slobber, exudes a distinctive houndy odor, and wants nothing more than to follow his nose.
	Their noses guide them through life, and they're never happier than when following an interesting scent.
	A responsive, interactive pet, one that will blow in your ear and follow you everywhere.

Text from dogtime.com and petfinder.com

MMD as a dependence measure?

Could we use MMD?

$$MMD(\underbrace{P_{XY}}_P, \underbrace{P_X P_Y}_Q, \mathcal{H}_\kappa)$$

- We don't have samples from $Q := P_X P_Y$, only pairs $\{(x_i, y_i)\}_{i=1}^n \stackrel{\text{i.i.d.}}{\sim} P_{XY}$
 - **Solution:** simulate Q with pairs (x_i, y_j) for $j \neq i$.
- What kernel κ to use for the RKHS \mathcal{H}_κ ?

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MMD as a dependence measure

Kernel k on images with feature space \mathcal{F} ,

$$k(\text{dog image}, \text{cat image})$$

Kernel l on captions with feature space \mathcal{G} ,

$$l(\text{A large animal who slings slobber, ...}, \text{A responsive, interactive pet ...})$$

MMD as a dependence measure

Kernel k on **images** with feature space \mathcal{F} ,

$$k(\text{dog image}, \text{cat image})$$

Kernel l on **captions** with feature space \mathcal{G} ,

$$l(\text{caption box}, \text{caption box})$$

Kernel κ on **image-text pairs**: **are images and captions similar?**

$$\kappa(\text{dog image} \text{ with caption } \text{A large animal who slings slobber, ...}, \text{cat image} \text{ with caption } \text{A responsive, interactive pet, ...})$$

$$= k(\text{dog image}, \text{cat image}) \times l(\text{caption box}, \text{caption box})$$

MMD as a dependence measure

- **Given:** Samples from a distribution P_{XY}
- **Goal:** Are X and Y independent?

$$MMD^2(\hat{P}_{XY}, \hat{P}_X \hat{P}_Y, \mathcal{H}_\kappa) := \frac{1}{n^2} \text{trace}(KL)$$

(K, L column centered)

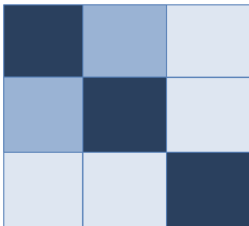
MMD as a dependence measure

- Given: Samples from a distribution P_{XY}
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K

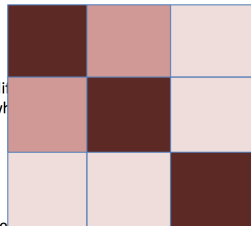


A large animal who slings slobber, exudes a distinctive houndy odor, ...

Their noses guide them through life and they're never happier than when following an interesting scent.

A responsive, interactive pet, one that will blow in your ear and follow you everywhere.

L



MMD as a dependence measure

Two questions:

- Why the product kernel? Many ways to combine kernels - why not eg a sum?
- Is there a more interpretable way of defining this dependence measure?

Illustration: dependence \neq correlation

- Given: Samples from a distribution P_{XY}
- Goal: Are X and Y dependent?

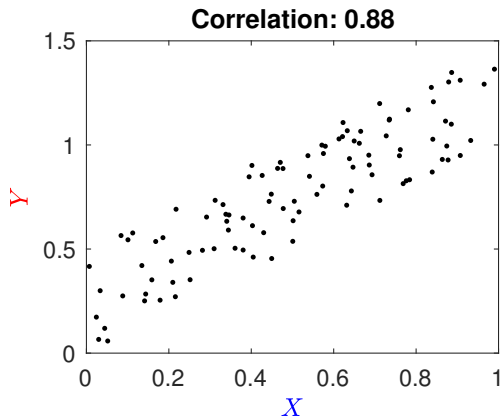


Illustration: dependence \neq correlation

- Given: Samples from a distribution P_{XY}
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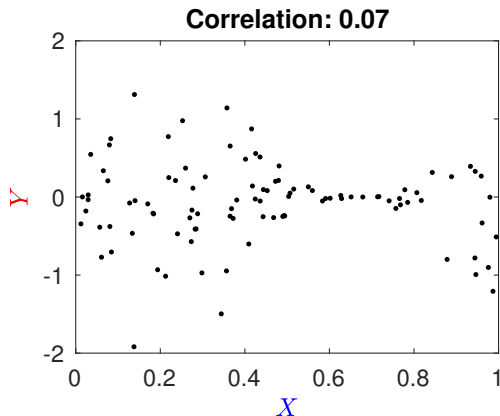
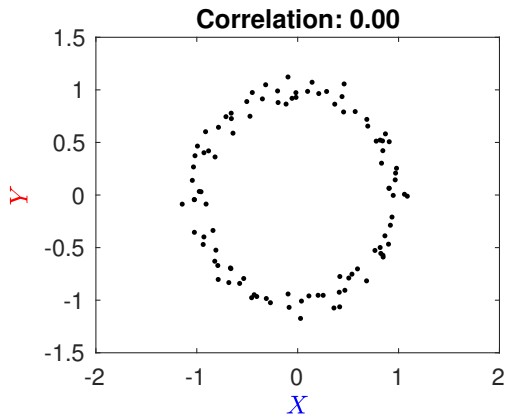


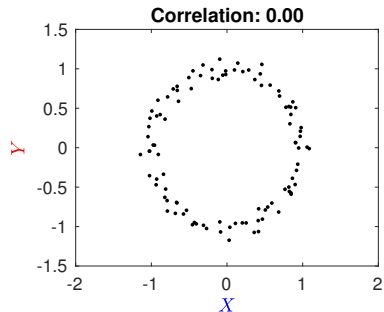
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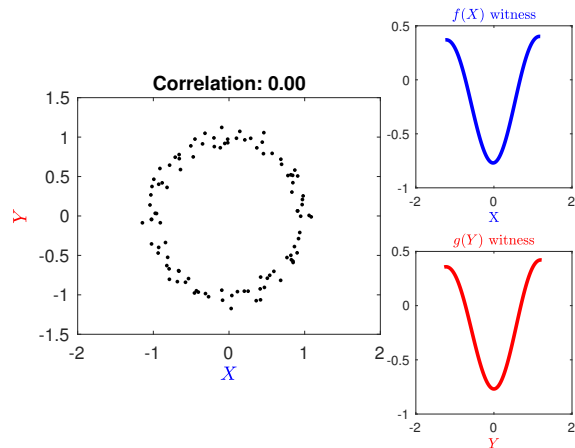
Finding covariance with smooth transformations

Illustration: two variables with no **correlation** but strong **dependence**.



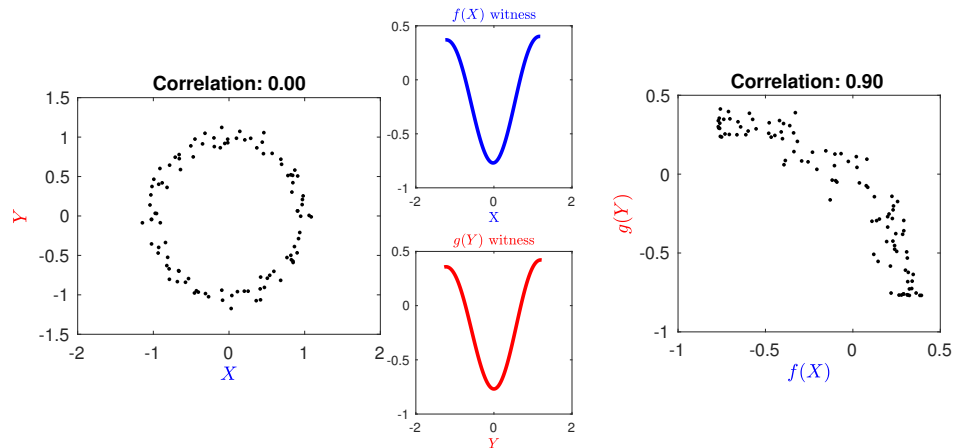
Finding covariance with smooth transformations

Illustration: two variables with no **correlation** but strong **dependence**.



Finding covariance with smooth transformations

Illustration: two variables with no **correlation** but strong **dependence**.



Define two spaces, one for each witness

Function in \mathcal{F}

$$f(x) = \sum_{j=1}^{\infty} f_j \varphi_j(x)$$

Feature map

$$\varphi(x) = \begin{bmatrix} \varphi_1(x) \\ \varphi_2(x) \\ \varphi_3(x) \\ \vdots \end{bmatrix}$$

Kernel for RKHS \mathcal{F} on \mathcal{X} :

$$k(x, x') = \langle \varphi(x), \varphi(x') \rangle_{\mathcal{F}}$$

Function in \mathcal{G}

$$g(y) = \sum_{j=1}^{\infty} g_j \phi_j(y)$$

Feature map

$$\phi(y) = \begin{bmatrix} \phi_1(y) \\ \phi_2(y) \\ \phi_3(y) \\ \vdots \end{bmatrix}$$

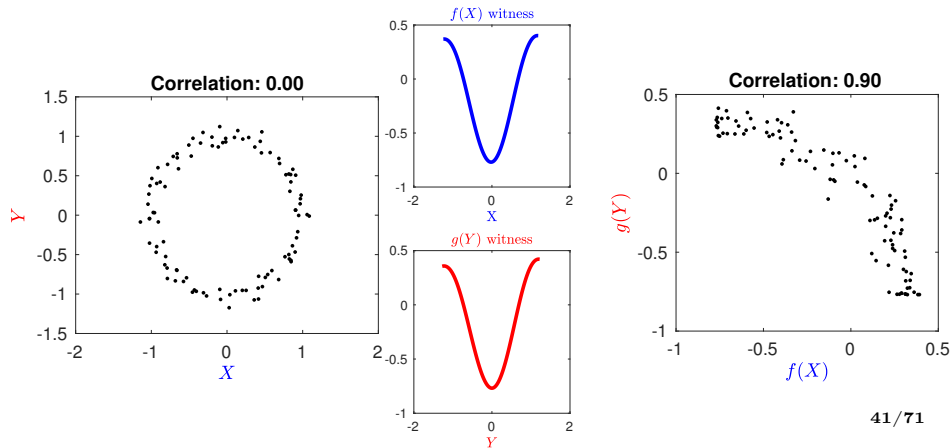
Kernel for RKHS \mathcal{G} on \mathcal{Y} :

$$l(y, y') = \langle \phi(y), \phi(y') \rangle_{\mathcal{G}}$$

The constrained covariance

The constrained covariance is

$$\text{COCO}(P_{XY}) = \sup_{\substack{\|f\|_{\mathcal{F}} \leq 1 \\ \|g\|_{\mathcal{G}} \leq 1}} \text{cov}[f(x)g(y)]$$



The constrained covariance

The constrained covariance is

$$\text{COCO}(P_{XY}) = \sup_{\substack{\|f\|_{\mathcal{F}} \leq 1 \\ \|g\|_{\mathcal{G}} \leq 1}} \text{cov} \left[\left(\sum_{j=1}^{\infty} f_j \varphi_j(x) \right) \left(\sum_{j=1}^{\infty} g_j \phi_j(y) \right) \right]$$

The constrained covariance

The constrained covariance is

$$\text{COCO}(P_{XY}) = \sup_{\substack{\|f\|_{\mathcal{F}} \leq 1 \\ \|g\|_{\mathcal{G}} \leq 1}} E_{xy} \left[\left(\sum_{j=1}^{\infty} f_j \varphi_j(x) \right) \left(\sum_{j=1}^{\infty} g_j \phi_j(y) \right) \right]$$

Fine print: feature mappings $\varphi(x)$ and $\phi(y)$ assumed to have zero mean.

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Fine print: feature mappings $\varphi(x)$ and $\phi(y)$ assumed to have zero mean.

Rewriting:

$$\begin{aligned} & E_{xy} [f(x)g(y)] \\ &= \begin{bmatrix} f_1 \\ f_2 \\ \vdots \end{bmatrix}^\top \underbrace{E_{xy} \left(\begin{bmatrix} \varphi_1(x) \\ \varphi_2(x) \\ \vdots \end{bmatrix} \begin{bmatrix} \phi_1(y) & \phi_2(y) & \dots \end{bmatrix} \right)}_{C_{\varphi(x)\phi(y)}} \begin{bmatrix} g_1 \\ g_2 \\ \vdots \end{bmatrix} \end{aligned}$$

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COCO: max singular value of feature covariance $C_{\varphi(x)\phi(y)}$

Computing COCO in practice

Given sample $\{(x_i, y_i)\}_{i=1}^n \stackrel{\text{i.i.d.}}{\sim} P_{XY}$, what is empirical $\widehat{\text{COCO}}$?

Computing COCO in practice

Given sample $\{(x_i, y_i)\}_{i=1}^n \stackrel{\text{i.i.d.}}{\sim} P_{XY}$, what is empirical \widehat{COCO} ?

\widehat{COCO} is largest eigenvalue γ_{\max} of

$$\begin{bmatrix} 0 & \frac{1}{n}KL \\ \frac{1}{n}LK & 0 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \gamma \begin{bmatrix} K & 0 \\ 0 & L \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix}.$$

$K_{ij} = k(x_i, x_j)$ and $L_{ij} = l(y_i, y_j)$.

Fine print: kernels are computed with empirically centered features $\varphi(x) - \frac{1}{n} \sum_{i=1}^n \varphi(x_i)$ and $\phi(y) - \frac{1}{n} \sum_{i=1}^n \phi(y_i)$.

G., Smola., Bousquet, Herbrich, Belitski, Augath, Murayama, Pauls, Schoelkopf, and Logothetis, AISTATS'05

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$K_{ij} = k(x_i, x_j)$ and $L_{ij} = l(y_i, y_j)$.

Witness functions (singular vectors):

$$f(x) \propto \sum_{i=1}^n \alpha_i k(x_i, x) \quad g(y) \propto \sum_{i=1}^n \beta_i l(y_i, y)$$

Fine print: kernels are computed with empirically centered features $\varphi(x) - \frac{1}{n} \sum_{i=1}^n \varphi(x_i)$ and $\phi(y) - \frac{1}{n} \sum_{i=1}^n \phi(y_i)$.

G., Smola., Bousquet, Herbrich, Belitski, Augath, Murayama, Pauls, Schoelkopf, and Logothetis, AISTATS'05

Empirical COCO: proof (1)

The Lagrangian is

$$\mathcal{L}(f, g, \lambda, \gamma) = \underbrace{\frac{1}{n} \sum_{i=1}^n [f(x_i)g(y_i)]}_{\text{covariance}} - \underbrace{\frac{\lambda}{2} (\|f\|_{\mathcal{F}}^2 - 1) - \frac{\gamma}{2} (\|g\|_{\mathcal{G}}^2 - 1)}_{\text{smoothness constraints}}.$$

Fine print: $f(x_i)g(y_i)$ centered to have zero empirical mean.

Empirical COCO: proof (1)

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Fine print: $f(x_i)g(y_i)$ centered to have zero empirical mean.

Assume (cf representer theorem):

$$f = \sum_{i=1}^n \alpha_i \varphi(x_i) \quad g = \sum_{i=1}^n \beta_i \psi(y_i)$$

for centered $\varphi(x_i), \psi(y_i)$.

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for centered $\varphi(x_i), \psi(y_i)$.

First step is **smoothness constraint**:

$$\|f\|_{\mathcal{F}}^2 - 1 = \langle f, f \rangle_{\mathcal{F}} - 1$$

Empirical COCO: proof (1)

The Lagrangian is

$$\mathcal{L}(f, g, \lambda, \gamma) = \underbrace{\frac{1}{n} \sum_{i=1}^n [f(x_i)g(y_i)]}_{\text{covariance}} - \underbrace{\frac{\lambda}{2} (\|f\|_{\mathcal{F}}^2 - 1) - \frac{\gamma}{2} (\|g\|_{\mathcal{G}}^2 - 1)}_{\text{smoothness constraints}}.$$

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for centered $\varphi(x_i)$, $\psi(y_i)$.

First step is **smoothness constraint**:

$$\begin{aligned} \|f\|_{\mathcal{F}}^2 - 1 &= \langle f, f \rangle_{\mathcal{F}} - 1 \\ &= \left\langle \sum_{i=1}^n \alpha_i \varphi(x_i), \sum_{i=1}^n \alpha_i \varphi(x_i) \right\rangle_{\mathcal{F}} - 1 \end{aligned}$$

Empirical COCO: proof (1)

The Lagrangian is

$$\mathcal{L}(f, g, \lambda, \gamma) = \underbrace{\frac{1}{n} \sum_{i=1}^n [f(x_i)g(y_i)]}_{\text{covariance}} - \underbrace{\frac{\lambda}{2} (\|f\|_{\mathcal{F}}^2 - 1) - \frac{\gamma}{2} (\|g\|_{\mathcal{G}}^2 - 1)}_{\text{smoothness constraints}}.$$

Fine print: $f(x_i)g(y_i)$ centered to have zero empirical mean.

Assume (cf representer theorem):

$$f = \sum_{i=1}^n \alpha_i \varphi(x_i) \quad g = \sum_{i=1}^n \beta_i \psi(y_i)$$

for centered $\varphi(x_i)$, $\psi(y_i)$.

First step is **smoothness constraint**:

$$\begin{aligned} \|f\|_{\mathcal{F}}^2 - 1 &= \langle f, f \rangle_{\mathcal{F}} - 1 \\ &= \left\langle \sum_{i=1}^n \alpha_i \varphi(x_i), \sum_{i=1}^n \alpha_i \varphi(x_i) \right\rangle_{\mathcal{F}} - 1 \\ &= \alpha^\top K \alpha - 1 \end{aligned}$$

Proof sketch (2)

Second step is covariance:

$$\begin{aligned}\frac{1}{n} \sum_{i=1}^n [f(x_i)g(y_i)] &= \frac{1}{n} \sum_{i=1}^n \langle f, \varphi(x_i) \rangle_{\mathcal{F}} \langle g, \varphi(y_i) \rangle_{\mathcal{G}} \\ &= \frac{1}{n} \sum_{i=1}^n \left\langle \sum_{\ell=1}^n \alpha_{\ell} \varphi(x_{\ell}), \varphi(x_i) \right\rangle_{\mathcal{F}} \langle g, \varphi(y_i) \rangle_{\mathcal{G}} \\ &= \frac{1}{n} \alpha^{\top} KL \beta\end{aligned}$$

Proof sketch (2)

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where $K_{ij} = k(x_i, x_j) = \langle \varphi(x_i), \varphi(x_j) \rangle_{\mathcal{F}}$ $L_{ij} = l(y_i, y_j)$.

Proof sketch (2)

Second step is covariance:

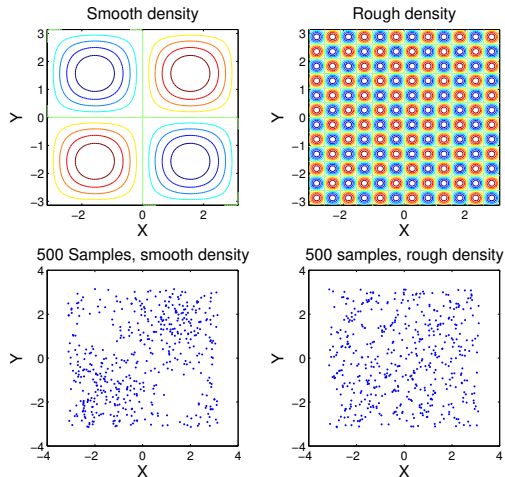
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where $K_{ij} = k(x_i, x_j) = \langle \varphi(x_i), \varphi(x_j) \rangle_{\mathcal{F}}$ $L_{ij} = l(y_i, y_j)$.

The Lagrangian is now:

$$\mathcal{L}(f, g, \lambda, \gamma) = \frac{1}{n} \alpha^{\top} K L \beta - \frac{\lambda}{2} (\alpha^{\top} K \alpha - 1) - \frac{\gamma}{2} (\beta^{\top} L \beta - 1)$$

What is a large dependence with COCO?



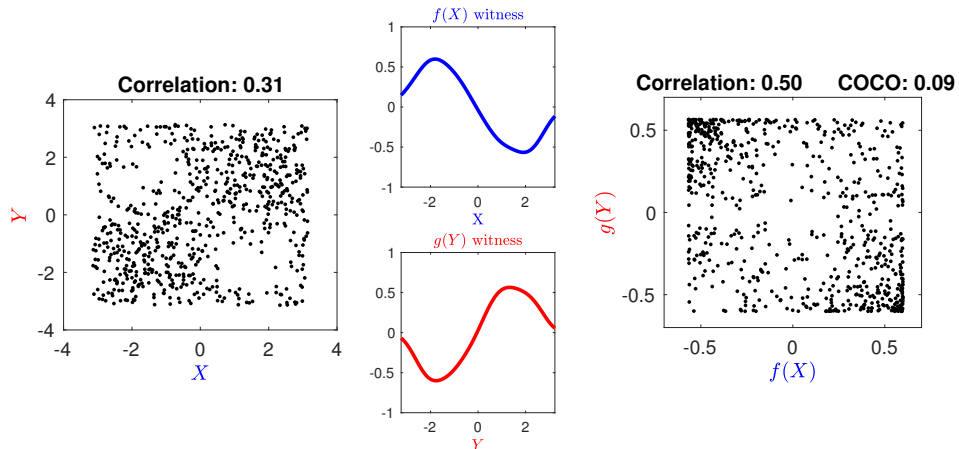
Density takes the form:

$$P_{XY} \propto 1 + \sin(\omega x) \sin(\omega y)$$

Which of these is the more “dependent”?

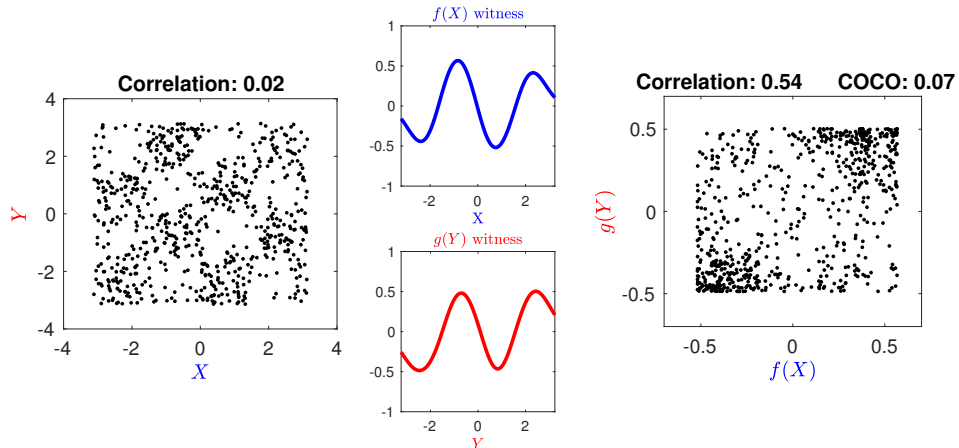
Finding covariance with smooth transformations

Case of $\omega = 1$:



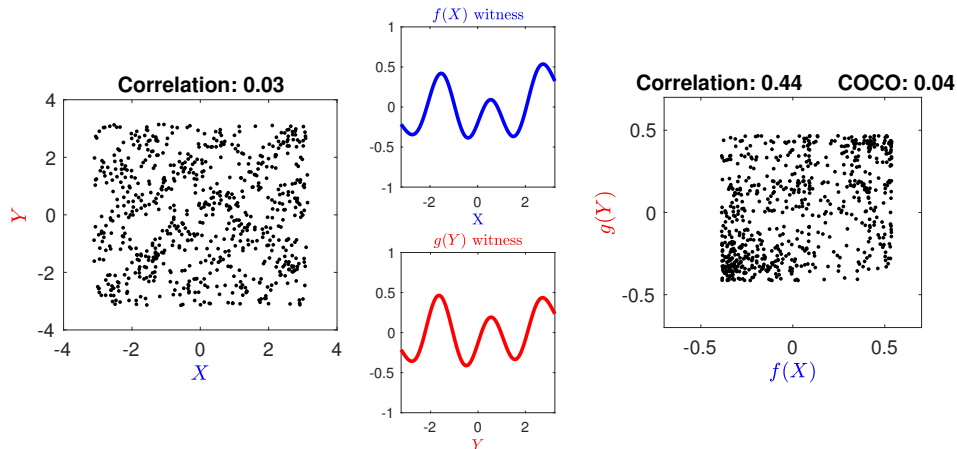
Finding covariance with smooth transformations

Case of $\omega = 2$:



Finding covariance with smooth transformations

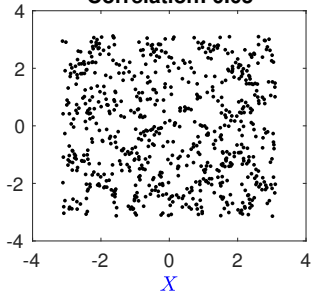
Case of $\omega = 3$:



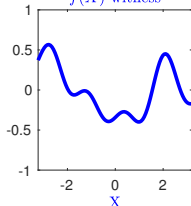
Finding covariance with smooth transformations

Case of $\omega = 4$:

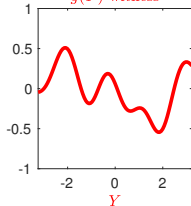
Correlation: 0.05



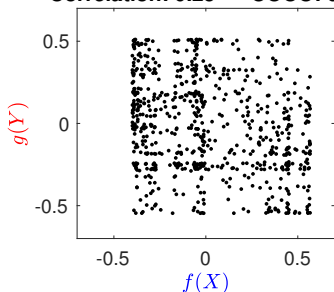
$f(X)$ witness



$g(Y)$ witness



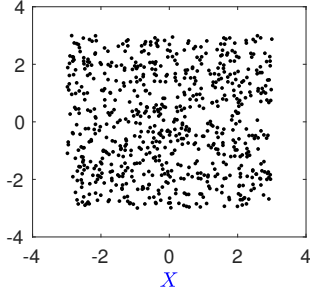
Correlation: 0.25 COCO: 0.02



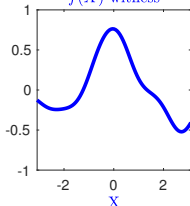
Finding covariance with smooth transformations

Case of $\omega = ??$:

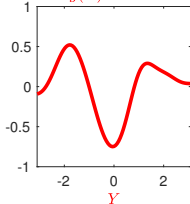
Correlation: 0.01



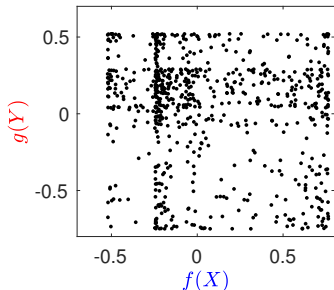
$f(X)$ witness



$g(Y)$ witness

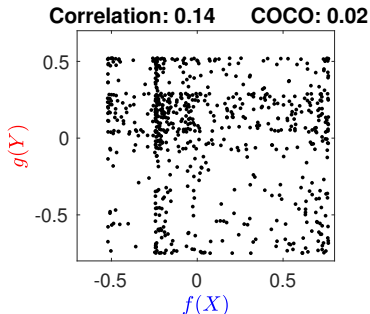
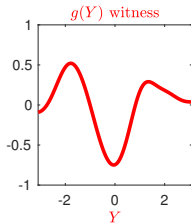
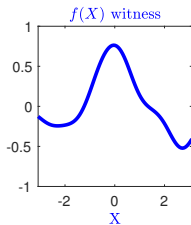
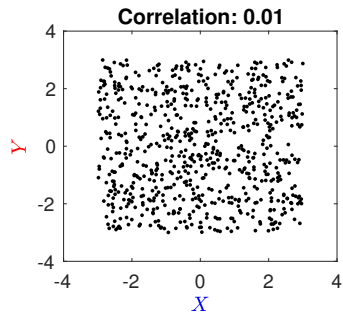


Correlation: 0.14 COCO: 0.02



Finding covariance with smooth transformations

Case of $\omega = 0$: uniform noise! (shows bias)



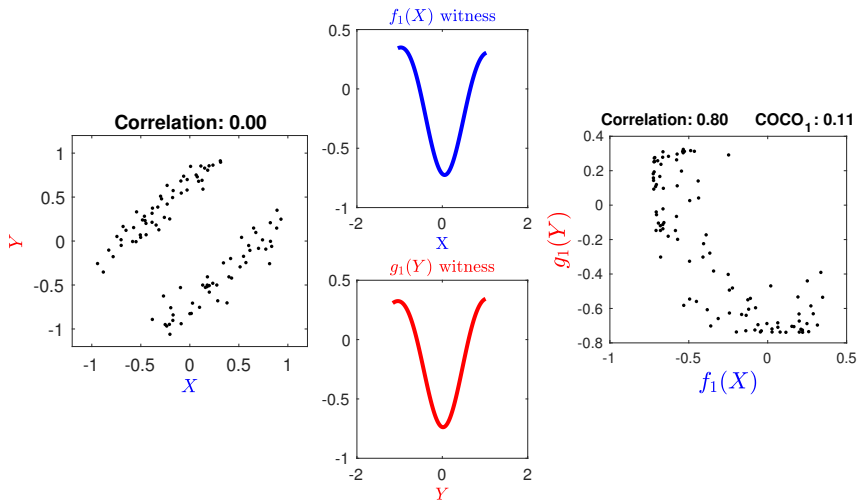
Dependence largest when at “low” frequencies

- As dependence is encoded at **higher frequencies**, the **smooth mappings** f, g achieve lower linear dependence.
- Even for **independent variables**, COCO will not be zero at **finite sample sizes**, since some mild linear dependence will be found by f, g (**bias**)
- This **bias** will decrease with increasing sample size.

Can we do better than COCO?

A second example with zero correlation.

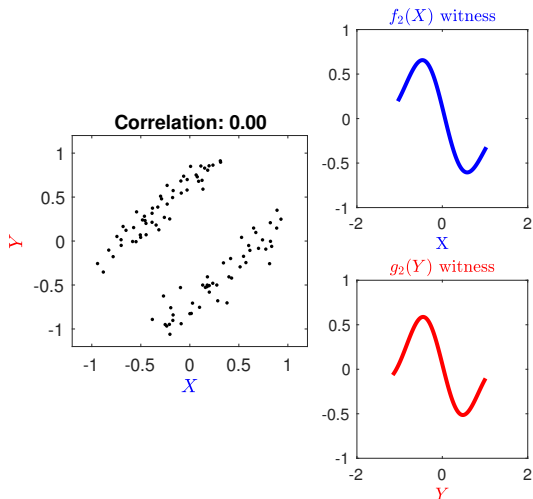
First singular value of feature covariance $C_{\varphi(x)\phi(y)}$:



Can we do better than COCO?

A second example with zero correlation.

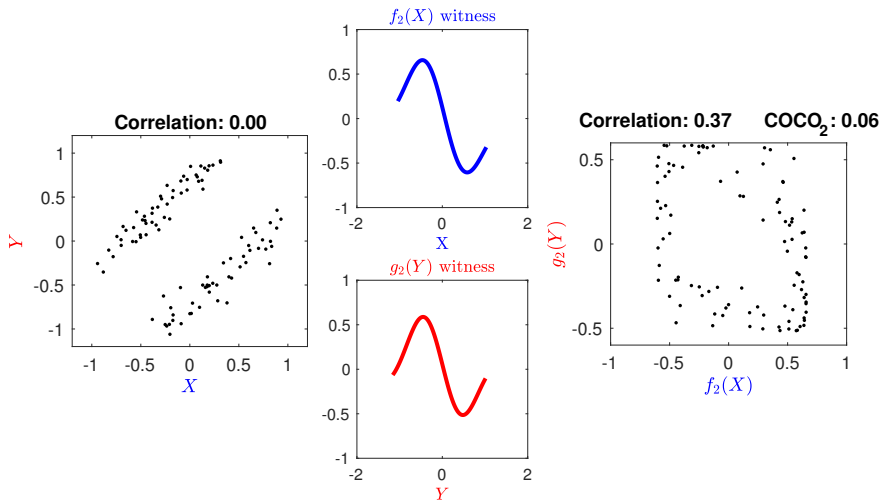
Second singular value of feature covariance $C_{\varphi(x)\phi(y)}$:



Can we do better than COCO?

A second example with zero correlation.

Second singular value of feature covariance $C_{\varphi(x)\phi(y)}$:



The Hilbert-Schmidt Independence Criterion

Writing the i th singular value of the feature covariance $C_{\varphi(x)\phi(y)}$ as

$$\gamma_i := \text{COV}_i(P_{XY}; \mathcal{F}, \mathcal{G}),$$

define **Hilbert-Schmidt Independence Criterion (HSIC)**

$$\text{HSIC}^2(P_{XY}; \mathcal{F}, \mathcal{G}) = \sum_{i=1}^{\infty} \gamma_i^2.$$

G, Bousquet, Smola., and Schoelkopf, ALT05; G., Fukumizu, Teo., Song., Schoelkopf., and Smola, NIPS 2007,.

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HSIC is MMD with product kernel!

$$\text{HSIC}^2(P_{XY}; \mathcal{F}, \mathcal{G}) = \text{MMD}^2(P_{XY}, P_X P_Y; \mathcal{H}_{\kappa})$$

where $\kappa((x, y), (x', y')) = k(x, x')l(y, y')$.

Asymptotics of HSIC under independence

- Given sample $\{(x_i, y_i)\}_{i=1}^n \stackrel{\text{i.i.d.}}{\sim} P_{XY}$, what is empirical \widehat{HSIC} ?
- Empirical HSIC (biased)

$$\widehat{HSIC} = \frac{1}{n^2} \text{trace}(KL)$$

$K_{ij} = k(x_i, x_j)$ and $L_{ij} = l(y_i, y_j)$ (K and L computed with empirically centered features)

- Statistical testing: given $P_{XY} = P_X P_Y$, what is the threshold c_α such that $P(\widehat{HSIC} > c_\alpha) < \alpha$ for small α ?
- Asymptotics of \widehat{HSIC} when $P_{XY} = P_X P_Y$:

$$n\widehat{HSIC} \xrightarrow{D} \sum_{l=1}^{\infty} \lambda_l z_l^2, \quad z_l \sim \mathcal{N}(0, 1) \text{ i.i.d.}$$

where $\lambda_l \psi_l(z_j) = \int h_{ijqr} \psi_l(z_i) dF_{i,q,r}$, $h_{ijqr} = \frac{1}{4!} \sum_{(t,u,v,w)}^{(i,j,q,r)} k_{tu} l_{tv} + k_{tu} l_{vw} - 2k_{tu} l_{tv}$

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A statistical test

- Given $P_{XY} = P_X P_Y$, what is the threshold c_α such that $P(\widehat{HSIC} > c_\alpha) < \alpha$ for small α (prob. of false positive)?

- Original time series:

$X_1 X_2 X_3 X_4 X_5 X_6 X_7 X_8 X_9 X_{10}$
 $Y_1 Y_2 Y_3 Y_4 Y_5 Y_6 Y_7 Y_8 Y_9 Y_{10}$

- Permutation:

$X_1 X_2 X_3 X_4 X_5 X_6 X_7 X_8 X_9 X_{10}$
 $Y_7 Y_3 Y_9 Y_2 Y_4 Y_8 Y_5 Y_1 Y_6 Y_{10}$

- Null distribution via permutation

- Compute HSIC for $\{x_i, y_{\pi(i)}\}_{i=1}^n$ for random permutation π of indices $\{1, \dots, n\}$. This gives HSIC for independent variables.
- Repeat for many different permutations, get empirical CDF
- Threshold c_α is $1 - \alpha$ quantile of empirical CDF

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- Null distribution via **permutation**

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- Repeat for many different permutations, get empirical CDF
- Threshold c_α is $1 - \alpha$ quantile of empirical CDF

Application: dependence detection across languages

Testing task: detect dependence between English and French text

X	Y
Honourable senators, I have a question for the Leader of the Government in the Senate	Honorables sénateurs, ma question s'adresse au leader du gouvernement au Sénat
No doubt there is great pressure on provincial and municipal governments	Les ordres de gouvernements provinciaux et municipaux subissent de fortes pressions
In fact, we have increased federal investments for early childhood development.	Au contraire, nous avons augmenté le financement fédéral pour le développement des jeunes
• • •	• • •

Application: dependence detection across languages

Testing task: detect dependence between **English** and **French** text

k -spectrum kernel, $k = 10$, sample size $n = 10$

X

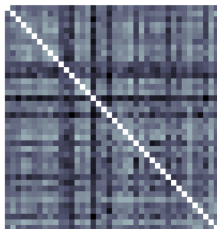
Y

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have a question for the
Leader of the Government
in the Senate

No doubt there is great
pressure on provincial and
municipal governments

In fact, we have increased
federal investments for
early childhood
development.

•
•
•



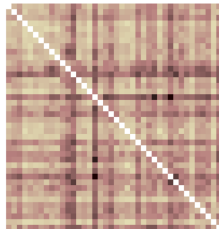
K

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provinciaux et municipaux
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Au contraire, nous avons
augmenté
le financement fédéral pour le
développement des jeunes

•
•
•



L

$$\widehat{HSIC} = \frac{1}{n^2} \text{trace}(KL)$$

(K and L column centered)

Application: Dependence detection across languages

Results (for $\alpha = 0.05$)

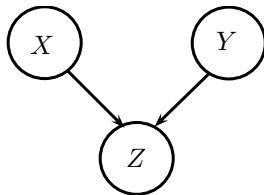
- k-spectrum kernel: average Type II error 0
- Bag of words kernel: average Type II error 0.18

Settings: Five line extracts, averaged over 300 repetitions, for “Agriculture” transcripts. Similar results for Fisheries and Immigration transcripts.

Testing higher order interactions

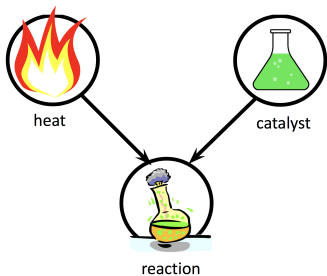
Detecting higher order interaction

How to detect V-structures with pairwise weak individual dependence?



Detecting higher order interaction

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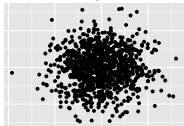


Detecting higher order interaction

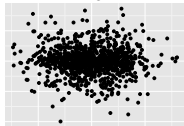
How to detect V-structures with pairwise weak individual dependence?

$$X \perp\!\!\!\perp Y, Y \perp\!\!\!\perp Z, X \perp\!\!\!\perp Z$$

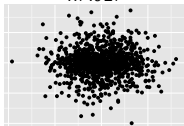
X1 vs Y1



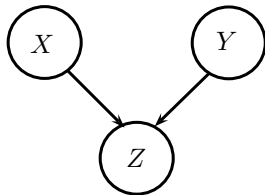
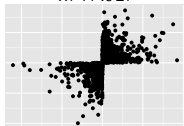
Y1 vs Z1



X1 vs Z1



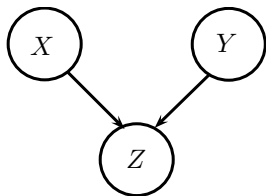
X1*Y1 vs Z1



- $X, Y \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1)$
- $Z | X, Y \sim \text{sign}(XY) \text{Exp}\left(\frac{1}{\sqrt{2}}\right)$

Fine print: Faithfulness violated here!

V-structure discovery



Assume $X \perp\!\!\!\perp Y$ has been established.

V-structure can then be detected by:

- Consistent CI test: $H_0 : X \perp\!\!\!\perp Y | Z$ [Fukumizu et al. 2008, Zhang et al. 2011]
- Factorisation test: $H_0 : (X, Y) \perp\!\!\!\perp Z \vee (X, Z) \perp\!\!\!\perp Y \vee (Y, Z) \perp\!\!\!\perp X$
(multiple standard two-variable tests)

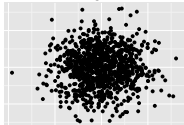
How well do these work?

Detecting higher order interaction

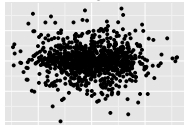
Generalise earlier example to p dimensions

$$X \perp\!\!\!\perp Y, Y \perp\!\!\!\perp Z, X \perp\!\!\!\perp Z$$

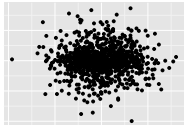
X1 vs Y1



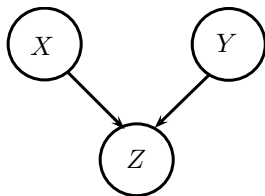
Y1 vs Z1



X1 vs Z1



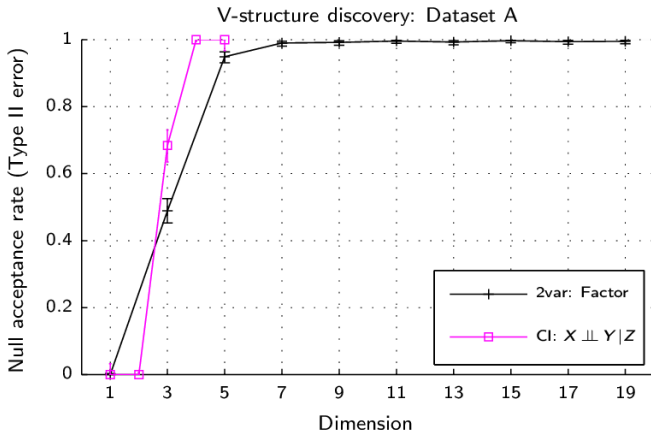
X1*Y1 vs Z1



- $X, Y \stackrel{i.i.d.}{\sim} \mathcal{N}(0, 1)$
- $Z | X, Y \sim \text{sign}(XY) \text{Exp}(\frac{1}{\sqrt{2}})$
- $X_{2:p}, Y_{2:p}, Z_{2:p} \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \mathbf{I}_{p-1})$

Fine print: Faithfulness violated here!

V-structure discovery



CI test for $X \perp\!\!\!\perp Y|Z$ from Zhang et al. (2011), and a factorisation test, $n = 500$

Lancaster interaction measure

Lancaster interaction measure of $(X_1, \dots, X_D) \sim P$ is a signed measure ΔP that **vanishes** whenever P can be factorised non-trivially.

$$D = 2: \quad \Delta_L P = P_{XY} - P_X P_Y$$

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Lancaster interaction measure

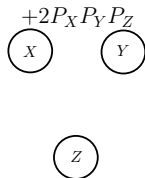
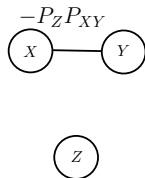
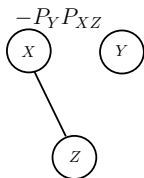
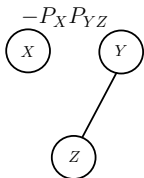
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$$\Delta_L P =$$

$$P_{XYZ}$$

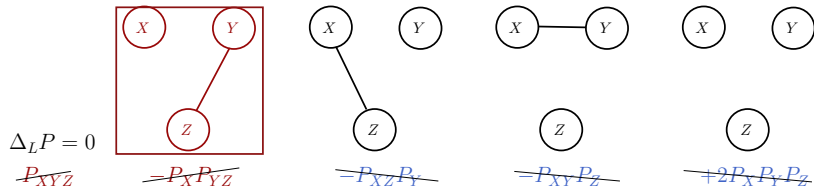


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Case of $P_X \perp\!\!\!\perp P_{YZ}$

Lancaster interaction measure

Lancaster interaction measure of $(X_1, \dots, X_D) \sim P$ is a signed measure ΔP that **vanishes** whenever P can be factorised non-trivially.

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$$(X, Y) \perp\!\!\!\perp Z \vee (X, Z) \perp\!\!\!\perp Y \vee (Y, Z) \perp\!\!\!\perp X \Rightarrow \Delta_L P = 0.$$

...so what might be missed?

Lancaster interaction measure

Lancaster interaction measure of $(X_1, \dots, X_D) \sim P$ is a signed measure ΔP that **vanishes** whenever P can be factorised non-trivially.

$$D = 2: \quad \Delta_L P = P_{XY} - P_X P_Y$$

$$D = 3: \quad \Delta_L P = P_{XYZ} - P_X P_{YZ} - P_Y P_{XZ} - P_Z P_{XY} + 2P_X P_Y P_Z$$

$$\Delta_L P = 0 \not\Rightarrow (X, Y) \perp\!\!\!\perp Z \vee (X, Z) \perp\!\!\!\perp Y \vee (Y, Z) \perp\!\!\!\perp X$$

Example:

$P(0,0,0) = 0.2$	$P(0,0,1) = 0.1$	$P(1,0,0) = 0.1$	$P(1,0,1) = 0.1$
$P(0,1,0) = 0.1$	$P(0,1,1) = 0.1$	$P(1,1,0) = 0.1$	$P(1,1,1) = 0.2$

A kernel test statistic using Lancaster Measure

Construct a test by estimating $\|\mu_\kappa(\Delta_L P)\|_{\mathcal{H}_\kappa}^2$, where $\kappa = k \otimes l \otimes m$:

$$\begin{aligned} & \|\mu_\kappa(P_{XYZ} - P_{XY}P_Z - \dots)\|_{\mathcal{H}_\kappa}^2 = \\ & \langle \mu_\kappa P_{XYZ}, \mu_\kappa P_{XYZ} \rangle_{\mathcal{H}_\kappa} - 2 \langle \mu_\kappa P_{XYZ}, \mu_\kappa P_{XY}P_Z \rangle_{\mathcal{H}_\kappa} \dots \end{aligned}$$

A kernel test statistic using Lancaster Measure

$\nu \setminus \nu'$	P_{XYZ}	$P_{XY}P_Z$	$P_{XZ}P_Y$	$P_{YZ}P_X$	$P_X P_Y P_Z$
P_{XYZ}	$(K \circ L \circ M)_{++}$	$((K \circ L)M)_{++}$	$((K \circ M)L)_{++}$	$((M \circ L)K)_{++}$	$\text{tr}(K_{++} \circ L_{++} \circ M_{++})$
$P_{XY}P_Z$		$(K \circ L)_{++} M_{++}$	$(MKL)_{++}$	$(KLM)_{++}$	$(KL)_{++} M_{++}$
$P_{XZ}P_Y$			$(K \circ M)_{++} L_{++}$	$(KML)_{++}$	$(KM)_{++} L_{++}$
$P_{YZ}P_X$				$(L \circ M)_{++} K_{++}$	$(LM)_{++} K_{++}$
$P_X P_Y P_Z$					$K_{++} L_{++} M_{++}$

Table: V -statistic estimators of $\langle \mu_\kappa \nu, \mu_\kappa \nu' \rangle_{\mathcal{H}_\kappa}$ (without terms $P_X P_Y P_Z$). H is centering matrix $I - n^{-1}$

Lancaster interaction statistic: Sejdinovic, G, Bergsma, NIPS13

$$\|\mu_\kappa(\Delta_L P)\|_{\mathcal{H}_\kappa}^2 = \frac{1}{n^2} \boxed{(HKH \circ H L H \circ H M H)_{++}}$$

A kernel test statistic using Lancaster Measure

$\nu \setminus \nu'$	P_{XYZ}	$P_{XY}P_Z$	$P_{XZ}P_Y$	$P_{YZ}P_X$	$P_X P_Y P_Z$
P_{XYZ}	$(K \circ L \circ M)_{++}$	$((K \circ L)M)_{++}$	$((K \circ M)L)_{++}$	$((M \circ L)K)_{++}$	$\text{tr}(K_{++} \circ L_{++} \circ M_{++})$
$P_{XY}P_Z$		$(K \circ L)_{++} M_{++}$	$(MKL)_{++}$	$(KLM)_{++}$	$(KL)_{++} M_{++}$
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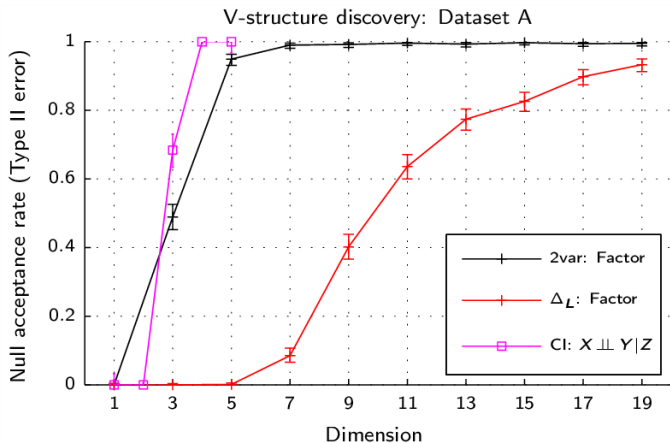
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$$\|\mu_\kappa(\Delta_L P)\|_{\mathcal{H}_\kappa}^2 = \frac{1}{n^2} \boxed{(H \mathbf{K} H \circ H \mathbf{L} H \circ H \mathbf{M} H)_{++}}$$

Empirical joint central moment in the feature space

V-structure discovery



Lancaster test, CI test for $X \perp\!\!\!\perp Y | Z$ from Zhang et al. (2011), and a factorisation test, $n = 500$

Interaction for $D \geq 4$

- Interaction measure valid for all D :

(Streitberg, 1990)

$$\Delta_S P = \sum_{\pi} (-1)^{|\pi|-1} (|\pi| - 1)! J_{\pi} P$$

- For a partition π , J_{π} associates to the joint the corresponding factorisation, e.g., $J_{13|2|4} P = P_{X_1 X_3} P_{X_2} P_{X_4}$.

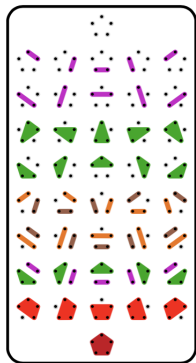
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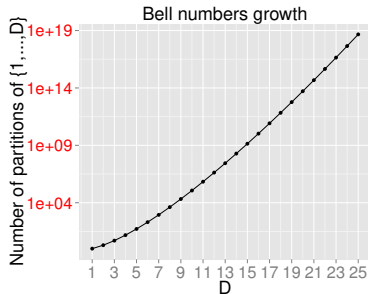
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From Gatsby:

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- Wittawat Jitkrittum
- Heiko Strathmann
- Dougal Sutherland
- Wenkai Xu

External collaborators:

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- Bernhard Schoelkopf
- Dino Sejdinovic
- Bharath Sriperumbudur
- Alex Smola
- Zoltan Szabo

Questions?

