The Maximum Mean Discrepancy for Training Generative Adversarial Networks

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A motivation: comparing two samples

- **Given:** Samples from unknown distributions P and Q.
- **Goal:** do P and Q differ?

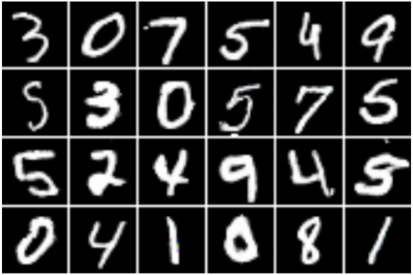
$$\sim P$$

$$\sim Q$$

A real-life example: two-sample tests

- **Have:** Two collections of samples X, Y from unknown distributions P and Q.
- **Goal:** do P and Q differ?

MNIST samples



Samples from a GAN

Significant difference in GAN and MNIST?

T. Salimans, I. Goodfellow, W. Zaremba, V. Cheung, A. Radford, Xi Chen, NIPS 2016
Sutherland, Tung, Strathmann, De, Ramdas, Smola, G., ICLR 2017.

Training generative models

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A portrait created by AI just sold for $432,000. But is it really art?

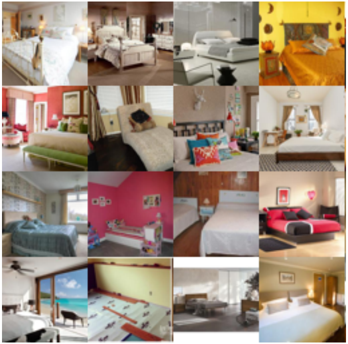
An image of Edmond de Belamy, created by a computer, has just been sold at Christie's. But no algorithm can capture our complex human consciousness

1,085 455

▲ Portrait of Edmond Bellamy at Christie's in New York. Photograph: Timothy A Clary/AFP/Getty Images

Training generative models

- **Have:** One collection of samples X from unknown distribution P.
- **Goal:** generate samples Q that look like P



LSUN bedroom samples P

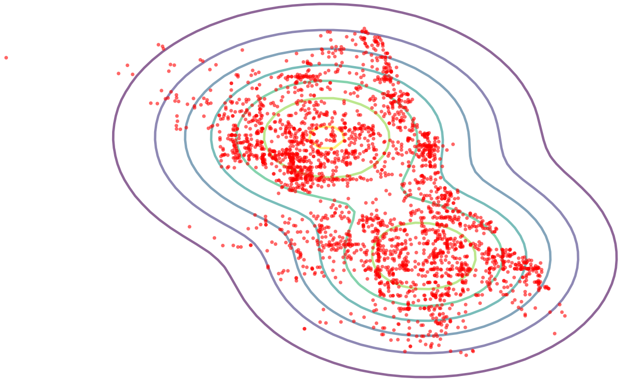
Generated Q, MMD GAN

Using MMD to train a GAN

(Binkowski, Sutherland, Arbel, G., ICLR 2018),
(Arbel, Sutherland, Binkowski, G., arXiv 2018)

Not covered: testing goodness of fit

- **Given:** **A model** P and samples and Q.
- **Goal:** is P a good fit for Q?



Chicago crime data

Model is Gaussian mixture with **two** components.

Not covered: testing independence

- **Given:** Samples from a distribution P_{XY}
- **Goal:** Are X and Y independent?

X	Y
	A large animal who slings slobber, exudes a distinctive houndy odor, and wants nothing more than to follow his nose.
	Their noses guide them through life, and they're never happier than when following an interesting scent.
	A responsive, interactive pet, one that will blow in your ear and follow you everywhere.

Text from dogtime.com and petfinder.com

Outline

- Maximum Mean Discrepancy (MMD)...
  - ...as a difference in feature means
  - ...as an integral probability metric (not just a technicality!)

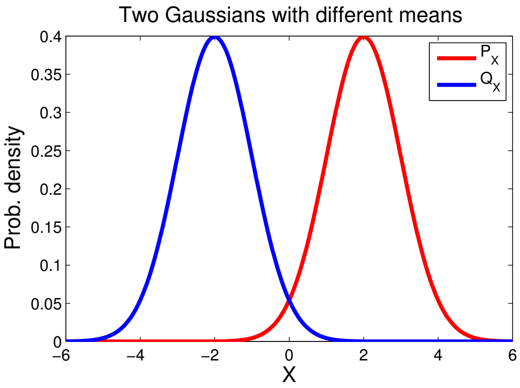
- A statistical test based on the MMD

- Training generative adversarial networks with MMD
  - Gradient regularisation and data adaptivity
  - Evaluating GAN performance? Problems with Inception and FID.

Maximum Mean Discrepancy

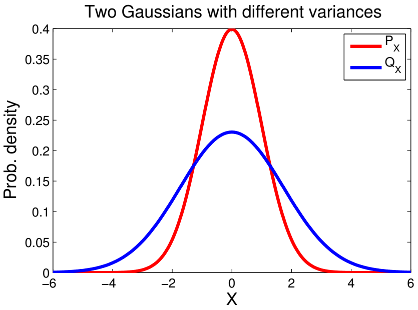
Feature mean difference

- Simple example: 2 Gaussians with different means
- Answer: t-test



Feature mean difference

- Two Gaussians with same means, different variance
- Idea: look at difference in **means of features** of the RVs
- In Gaussian case: second order features of form $\varphi(x) = x^2$



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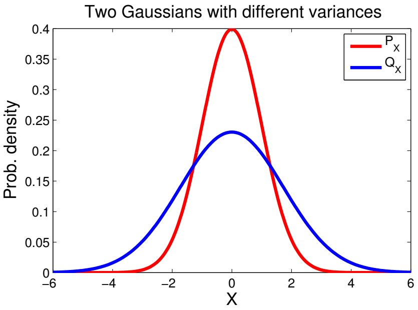
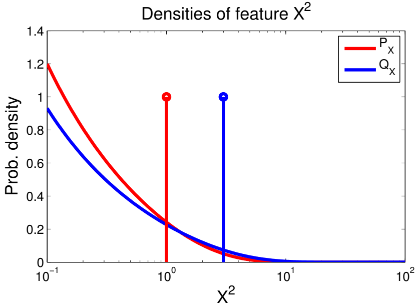
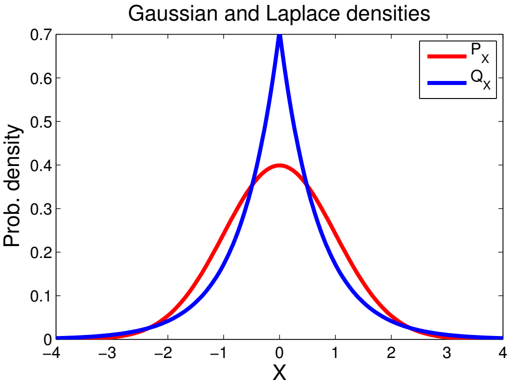




Feature mean difference

- Gaussian and Laplace distributions
- Same mean *and* same variance
- Difference in means using **higher order features**...RKHS



Infinitely many features using kernels

Kernels: dot products of features

Feature map $\varphi(x) \in \mathcal{F}$,

$$\varphi(x) = [\ldots \varphi_i(x) \ldots] \in \ell_2$$

For positive definite k,

$$k(x, x') = \langle \varphi(x), \varphi(x') \rangle_{\mathcal{F}}$$

Infinitely many features $\varphi(x)$, dot product in closed form!

Infinitely many features using kernels

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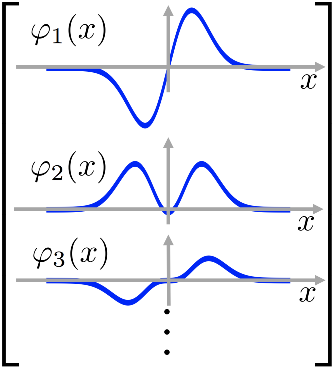
Infinitely many features $\varphi(x)$, dot product in closed form!

Exponentiated quadratic kernel

$$k(x, x') = \exp\left(-\gamma \|x - x'\|^2\right)$$

$$\varphi(x) =$$



Features: Gaussian Processes for Machine learning, Rasmussen and Williams, Ch. 4.

Infinitely many features of *distributions*

Given P a Borel **probability measure** on $\mathcal{X}$, define feature map of probability P,

$$\mu_P = [\ldots \mathbf{E}_P [\varphi_i(X)] \ldots]$$

For positive definite $k(x, x')$,

$$\langle \mu_P, \mu_Q \rangle_{\mathcal{F}} = \mathbf{E}_{P,Q} k(x, y)$$

for $x \sim P$ and $y \sim Q$.

Fine print: feature map $\varphi(x)$ must be Bochner integrable for all probability measures considered. Always true if kernel bounded.

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The maximum mean discrepancy

The maximum mean discrepancy is the distance between **feature means**:

$$\begin{aligned} MMD^2(P, Q) &= \|\mu_P - \mu_Q\|^2_{\mathcal{F}} \\ &= \langle \mu_P, \mu_P \rangle_{\mathcal{F}} + \langle \mu_Q, \mu_Q \rangle_{\mathcal{F}} - 2 \langle \mu_P, \mu_Q \rangle_{\mathcal{F}} \\ &= \underbrace{\mathbf{E}_P k(X, X')}_{\text{(a)}} + \underbrace{\mathbf{E}_Q k(Y, Y')}_{\text{(a)}} - 2\underbrace{\mathbf{E}_{P,Q} k(X, Y)}_{\text{(b)}} \end{aligned}$$

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(a)= within distrib. similarity, (b)= cross-distrib. similarity.

Illustration of MMD

- Dogs ($= P$) and fish ($= Q$) example revisited
- Each entry is one of $k(\text{dog}_i, \text{dog}_j)$, $k(\text{dog}_i, \text{fish}_j)$, or $k(\text{fish}_i, \text{fish}_j)$

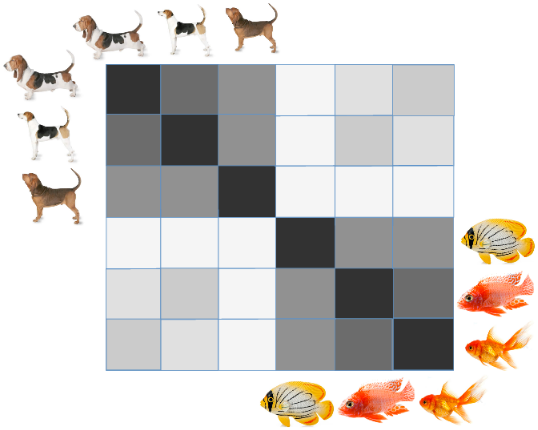
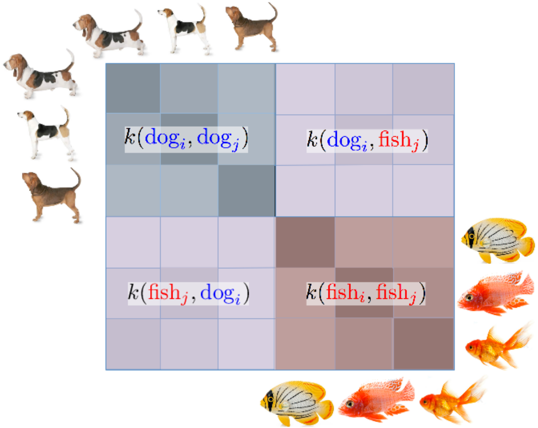


Illustration of MMD

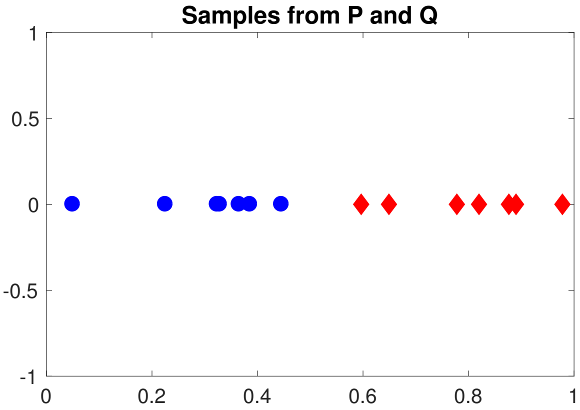
The maximum mean discrepancy:

$$\widehat{MMD}^2 = \frac{1}{n(n-1)} \sum_{i \neq j} k(\text{dog}_i, \text{dog}_j) + \frac{1}{n(n-1)} \sum_{i \neq j} k(\text{fish}_i, \text{fish}_j) - \frac{2}{n^2} \sum_{i,j} k(\text{dog}_i, \text{fish}_j)$$



MMD as an integral probability metric

Are P and Q different?



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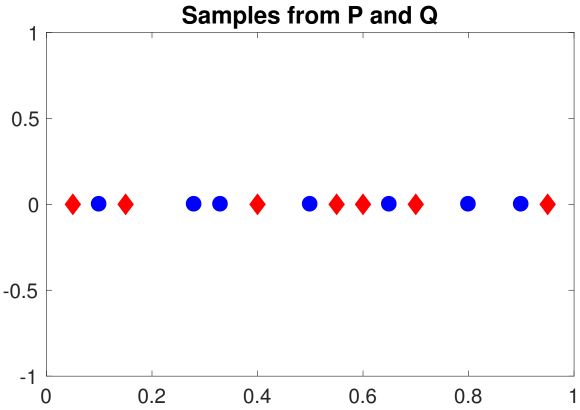
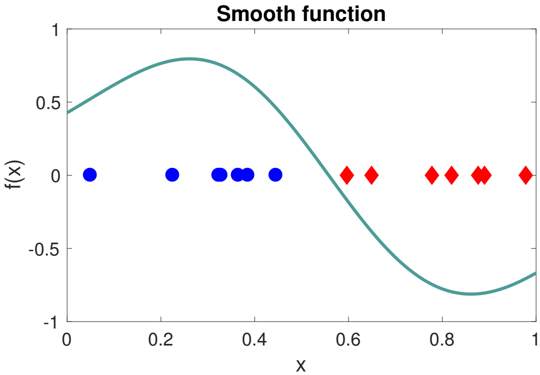


MMD as an integral probability metric

Integral probability metric:

Find a "well behaved function" $f(x)$ to maximize

$$\mathbf{E}_P f(X) - \mathbf{E}_Q f(Y)$$



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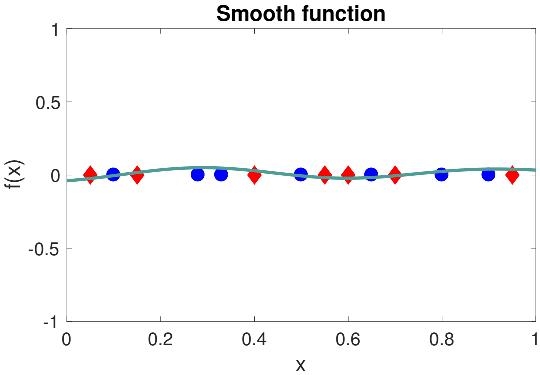

MMD as an integral probability metric

Maximum mean discrepancy: smooth function for P vs Q

$$MMD(P, Q; F) := \sup_{\|f\| \leq 1} \left[\mathbf{E}_P f(X) - \mathbf{E}_Q f(Y) \right]$$

$$(F = \text{unit ball in RKHS } \mathcal{F})$$

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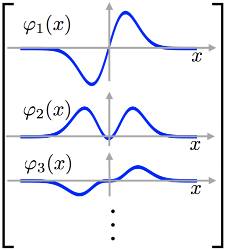
Functions are linear combinations of features:

$$f(x) = \langle f, \varphi(x) \rangle_{\mathcal{F}} = \sum_{\ell=1}^{\infty} f_\ell \varphi_\ell(x) = \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ \vdots \end{bmatrix}^\top$$



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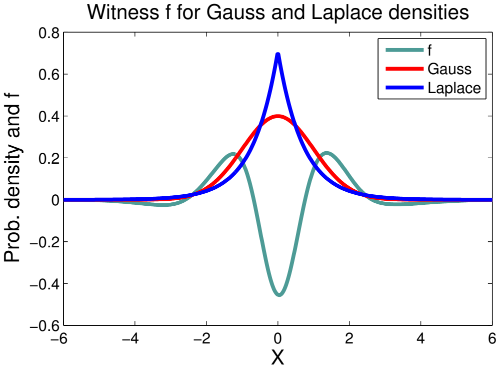

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Expectations of functions are linear combinations of expected features

$$\mathbf{E}_P(f(X)) = \langle f, \mathbf{E}_P \varphi(X) \rangle_{\mathcal{F}} = \langle f, \mu_P \rangle_{\mathcal{F}}$$

(always true if kernel is bounded)

MMD as an integral probability metric

Maximum mean discrepancy: smooth function for P vs Q

$$MMD(P, Q; F) := \sup_{\|f\| \leq 1} \left[\mathbf{E}_P f(X) - \mathbf{E}_Q f(Y) \right]$$

$$(F = \text{unit ball in RKHS } \mathcal{F})$$

For characteristic RKHS $\mathcal{F}$, $MMD(P, Q; F) = 0$ iff $P = Q$

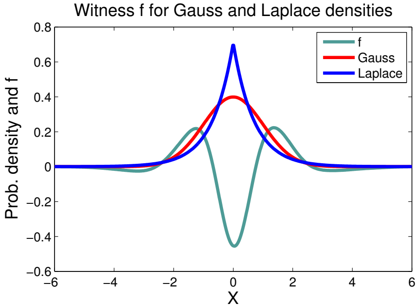
Other choices for witness function class:

- Bounded continuous [Dudley, 2002]
- Bounded varation 1 (Kolmogorov metric) [Müller, 1997]
- Bounded Lipschitz (Wasserstein distances) [Dudley, 2002]

Integral prob. metric vs feature difference

The MMD:

$$MMD(P, Q; F) = \sup_{f \in F} \left[\mathbf{E}_P f(X) - \mathbf{E}_Q f(Y) \right]$$



Integral prob. metric vs feature difference

The MMD:

use

$$\mathbf{E}_P f(X) = \langle \mu_P, f \rangle_{\mathcal{F}}$$

$$\begin{aligned}
&MMD(P, Q; F) \\
&= \sup_{f \in F} \left[\mathbf{E}_P f(X) - \mathbf{E}_Q f(Y)\right] \\
&= \sup_{f \in F} \langle f, \mu_P - \mu_Q \rangle_{\mathcal{F}}
\end{aligned}$$

Integral prob. metric vs feature difference

The MMD:

$$
\begin{aligned}
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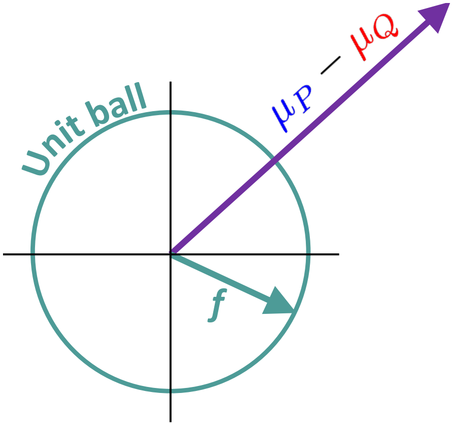

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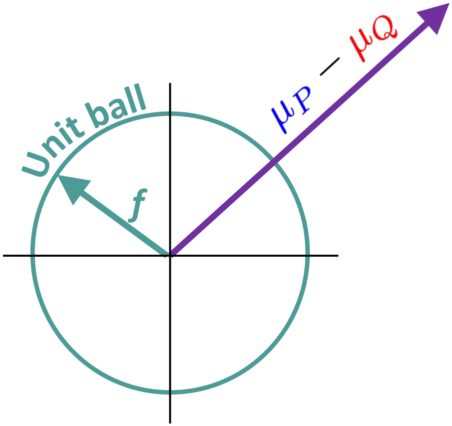

Integral prob. metric vs feature difference

The MMD:

$$MMD(P, Q; F)$$
$$= \sup_{f \in F} [\mathbf{E}_P f(X) - \mathbf{E}_Q f(Y)]$$
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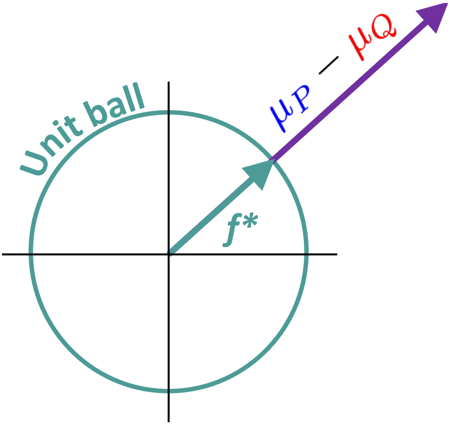


$$f^* = \frac{\mu_P - \mu_Q}{\|\mu_P - \mu_Q\|}$$

Integral prob. metric vs feature difference

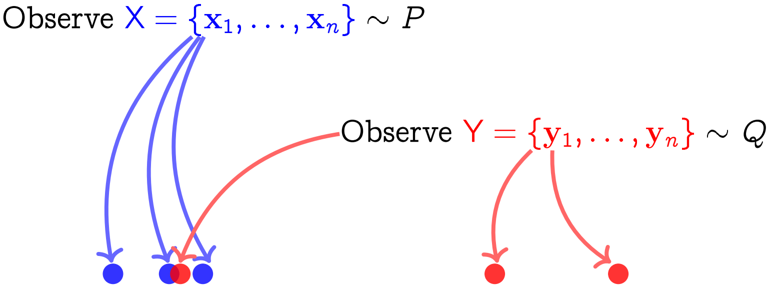
The MMD:

$$
\begin{aligned}
&MMD(P, Q; F) \\
&= \sup_{f \in F} \left[\mathbf{E}_P f(X) - \mathbf{E}_Q f(Y)\right] \\
&= \sup_{f \in F} \langle f, \mu_P - \mu_Q \rangle_{\mathcal{F}} \\
&= \|\mu_P - \mu_Q\|
\end{aligned}
$$

$\boxed{\text{Function view and feature view equivalent}}$

Construction of MMD witness

Construction of empirical witness function (proof: next slide!)



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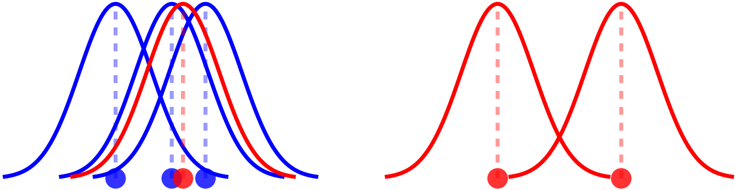

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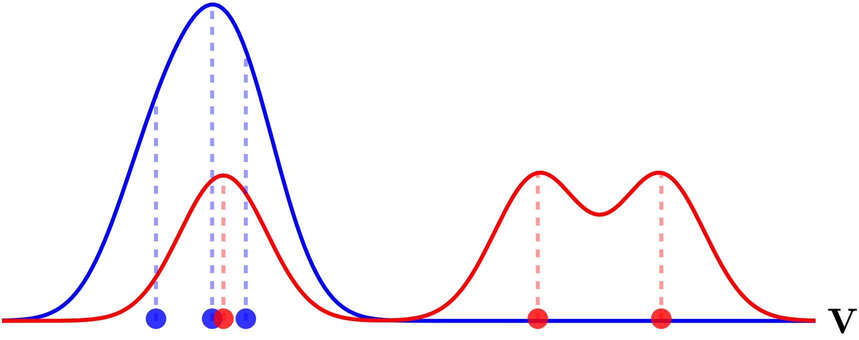

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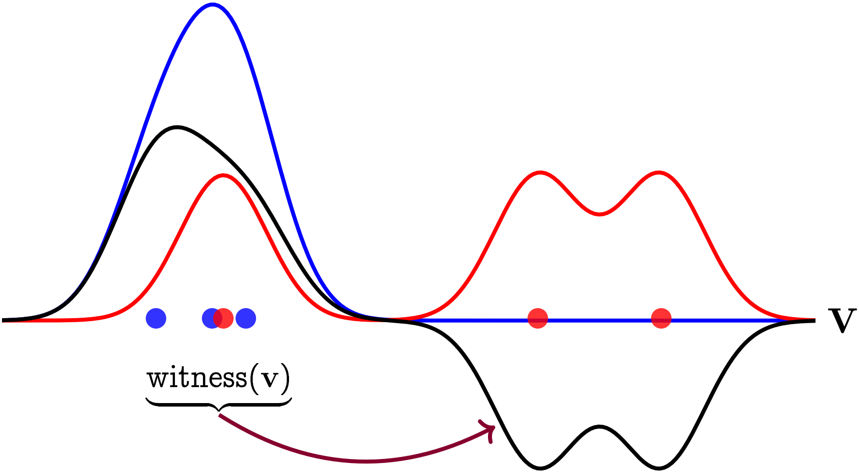

Derivation of empirical witness function

Recall the witness function expression

$$f^* \propto \mu_P - \mu_Q$$

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Recall the witness function expression

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$$\widehat{\mu}_P := \frac{1}{n}\sum_{i=1}^{n} \varphi(x_i)$$

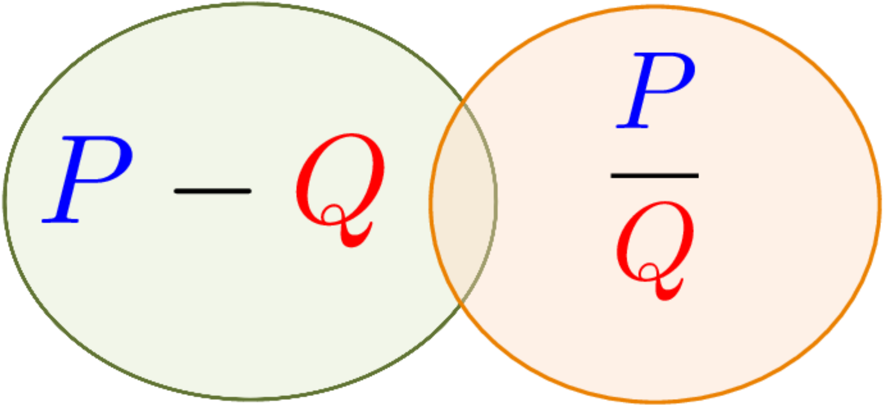
The empirical witness function at v

$$\begin{aligned} f^*(v) &= \langle f^*, \varphi(v)\rangle_{\mathcal{F}} \\ &\propto \langle \widehat{\mu}_P - \widehat{\mu}_Q, \varphi(v)\rangle_{\mathcal{F}} \\ &= \frac{1}{n}\sum_{i=1}^{n} k(x_i, v) - \frac{1}{n}\sum_{i=1}^{n} k(\mathrm{y}_i, v) \end{aligned}$$

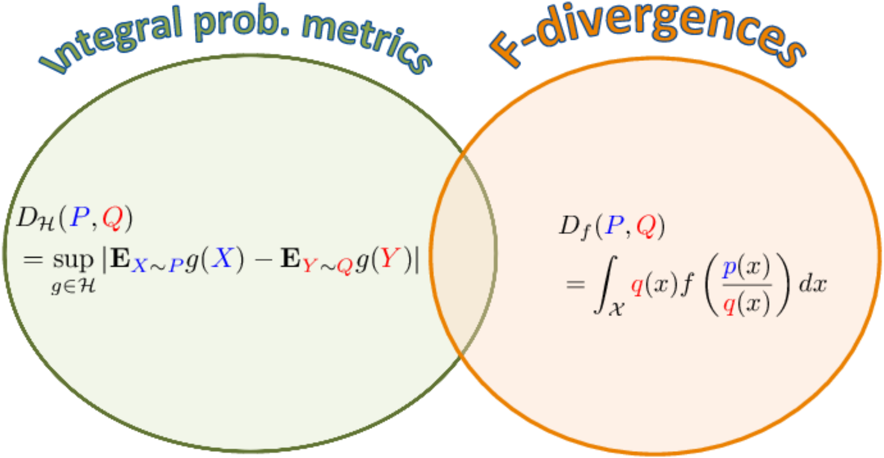
Don't need explicit feature coefficients $f^* := \begin{bmatrix} f_1^* & f_2^* & \dots \end{bmatrix}$

Interlude: divergence measures

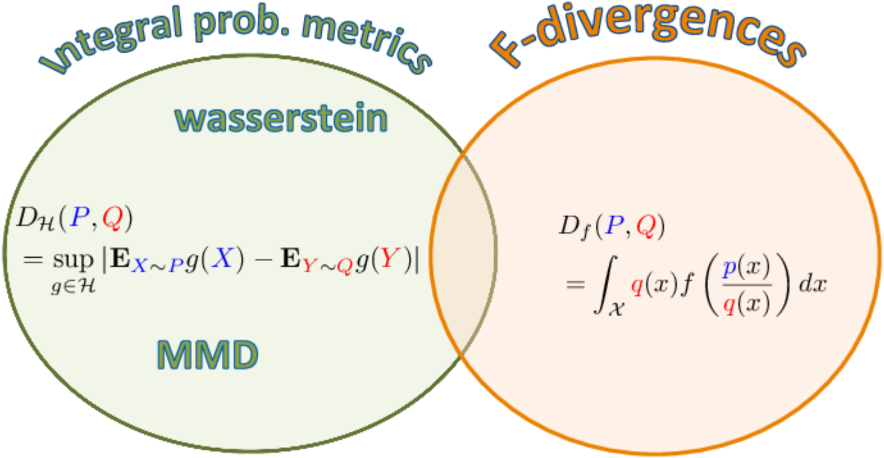
Divergences



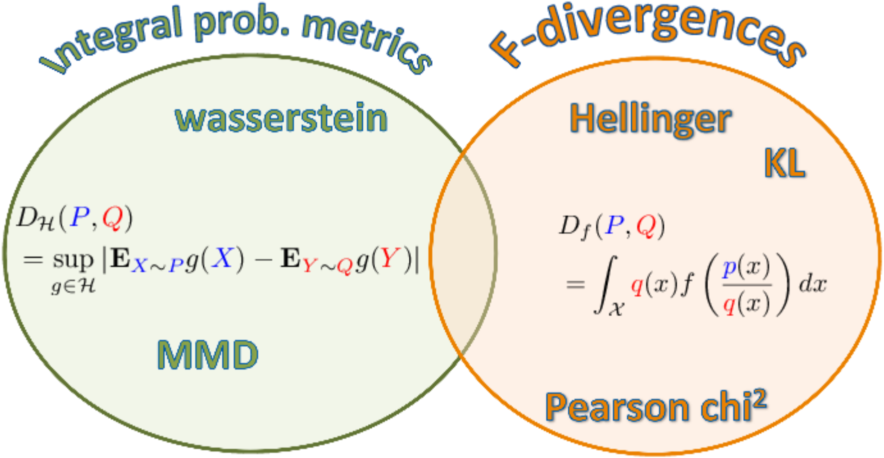
Divergences



Divergences



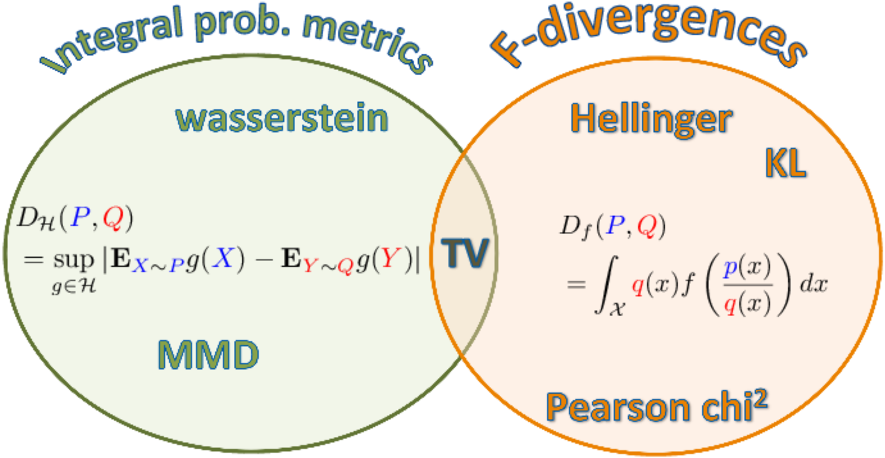
Divergences



$$D_{\mathcal{H}}(P,Q) = \sup_{g\in\mathcal{H}} |\mathbf{E}_{X\sim P}g(X) - \mathbf{E}_{Y\sim Q}g(Y)|$$

$$D_f(P,Q) = \int_{\mathcal{X}} q(x) f\left(\frac{p(x)}{q(x)}\right) dx$$

Divergences



Sriperumbudur, Fukumizu, G, Schoelkopf, Lanckriet (2012)

Two-Sample Testing with MMD

A statistical test using MMD

The empirical MMD:

$$\widehat{MMD}^2 = \frac{1}{n(n-1)} \sum_{i \neq j} k(x_i, x_j) + \frac{1}{n(n-1)} \sum_{i \neq j} k(\mathrm{y}_i, \mathrm{y}_j) - \frac{2}{n^2} \sum_{i,j} k(x_i, \mathrm{y}_j)$$

How does this help decide whether $P = Q$?

A statistical test using MMD

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Perspective from statistical hypothesis testing:

- **Null hypothesis** $\mathcal{H}_0$ when $P = Q$
  - should see $\widehat{MMD}^2$ "close to zero".
- **Alternative hypothesis** $\mathcal{H}_1$ when $P \neq Q$
  - should see $\widehat{MMD}^2$ "far from zero"

A statistical test using MMD

The empirical MMD:

$$\widehat{MMD}^2 = \frac{1}{n(n-1)} \sum_{i \neq j} k(x_i, x_j) + \frac{1}{n(n-1)} \sum_{i \neq j} k(\mathrm{y}_i, \mathrm{y}_j) - \frac{2}{n^2} \sum_{i,j} k(x_i, \mathrm{y}_j)$$

Perspective from statistical hypothesis testing:

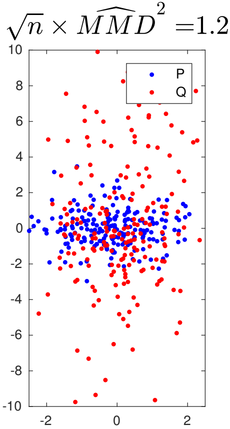
- **Null hypothesis $\mathcal{H}_0$** when $P = Q$
  - should see $\widehat{MMD}^2$ "close to zero".
- **Alternative hypothesis $\mathcal{H}_1$** when $P \neq Q$
  - should see $\widehat{MMD}^2$ "far from zero"

Want Threshold c_α for $\widehat{MMD}^2$ to get false positive rate α

Behaviour of $\widehat{MMD}^2$ when $P \neq Q$

Draw $n = 200$ i.i.d samples from P and Q

- Laplace with different y-variance.
- $\sqrt{n} \times \widehat{MMD}^2 = 1.2$



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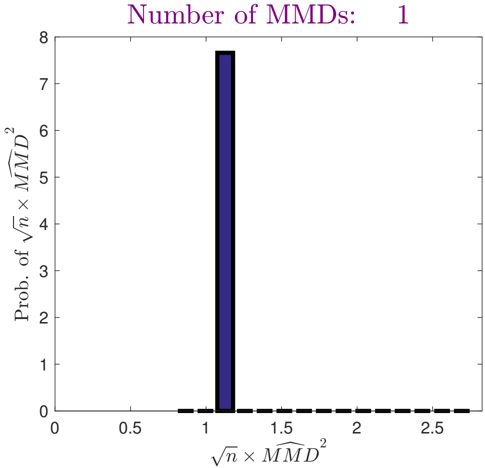
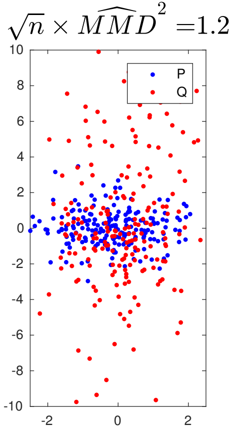
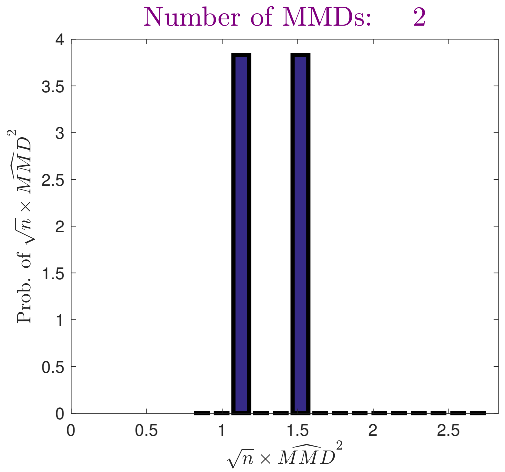


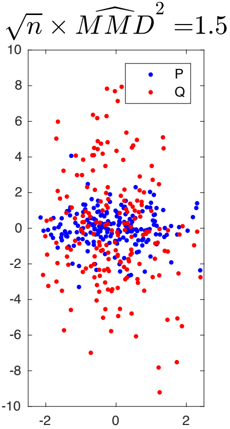


Behaviour of $\widehat{MMD}^2$ when $P \neq Q$

Draw $n = 200$ **new** samples from P and Q

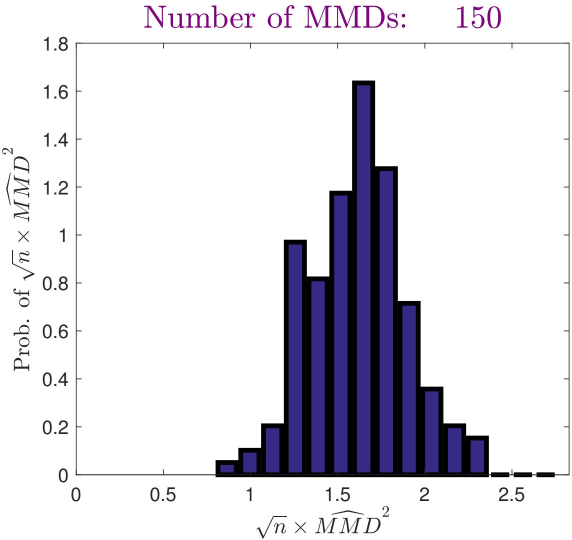
- Laplace with different y-variance.
- $\sqrt{n} \times \widehat{MMD}^2 = 1.5$





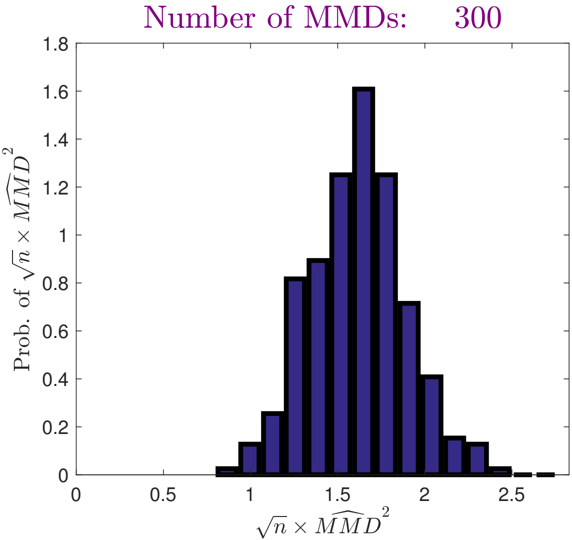
Behaviour of $\widehat{MMD}^2$ when $P \neq Q$

Repeat this 150 times . . .



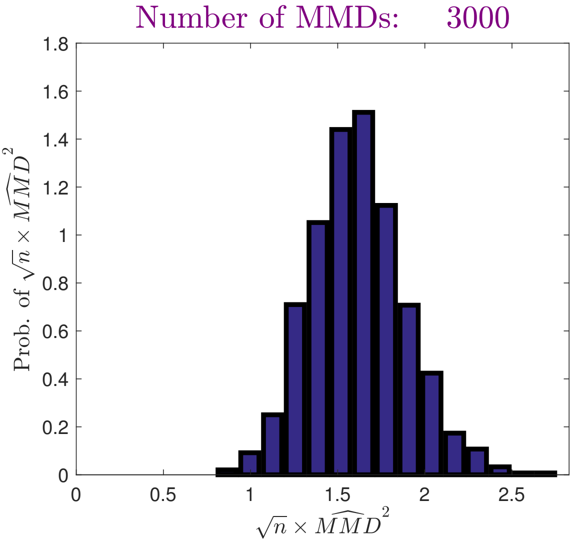
Behaviour of $\widehat{MMD}^2$ when $P \neq Q$

Repeat this 300 times ...



Behaviour of $\widehat{MMD}^2$ when $P \neq Q$

Repeat this 3000 times ...

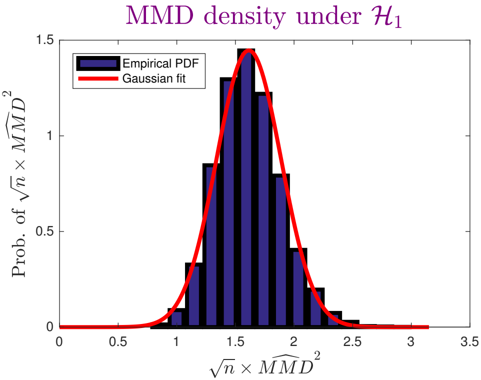


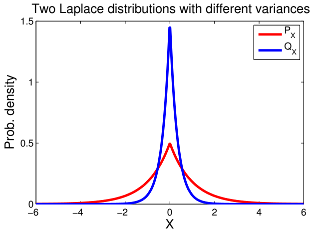
Asymptotics of $\widehat{MMD}^2$ when $P \neq Q$

When $P \neq Q$, statistic is asymptotically normal,

$$\frac{\widehat{\mathrm{MMD}}^2 - \mathrm{MMD}(P, Q)}{\sqrt{V_n(P, Q)}} \xrightarrow{D} \mathcal{N}(0, 1),$$

where variance $V_n(P, Q) = O\left(n^{-1}\right)$.



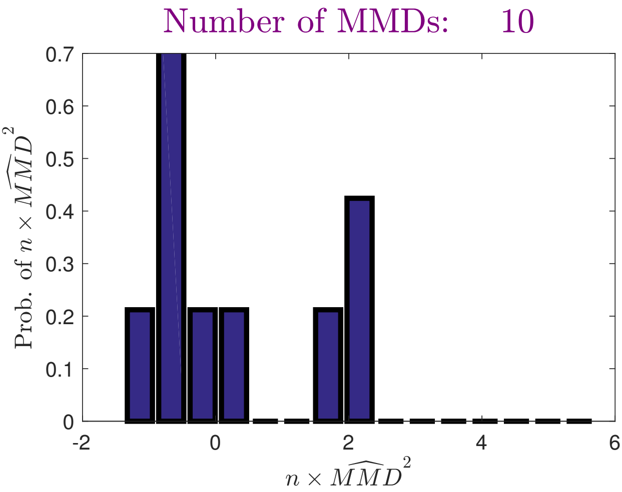


Behaviour of $\widehat{MMD}^2$ when $P = Q$

What happens when P and Q are the same?

Behaviour of $\widehat{MMD}^2$ when $P = Q$

- Case of $P = Q = \mathcal{N}(0,1)$



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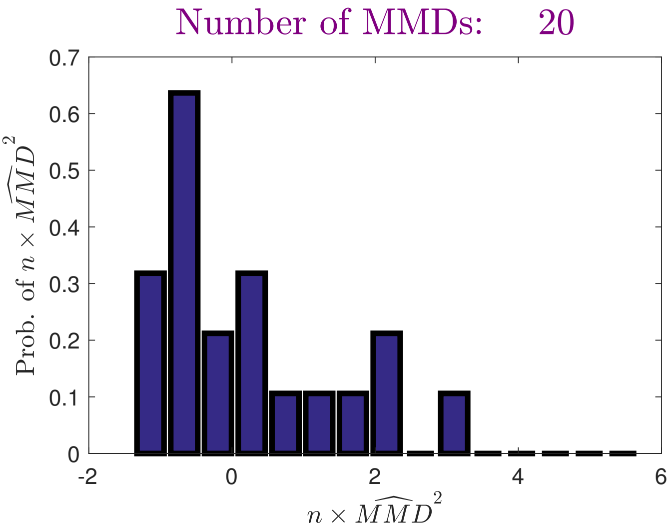

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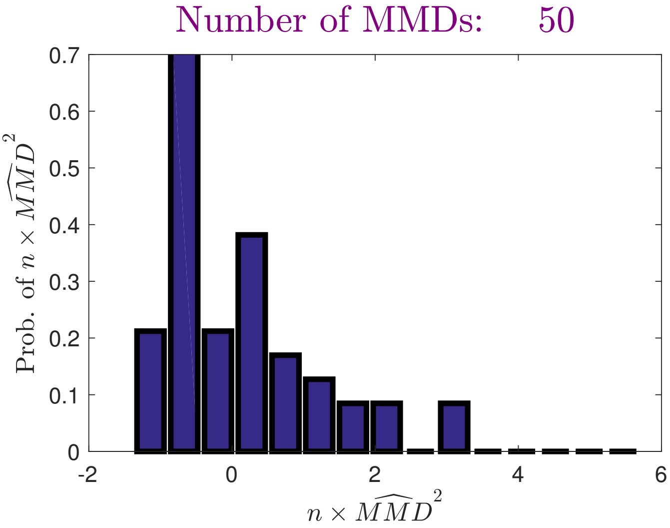

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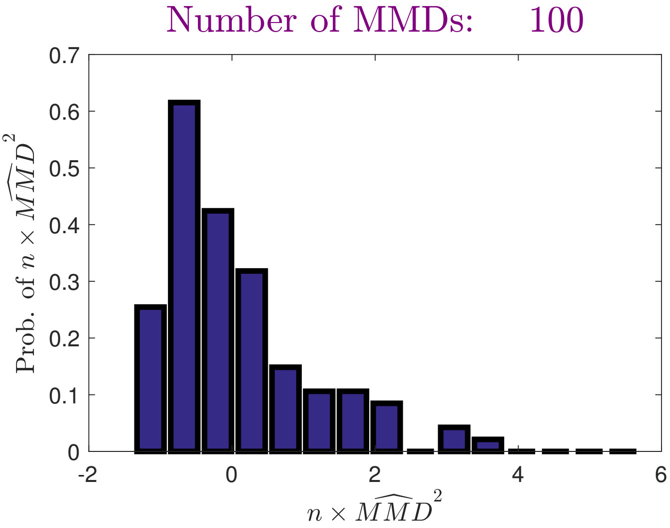

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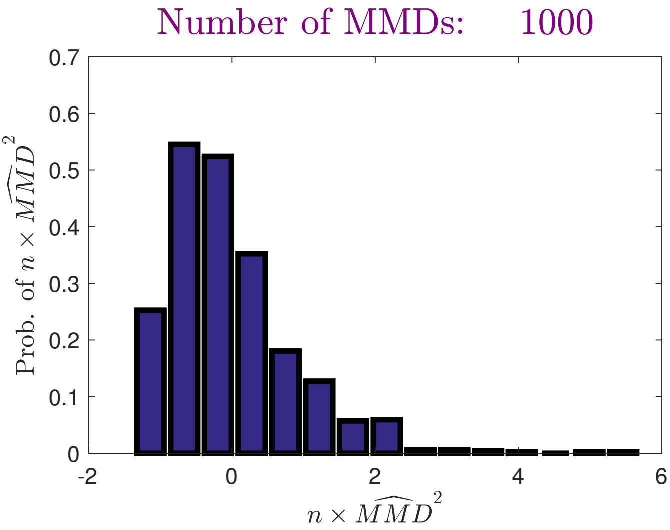
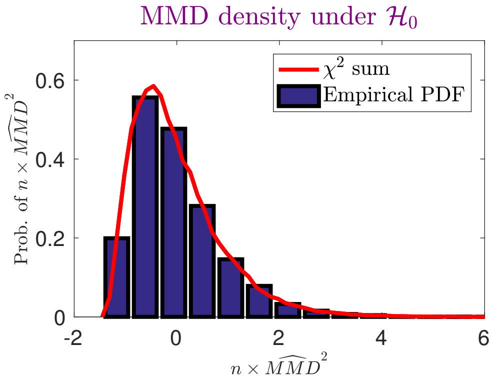


Asymptotics of $\widehat{MMD}^2$ when $P = Q$

Where $P = Q$, statistic has asymptotic distribution

$$n\widehat{\mathrm{MMD}}^2 \sim \sum_{l=1}^{\infty} \lambda_l \left[z_l^2 - 2 \right]$$



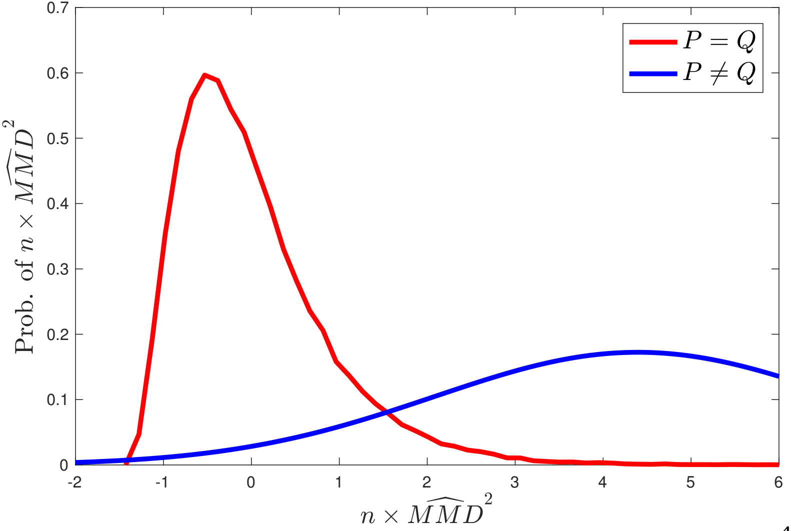
where

$$\lambda_i \psi_i(x') = \int_{\mathcal{X}} \underbrace{\tilde{k}(x, x')}_{\text{centred}} \psi_i(x) dP(x)$$

$$z_l \sim \mathcal{N}(0, 2) \quad \text{i.i.d.}$$

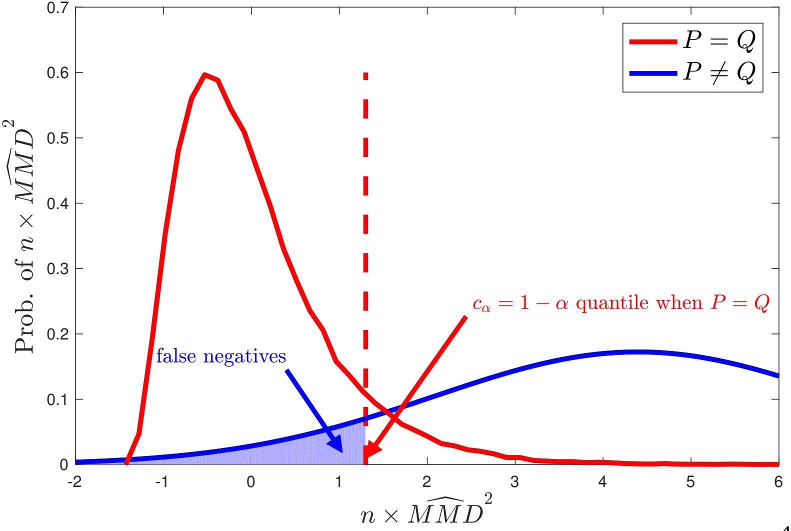
A statistical test

A summary of the asymptotics:



A statistical test

Test construction: (G., Borgwardt, Rasch, Schoelkopf, and Smola, JMLR 2012)



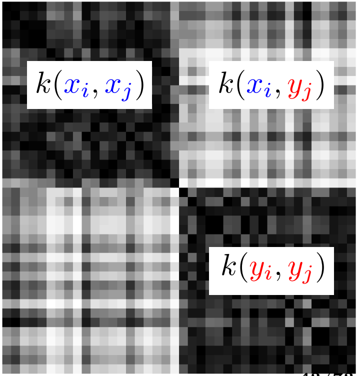
How do we get test threshold c_α?

Original empirical MMD for dogs and fish:

$X = [$  $\ldots]$

$Y = [$  $\ldots]$

$$\widehat{MMD}^2 = \frac{1}{n(n-1)} \sum_{i \neq j} k(x_i, x_j) + \frac{1}{n(n-1)} \sum_{i \neq j} k(y_i, y_j) - \frac{2}{n^2} \sum_{i,j} k(x_i, y_j)$$



How do we get test threshold c_α?

Permuted dog and fish samples (**merdogs**):

$\widetilde{X} = \Big[$  $\dots \Big]$

$\widetilde{Y} = \Big[$  $\dots \Big]$

How do we get test threshold c_α?

Permuted dog and fish samples (**merdogs**):

$\widetilde{X} = [$  $\dots\ ]$

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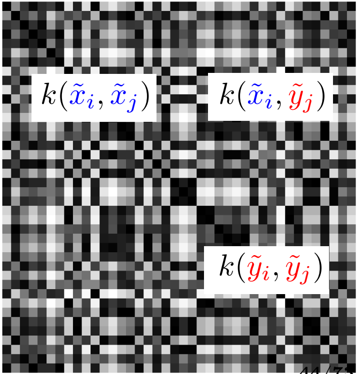
$$\widehat{MMD}^2 = \frac{1}{n(n-1)} \sum_{i \neq j} k(\tilde{x}_i, \tilde{x}_j) + \frac{1}{n(n-1)} \sum_{i \neq j} k(\tilde{y}_i, \tilde{y}_j) - \frac{2}{n^2} \sum_{i,j} k(\tilde{x}_i, \tilde{y}_j)$$

Permutation simulates

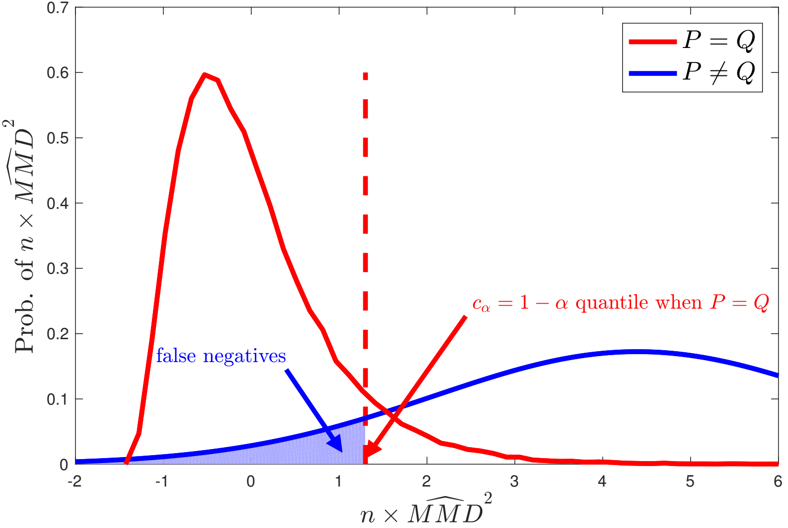
$P = Q$



How to choose the best kernel: optimising the kernel parameters

Graphical illustration

- Maximising test power same as minimizing false negatives



Optimizing kernel for test power

The power of our test ($\Pr_1$ denotes probability under $P \neq Q$):

$$\Pr_1\left(n\widehat{\mathrm{MMD}}^2 > \hat{c}_\alpha\right)$$

Optimizing kernel for test power

The power of our test ($\Pr_1$ denotes probability under $P \neq Q$):

$$\Pr_1\left(n\widehat{\mathrm{MMD}}^2 > \hat{c}_\alpha\right) \\ \to \Phi\left(\frac{n\mathrm{MMD}^2(P,Q)}{\sqrt{V_n(P,Q)}} - \frac{c_\alpha}{\sqrt{V_n(P,Q)}}\right)$$

where

- Φ is the CDF of the standard normal distribution.
- $\hat{c}_\alpha$ is an estimate of c_α test threshold.

Optimizing kernel for test power

The power of our test ($\Pr_1$ denotes probability under $P \neq Q$):

$$\Pr_1\left(n\widehat{\mathrm{MMD}}^2 > \hat{c}_\alpha\right)$$
$$\to \Phi\left(\underbrace{\frac{\mathrm{MMD}^2(P,Q)}{\sqrt{V_n(P,Q)}}}_{O(n^{1/2})} - \underbrace{\frac{c_\alpha}{n\sqrt{V_n(P,Q)}}}_{O(n^{-1/2})}\right)$$

Variance under $\mathcal{H}_1$ decreases as $\sqrt{V_n(P,Q)} \sim O(n^{-1/2})$

For large n, second term negligible!

Optimizing kernel for test power

The power of our test ($\Pr_1$ denotes probability under $P \neq Q$):

$$\Pr_1\left(n\widehat{\mathrm{MMD}}^2 > \hat{c}_\alpha\right)$$
$$\to \Phi\left(\frac{\mathrm{MMD}^2(P,Q)}{\sqrt{V_n(P,Q)}} - \frac{c_\alpha}{n\sqrt{V_n(P,Q)}}\right)$$

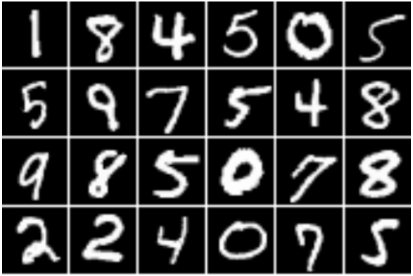
To maximize test power, maximize

$$\frac{\mathrm{MMD}^2(P,Q)}{\sqrt{V_n(P,Q)}}$$

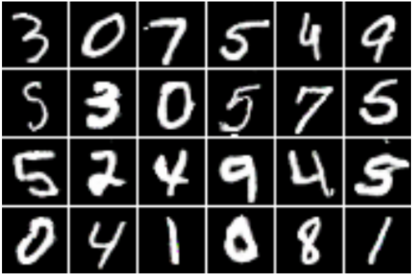
(Sutherland, Tung, Strathmann, De, Ramdas, Smola, G., ICLR 2017)

Code: github.com/dougalsutherland/opt-mmd

Troubleshooting for generative adversarial networks



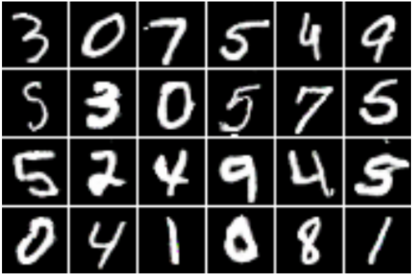
MNIST samples



Samples from a GAN

Troubleshooting for generative adversarial networks

MNIST samples



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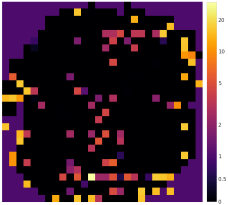
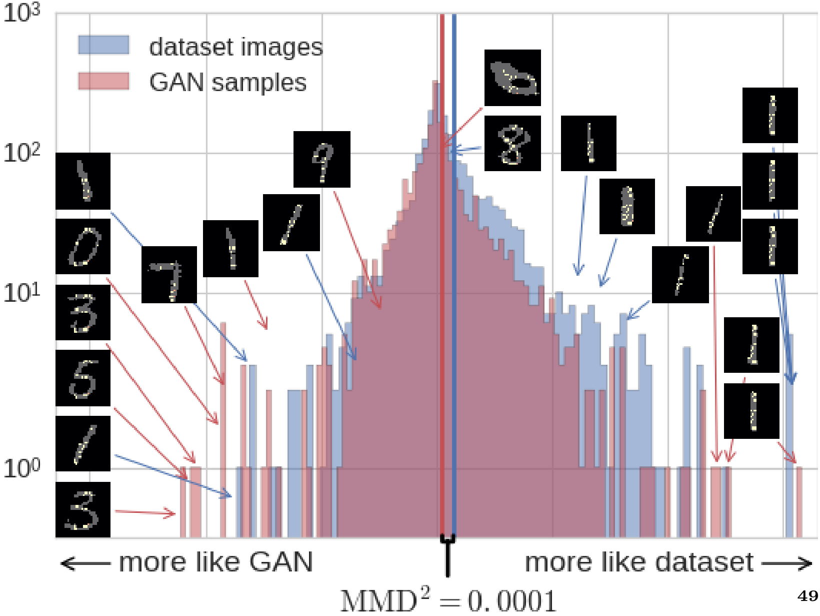


ARD map

- Power for **optimzed ARD kernel**: 1.00 at $\alpha = 0.01$
- Power for optimized RBF kernel: 0.57 at $\alpha = 0.01$

Troubleshooting generative adversarial networks



Training GANs with MMD

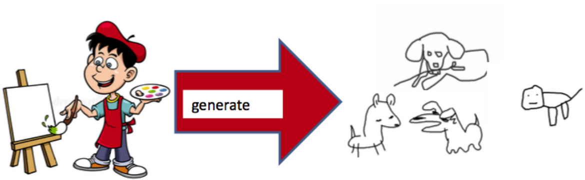
What is a Generative Adversarial Network (GAN)?

- Generator (student)

- Task: critic must teach generator to draw images (here dogs)

- Critic (teacher)

What is a Generative Adversarial Network (GAN)?



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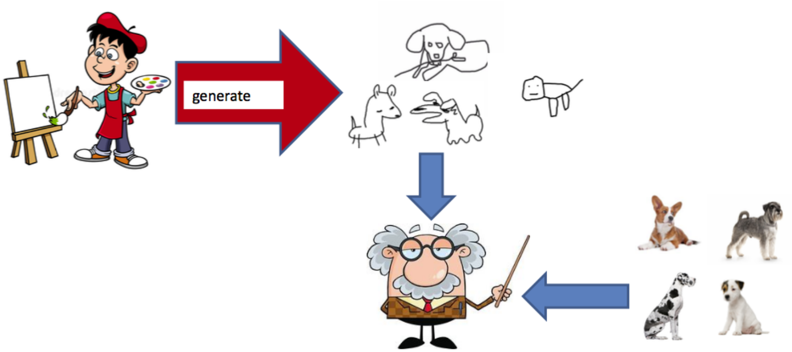

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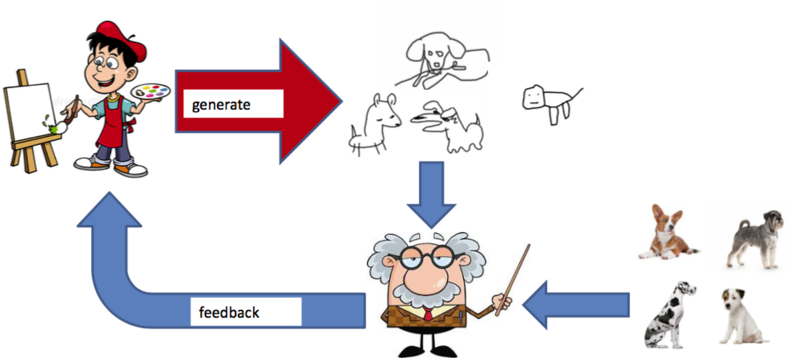
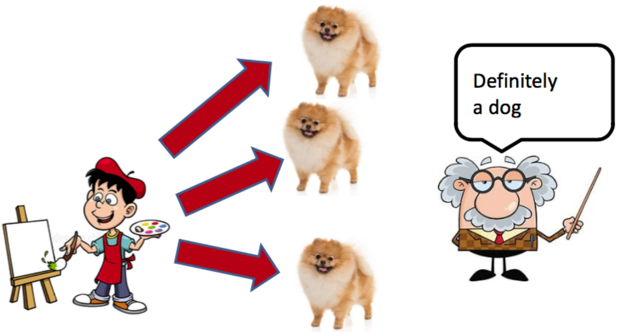


Why is classification not enough?



Classification **not** enough!

Need to compare **sets**

(otherwise student can just produce the same dog over and over)

MMD for GAN critic

Can you use MMD as a critic to train GANs?

From ICML 2015:

Generative Moment Matching Networks

Yujia Li[1] YUJIALI@CS.TORONTO.EDU
Kevin Swersky[1] KSWERSKY@CS.TORONTO.EDU
Richard Zemel[1,2] ZEMEL@CS.TORONTO.EDU
[1]Department of Computer Science, University of Toronto, Toronto, ON, CANADA
[2]Canadian Institute for Advanced Research, Toronto, ON, CANADA

From UAI 2015:

Training generative neural networks via Maximum Mean Discrepancy optimization

Gintare Karolina Dziugaite
University of Cambridge

Daniel M. Roy
University of Toronto

Zoubin Ghahramani
University of Cambridge

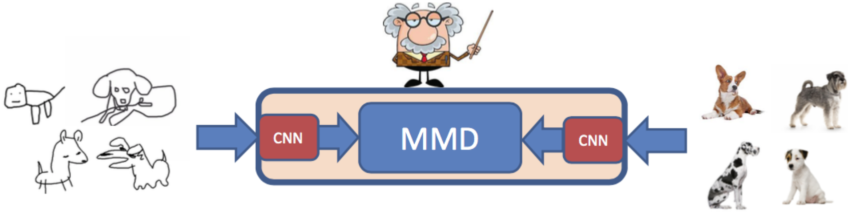
MMD for GAN critic

Can you use MMD as a critic to train GANs?

Need better image features.

How to improve the critic witness

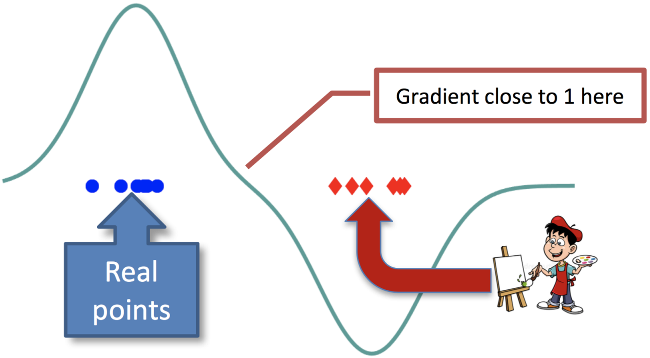
- Add convolutional features!
- The critic (teacher) also needs to be trained.
- How to regularise?



MMD GAN Li et al., [NIPS 2017]
Coulomb GAN Unterthiner et al., [ICLR 2018]

WGAN-GP

Wasserstein GAN Arjovsky et al. [ICML 2017]
WGAN-GP Gukrajani et al. [NIPS 2017]



WGAN-GP

Wasserstein GAN Arjovsky et al. [ICML 2017]
WGAN-GP Gukrajani et al. [NIPS 2017]

-  Given a generator G_θ with parameters θ to be trained. Samples $Y \sim G_\theta(Z)$ where $Z \sim R$
-  Given critic features h_ψ with parameters ψ to be trained. f_ψ a linear function of h_ψ.

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WGAN-GP gradient penalty:

$$\max_{\psi} \mathbf{E}_{X\sim P} f_\psi(X) - \mathbf{E}_{Z\sim R} f_\psi(G_\theta(Z)) + \lambda \mathbf{E}_{\widetilde{X}} \left(\left\| \nabla_{\widetilde{X}} f_\psi(\widetilde{X}) \right\| - 1 \right)^2$$

where

$$\widetilde{X} = \gamma x_i + (1-\gamma) G_\theta(z_j)$$

$$\gamma \sim \mathcal{U}([0,1]) \quad x_i \in \{x_\ell\}_{\ell=1}^m \quad z_j \in \{z_\ell\}_{\ell=1}^n$$

The (W)MMD

Train MMD critic features with the witness function gradient penalty

Binkowski, Sutherland, Arbel, G. [ICLR 2018], Bellemare et al. [2017] for energy distance:

$$\max_{\psi} MMD^2(h_\psi(X), h_\psi(G_\theta(Z))) + \lambda \mathbf{E}_{\widetilde{X}} \left(\left\| \nabla_{\widetilde{X}} f_\psi(\widetilde{X}) \right\| - 1 \right)^2$$

where

$$f_\psi(\cdot) = \frac{1}{m} \sum_{i=1}^{m} k(h_\psi(x_i), \cdot) - \frac{1}{n} \sum_{j=1}^{n} k(h_\psi(G_\theta(z_j)), \cdot)$$

New

$$\widetilde{X} = \gamma x_i + (1-\gamma) G_\theta(z_j)$$

$$\gamma \sim \mathcal{U}([0,1]) \quad x_i \in \{x_\ell\}_{\ell=1}^{m} \quad z_j \in \{z_\ell\}_{\ell=1}^{n}$$

Remark by Bottou et al. (2017): gradient penalty modifies the function class. So critic is not an MMD in RKHS $\mathcal{F}$.

MMD for GAN critic: revisited

From ICLR 2018:

Demystifying MMD GANs

Mikołaj Bińkowski*
Department of Mathematics
Imperial College London
mikbinkowski@gmail.com

Dougal J. Sutherland,* Michael Arbel & Arthur Gretton
Gatsby Computational Neuroscience Unit
University College London
{dougal,michael.n.arbel,arthur.gretton}@gmail.com

MMD for GAN critic: revisited

Samples are better!

MMD for GAN critic: revisited

Samples are better!

Can we do better still?

Convergence issues for WGAN-GP penalty

WGAN-GP style gradient penalty may not converge near solution

Nagarajan and Kolter [NIPS 2017], Mescheder et al. [ICML 2018], Balduzzi et al. [ICML 2018]

The Dirac-GAN

$$P = \delta_0 \qquad Q = \delta_\theta \qquad f_\psi(x) = \psi \cdot x$$

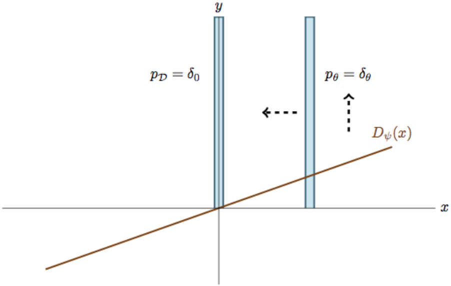

Figure from Mescheder et al. [ICML 2018]

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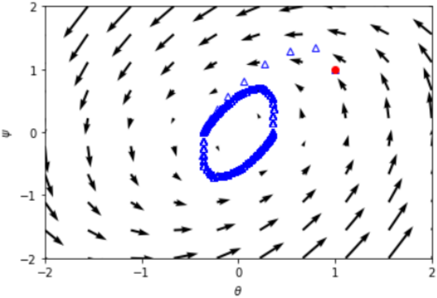

Figure from Mescheder et al. [ICML 2018]

A better gradient penalty

- New MMD GAN witness regulariser (NIPS 2018)

  Arbel, Sutherland, Binkowski, G. [NIPS 2018]
- Based on semi-supervised learning regulariser Bousquet et al. [NIPS 2004]
- Related to Sobolev GAN Mroueh et al. [ICLR 2018]

arXiv.org > stat > arXiv:1805.11565

Statistics > Machine Learning

On gradient regularizers for MMD GANs

Michael Arbel, Dougal J. Sutherland, Mikołaj Bińkowski, Arthur Gretton

(Submitted on 29 May 2018)

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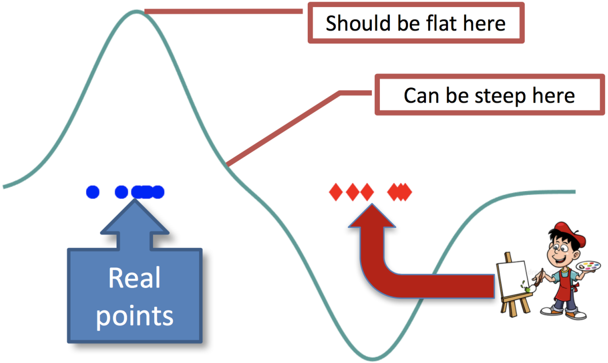

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Modified witness function:

$$\widetilde{MMD} := \sup_{\boxed{\|f\|_S \leq 1}} \left[\mathbb{E}_P f(X) - \mathbb{E}_Q f(Y)\right]$$

where

$$\|f\|_S^2 = \underbrace{\|f\|^2_{L_2(P)}}_{\text{L}_2\text{ norm control}} + \underbrace{\|\nabla f\|^2_{L_2(P)}}_{\text{Gradient control}} + \lambda \underbrace{\|f\|_k^2}_{\text{RKHS smoothness}}$$

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Problem: not computationally feasible: $O(n^3)$ per iteration.

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The scaled MMD:

$$SMMD = \sigma_{k,P,\lambda}\ MMD$$

where

$$\sigma_{k,P,\lambda} = \left(\lambda + \int k(x,x)\,dP(x) + \sum_{i=1}^{d} \int \partial_i \partial_{i+d} k(x,x)\ dP(x) \right)^{-1/2}$$

Replace expensive constraint with cheap upper bound:

$$\|f\|_S^2 \leq \sigma_{k,P,\lambda}^{-1}\ \|f\|_k^2$$

A better gradient penalty

- New MMD GAN witness regulariser (NIPS 2018)

  Arbel, Sutherland, Binkowski, G. [NIPS 2018]
- Based on semi-supervised learning regulariser Bousquet et al. [NIPS 2004]
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Idea: rather than regularise the critic or witness function, regularise features directly

Evaluation and experiments

Evaluation of GANs

The inception score? Salimans et al. [NIPS 2016]

Based on the classification output $p(y|x)$ of the inception model Szegedy et al. [ICLR 2014],

$$E_X \exp KL(P(y|X) \| P(y)).$$

High when:

- predictive label distribution $P(y|x)$ has low entropy (good quality images)
- label entropy $P(y)$ is high (good variety).

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Problem: relies on a trained classifier! Can't be used on new categories (celeb, bedroom...)

Evaluation of GANs

The Frechet inception distance? Heusel et al. [NIPS 2017]

Fits Gaussians to features in the inception architecture (pool3 layer):

$$FID(P, Q) = \|\mu_P - \mu_Q\|^2 + \text{tr}(\Sigma_P) + \text{tr}(\Sigma_Q) - 2\text{tr}\left((\Sigma_P \Sigma_Q)^{\frac{1}{2}}\right)$$

where μ_P and Σ_P are the feature mean and covariance of P

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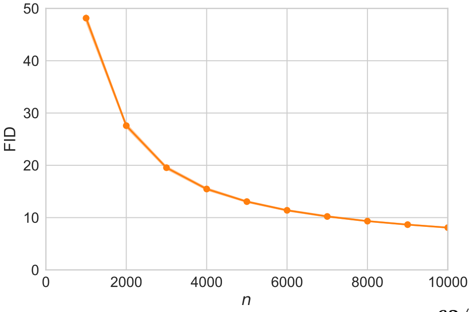
Problem: bias. For finite samples can consistently give incorrect answer.

- Bias demo, CIFAR-10 train vs test



Evaluation of GANs

The FID can give the wrong answer in theory.

Assume m samples from P and $n \to \infty$ samples from Q.

Given two alternatives:

$$P_1 \sim \mathcal{N}(0, (1 - m^{-1})^2) \qquad P_2 \sim \mathcal{N}(0, 1) \qquad Q \sim \mathcal{N}(0, 1).$$

Clearly,

$$FID(P_1, Q) = \frac{1}{m^2} > FID(P_2, Q) = 0$$

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Evaluation of GANs

The FID can give the wrong answer in practice.

Let $d = 2048$, and define

$$P_1 = \mathrm{relu}(\mathcal{N}(\mathbf{0}, I_d)) \quad P_2 = \mathrm{relu}(\mathcal{N}(\mathbf{1}, .8\Sigma + .2I_d)) \qquad Q = \mathrm{relu}(\mathcal{N}(\mathbf{1}, I_d))$$

where $\Sigma = \frac{4}{d}CC^T$, with C a $d \times d$ matrix with iid standard normal entries.

For a random draw of C:

$$FID(P_1, Q) \approx 1123.0 > 1114.8 \approx FID(P_2, Q)$$

With $m = 50\,000$ samples,

$$FID(\widehat{P_1}, Q) \approx 1133.7 < 1136.2 \approx FID(\widehat{P_2}, Q)$$

At $m = 100\,000$ samples, the ordering of the estimates is correct.

This behavior is similar for other random draws of C.

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The kernel inception distance (KID)

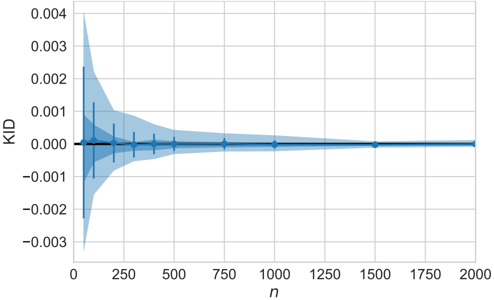
The Kernel inception distance Binkowski, Sutherland, Arbel, G. [ICLR 2018]

Measures similarity of the samples' representations in the inception architecture (pool3 layer)

MMD with kernel

$$k(x, y) = \left(\frac{1}{d} x^\top y + 1\right)^3 .$$

- Checks match for feature means, variances, skewness
- Unbiased : eg CIFAR-10 train/test



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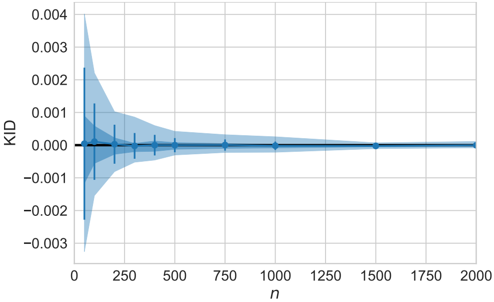

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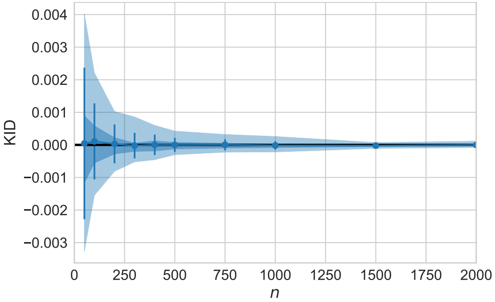

..."but isn't KID is computationally costly?"

"Block" KID implementation is cheaper than FID: see paper (or use Tensorflow implementation)!

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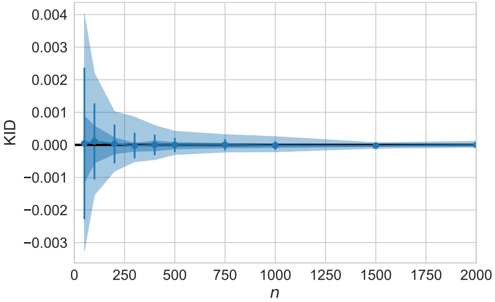

Also used for automatic learning rate adjustment: if $KID(\widehat{P}_{t+1}, Q)$ not significantly better than $KID(\widehat{P}_t, Q)$ then reduce learning rate.

[Bounliphone et al. ICLR 2016]

Related: "An empirical study on evaluation metrics of generative adversarial networks", Xu et al. [arxiv, June 2018]

Benchmarks for comparison (all from ICLR 2018)

SPECTRAL NORMALIZATION FOR GENERATIVE ADVERSARIAL NETWORKS

Takeru Miyato[1], **Toshiki Kataoka**[1], **Masanori Koyama**[2], **Yuichi Yoshida**[3]
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yos i.ac.jp
works, Inc. [2]Ritsumeikan University [3]National Institute of Informatics

We combine with scaled MMD

SOBOLEV GAN

Youssef Mroueh[†], **Chun-Liang Li**[∘,⋆], **Tom Sercu**[†,⋆], **Anant Raj**[◊,⋆] **& Yu Cheng**[†]
† IBM Research AI
∘ Carnegie Mellon University
◊ Max Planck Institute for Intelligent Systems
⋆ denotes Equal Contribution
{mroueh,chengyu}@us.ibm.com, chunlial@cs.cmu.edu,
tom.sercu1@ibm.com, anant.raj@tuebingen.mpg.de

DEMYSTIFYING MMD GANS

Mikołaj Bińkowski[*]
Department of Mathematics
Imperial College London
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Dougal J. Sutherland,[*] **Michael Arbel & Arthur Gretton**
Gatsby Computational Neuroscience Unit
Uni College London
,michael.n.arbel,arthur.gretton}@gmail.com

Our ICLR 2018 paper

BOUNDARY-SEEKING GENERATIVE ADVERSARIAL NETWORKS

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kyunghyun.cho@nyu.edu

Yoshua Bengio
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yoshua.bengio@umontreal.ca

Results: what does MMD buy you?

- Critic features from DCGAN: an f-filter critic has f, $2f$, $4f$ and $8f$ convolutional filters in layers 1-4. LSUN 64×64.

MMD GAN samples, $f = 64$,
KID=3

WGAN samples, $f = 64$,
KID=4

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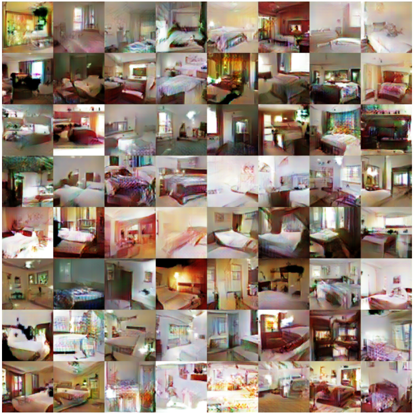
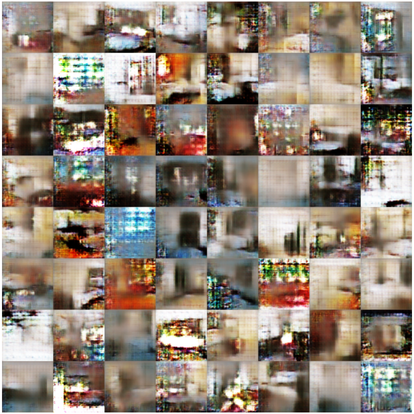


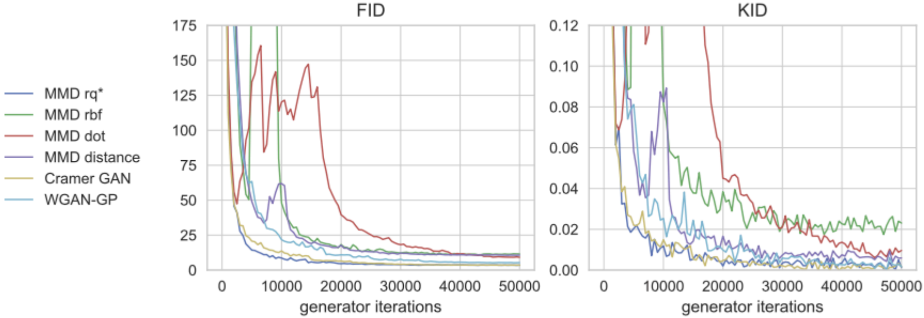
MMD GAN samples, $f = 16$,
KID=9



WGAN samples, $f = 16$,
$f = 64$, KID=37

The kernel inception distance (KID)

Faster training: performance scores vs generator iterations on MNIST



Results: celebrity faces 160×160

KID scores:

- Sobolev GAN: 14
- SN-GAN: 18
- Old MMD GAN: 13
- SMMD GAN: 6

202 599 face images, resized and cropped to 160 × 160

Results: imagenet 64×64

KID (FID) scores:

- BGAN: 47
- SN-GAN: 44
- SMMD GAN: 35

ILSVRC2012 (ImageNet) dataset, 1 281 167 images, resized to 64×64. Around 20 000 classes.

Results: imagenet 64×64

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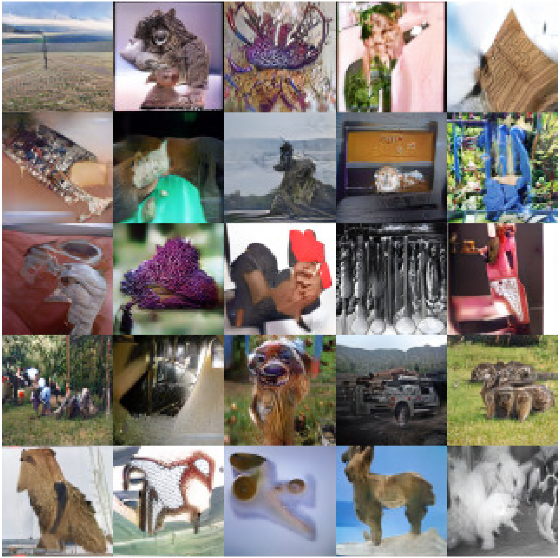

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Summary

- MMD critic gives state-of-the-art performance for GAN training (FID and KID)
  - use convolutional input features
  - train with new gradient regulariser
- Faster training, simpler critic network
- Reasons for good performance:
  - Unlike WGAN-GP, MMD loss still a valid critic when features not optimal
  - Kernel features do some of the "work", so simpler h_ψ features possible.
  - Better gradient/feature regulariser gives better critic

"Demystifying MMD GANs," including KID score, ICLR 2018:

https://github.com/mbinkowski/MMD-GAN

Gradient regularised MMD, NIPS 2018:

https://github.com/MichaelArbel/Scaled-MMD-GAN

Co-authors

From Gatsby:

- Mikolaj Binkowski
- Kacper Chwialkowski
- Wittawat Jitkrittum
- Heiko Strathmann
- Dougal Sutherland
- Wenkai Xu

External collaborators:

- Kenji Fukumizu
- Bernhard Schoelkopf
- Dino Sejdinovic
- Bharath Sriperumbudur
- Alex Smola
- Zoltan Szabo

Questions?


THE KERNEL
BREWERY
LONDON
BALTIC PORTER
THE KERNEL
EXPORT STOUT