

# Representing and comparing probabilities: Part 2

Arthur Gretton

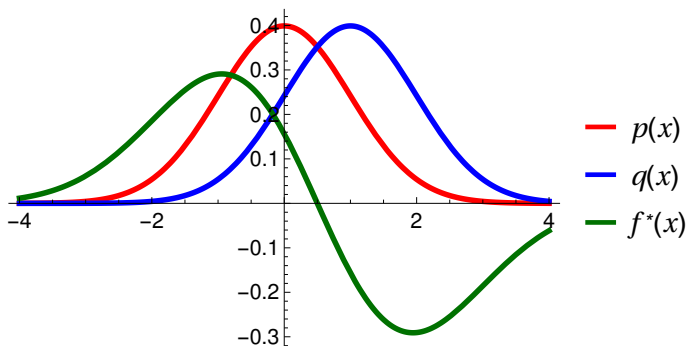
Gatsby Computational Neuroscience Unit,  
University College London

UAI, 2017

# Testing against a probabilistic model

## Statistical model criticism

$$MMD(P, Q) = \|f^*\|^2 = \sup_{\|f\|_{\mathcal{F}} \leq 1} [E_Q f - E_P f]$$



$f^*(x)$  is the witness function

Can we compute MMD with samples from  $Q$  and a model  $P$ ?

**Problem:** usually can't compute  $E_P f$  in closed form.

## Stein idea

To get rid of  $E_p f$  in

$$\sup_{\|f\|_{\mathcal{F}} \leq 1} [E_q f - E_p f]$$

we define the **Stein operator**

$$[T_p f](x) = \frac{1}{p(x)} \frac{d}{dx} (f(x)p(x))$$

Then

$$E_P T_P f = 0$$

subject to appropriate boundary conditions. (Oates, Girolami, Chopin, 2016)

## Stein idea: proof

$$\begin{aligned} E_p [T_p f] &= \int \left[ \frac{1}{p(x)} \frac{d}{dx} (f(x)p(x)) \right] p(x) dx \\ &= \int \left[ \frac{d}{dx} (f(x)p(x)) \right] dx \\ &= [f(x)p(x)]_{-\infty}^{\infty} \\ &= 0 \end{aligned}$$

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# Kernel Stein Discrepancy

Stein operator

$$T_p f = \partial_x f + f \partial_x (\log p)$$

**Kernel Stein Discrepancy (KSD)**

$$KSD(p, q, \mathcal{F}) = \sup_{\|g\|_{\mathcal{F}} \leq 1} E_q T_p g - E_p T_p g$$

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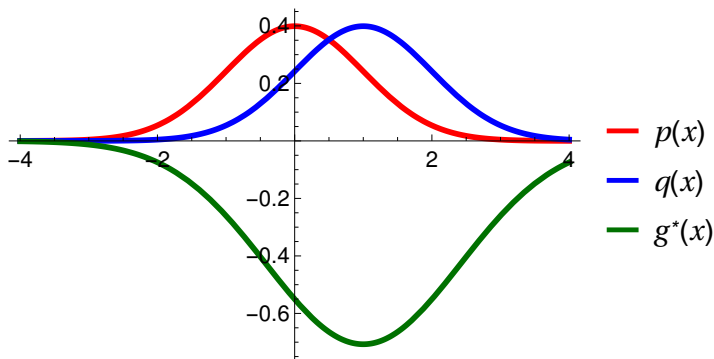
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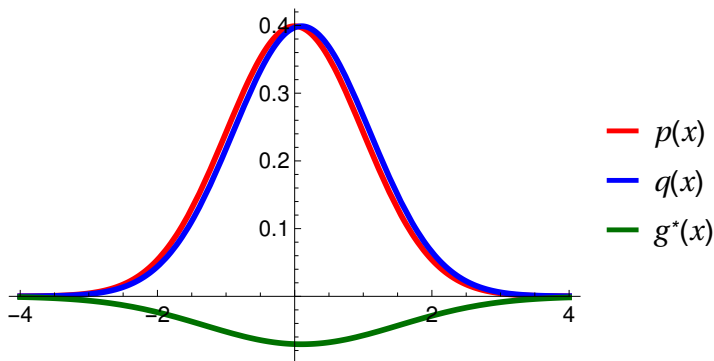
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## Kernel stein discrepancy

Closed-form expression for KSD: given  $Z, Z' \sim q$ , then  
(Chwialkowski, Strathmann, G., ICML 2016) (Liu, Lee, Jordan ICML 2016)

$$\text{KSD}(p, q, \mathcal{F}) = E_q h_p(Z, Z')$$

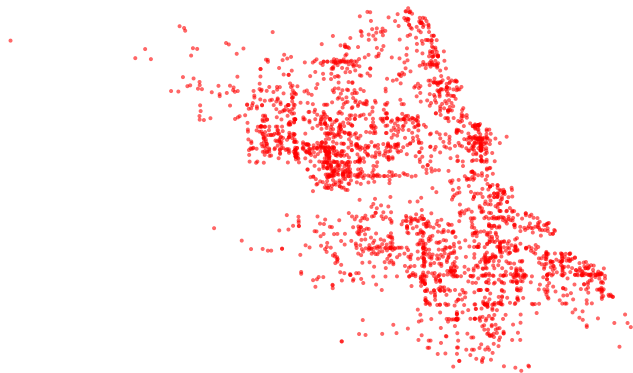
where

$$\begin{aligned} h_p(x, y) &:= \partial_x \log p(x) \partial_x \log p(y) k(x, y) \\ &\quad + \partial_y \log p(y) \partial_x k(x, y) \\ &\quad + \partial_x \log p(x) \partial_y k(x, y) \\ &\quad + \partial_x \partial_y k(x, y) \end{aligned}$$

and  $k$  is RKHS kernel for  $\mathcal{F}$

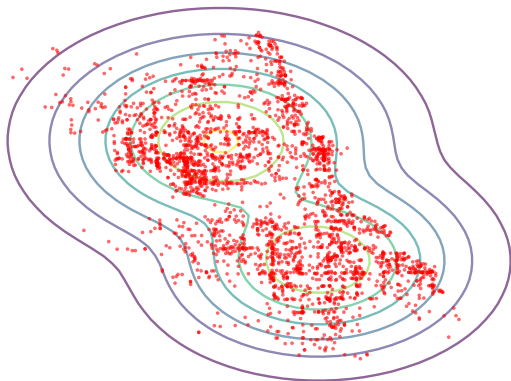
Only depends on kernel and  $\partial_x \log p(x)$ . Do not need to normalize  $p$ , or sample from it.

## Statistical model criticism



Chicago crime data

## Statistical model criticism

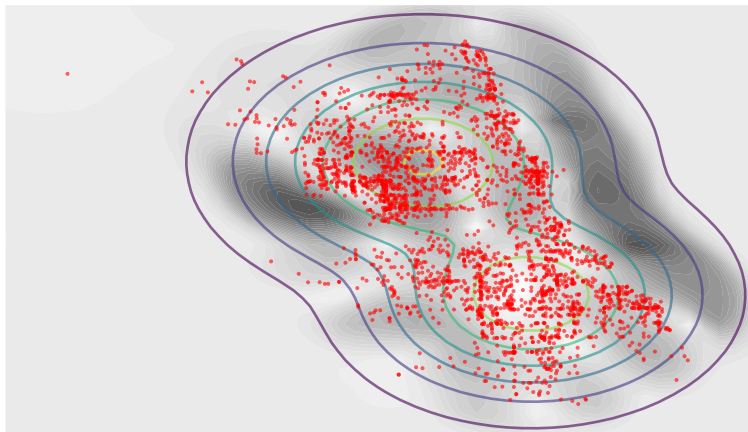


Chicago crime data

Model is Gaussian mixture with **two** components.



## Statistical model criticism

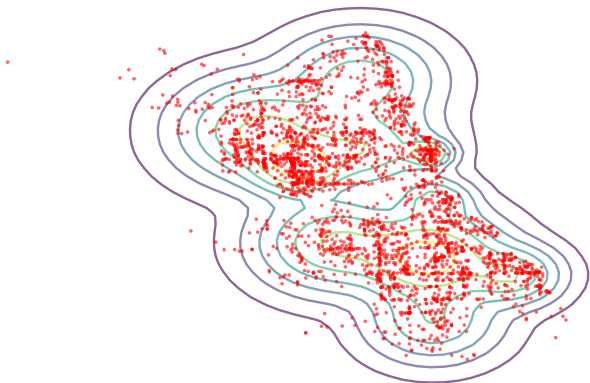


Chicago crime data

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Stein witness function

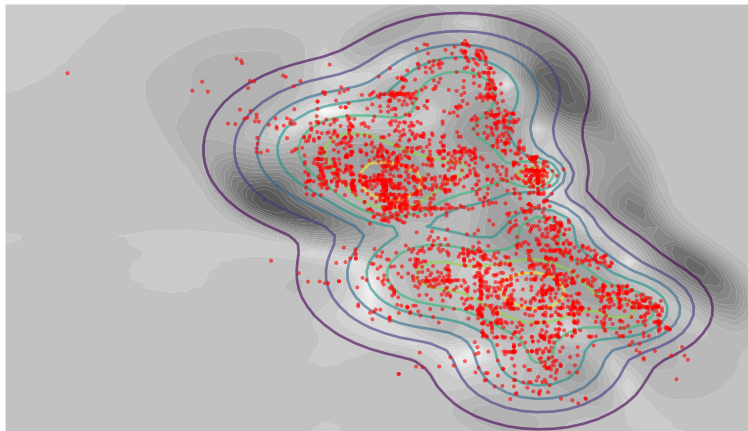
## Statistical model criticism



Chicago crime data

Model is Gaussian mixture with **ten** components.

## Statistical model criticism



Chicago crime data

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Stein witness function

Code: [https://github.com/karlnapf/kernel\\_goodness\\_of\\_fit](https://github.com/karlnapf/kernel_goodness_of_fit)

# Kernel stein discrepancy

## Further applications:

- Evaluation of approximate MCMC methods.  
(Chwialkowski, Strathmann, G., ICML 2016; Gorham, Mackey, ICML 2017)

## What kernel to use?

- The inverse multiquadric kernel,

$$k(x, y) = \left( c + \|x - y\|_2^2 \right)^\beta$$

for  $\beta \in (-1, 0)$ .

arXiv.org > stat > arXiv:1703.01717

Statistics > Machine Learning

### Measuring Sample Quality with Kernels

Jackson Gorham, Lester Mackey




ICML 2017

*(Submitted on 6 Mar 2017 (v1), last revised 3 Aug 2017 (this version, v6))*

# Testing statistical dependence

## Dependence testing

- Given: Samples from a distribution  $P_{X,Y}$
- Goal: Are  $X$  and  $Y$  independent?

X	Y
	A large animal who slings slobber, exudes a distinctive houndy odor, and wants nothing more than to follow his nose.
	Their noses guide them through life, and they're never happier than when following an interesting scent.
	A responsive, interactive pet, one that will blow in your ear and follow you everywhere.

Text from dogtime.com and petfinder.com

## MMD as a dependence measure?

Could we use MMD?

$$MMD(\underbrace{P_{XY}}_P, \underbrace{P_X P_Y}_Q, \mathcal{H}_\kappa)$$

- We don't have samples from  $Q := P_X P_Y$ , only pairs  $\{(x_i, y_i)\}_{i=1}^n \stackrel{\text{i.i.d.}}{\sim} P_{XY}$ 
  - **Solution:** simulate  $Q$  with pairs  $(x_i, y_j)$  for  $j \neq i$ .
- What kernel  $\kappa$  to use for the RKHS  $\mathcal{H}_\kappa$ ?

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## MMD as a dependence measure

Kernel  $k$  on images with feature space  $\mathcal{F}$ ,

$$k(\text{dog image}, \text{cat image})$$

Kernel  $l$  on captions with feature space  $\mathcal{G}$ ,

$$l(\text{A large animal who slings slobber, ...}, \text{A responsive, interactive pet ...})$$

## MMD as a dependence measure

Kernel  $k$  on **images** with feature space  $\mathcal{F}$ ,

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Kernel  $l$  on **captions** with feature space  $\mathcal{G}$ ,

$$l(\text{caption box}, \text{caption box})$$

Kernel  $\kappa$  on **image-text pairs**: **are images and captions similar?**

$$\kappa(\text{dog image}, \text{caption box}, \text{cat image}, \text{caption box})$$

$$= k(\text{dog image}, \text{cat image}) \times l(\text{caption box}, \text{caption box})$$

## MMD as a dependence measure

- **Given:** Samples from a distribution  $P_{XY}$
- **Goal:** Are  $X$  and  $Y$  independent?

$$MMD^2(\hat{P}_{XY}, \hat{P}_X \hat{P}_Y, \mathcal{H}_\kappa) := \frac{1}{n^2} \text{trace}(KL)$$

( $K, L$  column centered)

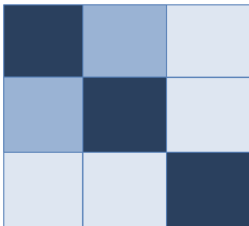
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**K**

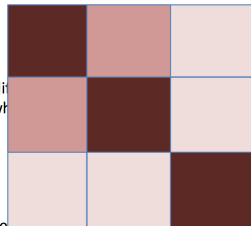


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**L**



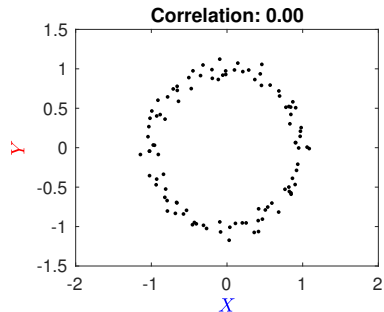
## MMD as a dependence measure

Two questions:

- Why the product kernel? Many ways to combine kernels - why not eg a sum?
- Is there a more interpretable way of defining this dependence measure?

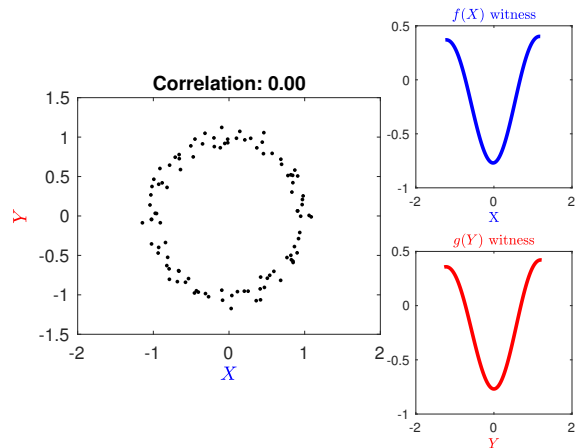
## Finding covariance with smooth transformations

Illustration: two variables with no **correlation** but strong **dependence**.



## Finding covariance with smooth transformations

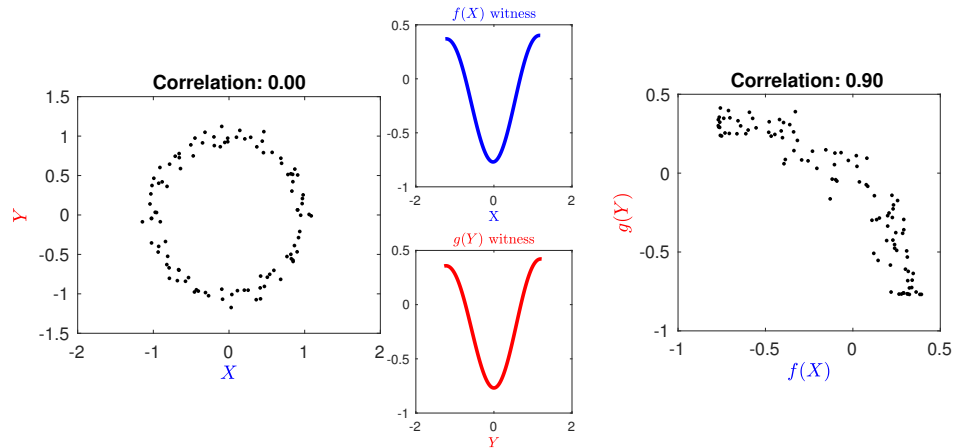
Illustration: two variables with no **correlation** but strong **dependence**.





## Finding covariance with smooth transformations

Illustration: two variables with no **correlation** but strong **dependence**.



## Define two spaces, one for each witness

Function in  $\mathcal{F}$

$$f(x) = \sum_{j=1}^{\infty} f_j \varphi_j(x)$$

Feature map

$$\varphi(x) = \begin{bmatrix} \varphi_1(x) \\ \varphi_2(x) \\ \varphi_3(x) \\ \vdots \end{bmatrix}$$

Kernel for RKHS  $\mathcal{F}$  on  $\mathcal{X}$ :

$$k(x, x') = \langle \varphi(x), \varphi(x') \rangle_{\mathcal{F}}$$

Function in  $\mathcal{G}$

$$g(y) = \sum_{j=1}^{\infty} g_j \phi_j(y)$$

Feature map

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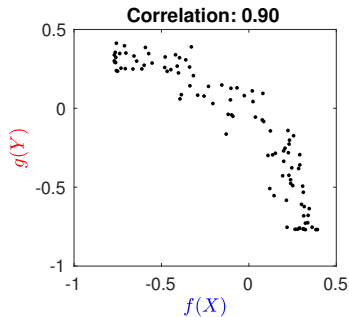
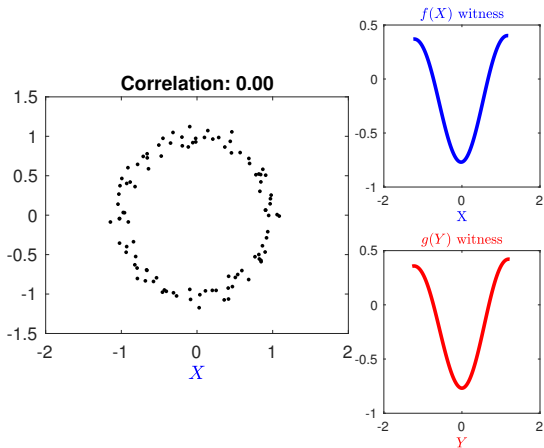
Kernel for RKHS  $\mathcal{G}$  on  $\mathcal{Y}$ :

$$l(x, x') = \langle \phi(y), \phi(y') \rangle_{\mathcal{G}}$$

# The constrained covariance

The constrained covariance is

$$\text{COCO}(P_{XY}) = \sup_{\substack{\|f\|_{\mathcal{F}} \leq 1 \\ \|g\|_{\mathcal{G}} \leq 1}} \text{cov}[f(x)g(y)]$$



## The constrained covariance

The constrained covariance is

$$\text{COCO}(P_{XY}) = \sup_{\substack{\|f\|_{\mathcal{F}} \leq 1 \\ \|g\|_{\mathcal{G}} \leq 1}} \text{cov} \left[ \left( \sum_{j=1}^{\infty} f_j \varphi_j(x) \right) \left( \sum_{j=1}^{\infty} g_j \phi_j(y) \right) \right]$$

## The constrained covariance

The constrained covariance is

$$\text{COCO}(P_{XY}) = \sup_{\substack{\|f\|_{\mathcal{F}} \leq 1 \\ \|g\|_{\mathcal{G}} \leq 1}} E_{xy} \left[ \left( \sum_{j=1}^{\infty} f_j \varphi_j(x) \right) \left( \sum_{j=1}^{\infty} g_j \phi_j(y) \right) \right]$$

**Fine print:** feature mappings  $\varphi(x)$  and  $\phi(y)$  assumed to have zero mean.

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Rewriting:

$$\begin{aligned} & E_{xy} [f(x)g(y)] \\ &= \begin{bmatrix} f_1 \\ f_2 \\ \vdots \end{bmatrix}^\top \underbrace{E_{xy} \left( \begin{bmatrix} \varphi_1(x) \\ \varphi_2(x) \\ \vdots \end{bmatrix} \begin{bmatrix} \phi_1(y) & \phi_2(y) & \dots \end{bmatrix} \right)}_{C_{\varphi(x)\phi(y)}} \begin{bmatrix} g_1 \\ g_2 \\ \vdots \end{bmatrix} \end{aligned}$$

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**COCO: max singular value of feature covariance  $C_{\varphi(x)\phi(y)}$**

## Computing COCO in practice

Given sample  $\{(x_i, y_i)\}_{i=1}^n \stackrel{\text{i.i.d.}}{\sim} P_{XY}$ , what is empirical  $\widehat{\text{COCO}}$  ?



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$\widehat{\text{COCO}}$  is largest eigenvalue  $\gamma_{\max}$  of

$$\begin{bmatrix} 0 & \frac{1}{n}KL \\ \frac{1}{n}LK & 0 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \gamma \begin{bmatrix} K & 0 \\ 0 & L \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix}.$$

$K_{ij} = k(x_i, x_j)$  and  $L_{ij} = l(y_i, y_j)$ .

**Fine print:** kernels are computed with empirically centered features  $\varphi(x) - \frac{1}{n} \sum_{i=1}^n \varphi(x_i)$  and  $\phi(y) - \frac{1}{n} \sum_{i=1}^n \phi(y_i)$ .

AG., A. Smola., O. Bousquet, R. Herbrich, A. Belitski, M. Augath, Y. Murayama, J. Pauls, B. Schoelkopf, and N. Logothetis, AISTATS'05

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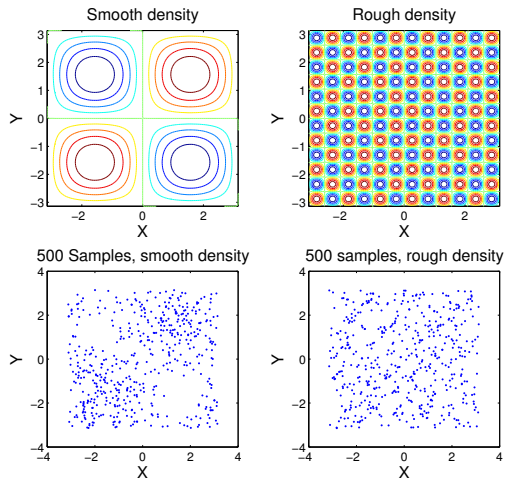
Witness functions (singular vectors):

$$f(x) \propto \sum_{i=1}^m \alpha_i k(x_i, x) \quad g(y) \propto \sum_{i=1}^n \beta_i l(y_i, y)$$

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## What is a large dependence with COCO?



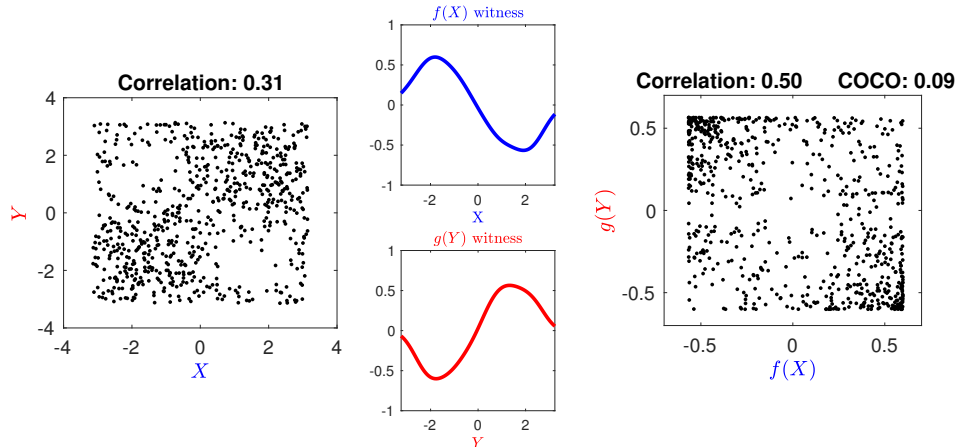
Density takes the form:

$$P_{XY} \propto 1 + \sin(\omega x) \sin(\omega y)$$

Which of these is the more "dependent"?

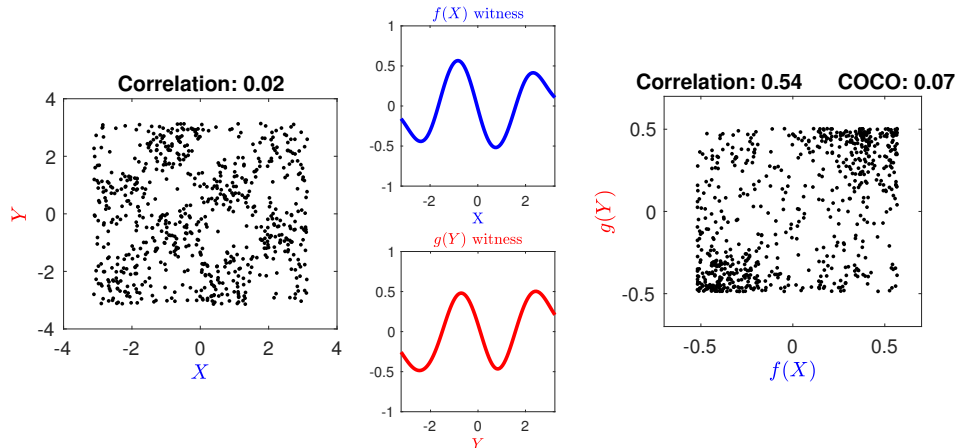
# Finding covariance with smooth transformations

Case of  $\omega = 1$ :



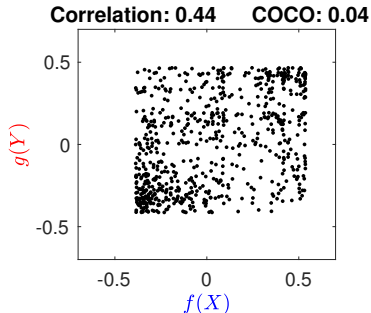
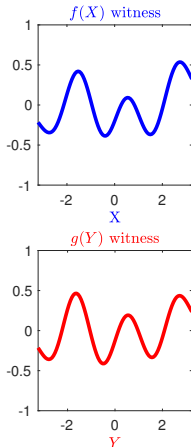
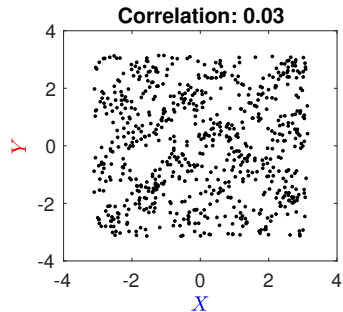
# Finding covariance with smooth transformations

Case of  $\omega = 2$ :



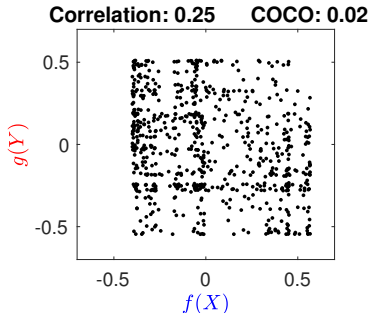
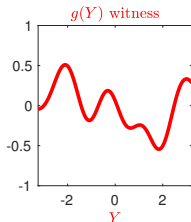
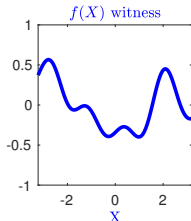
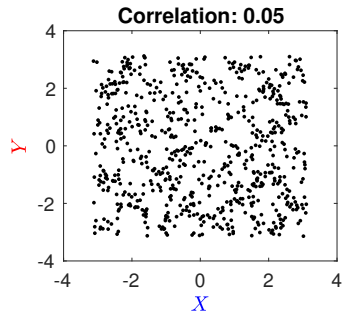
# Finding covariance with smooth transformations

Case of  $\omega = 3$ :



# Finding covariance with smooth transformations

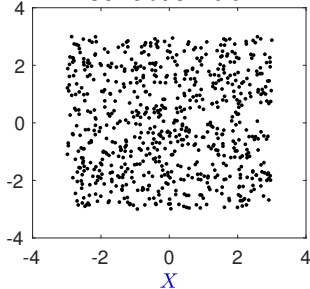
Case of  $\omega = 4$ :



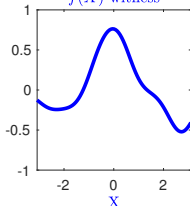
# Finding covariance with smooth transformations

Case of  $\omega = ??$ :

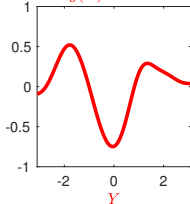
Correlation: 0.01



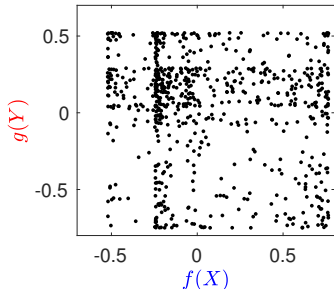
$f(X)$  witness



$g(Y)$  witness



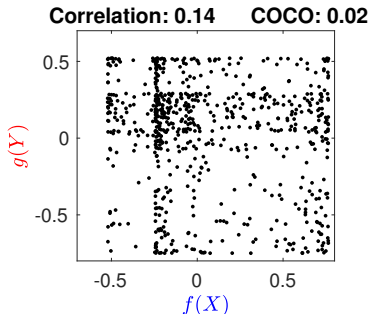
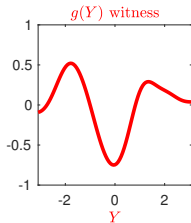
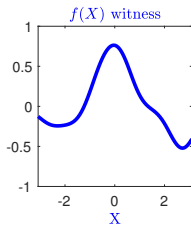
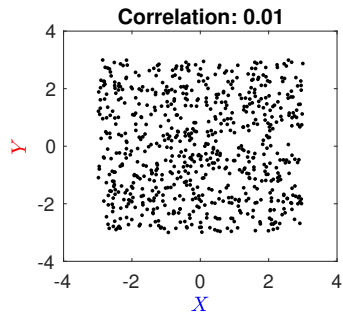
Correlation: 0.14 COCO: 0.02





# Finding covariance with smooth transformations

Case of  $\omega = 0$ : uniform noise! (shows bias)



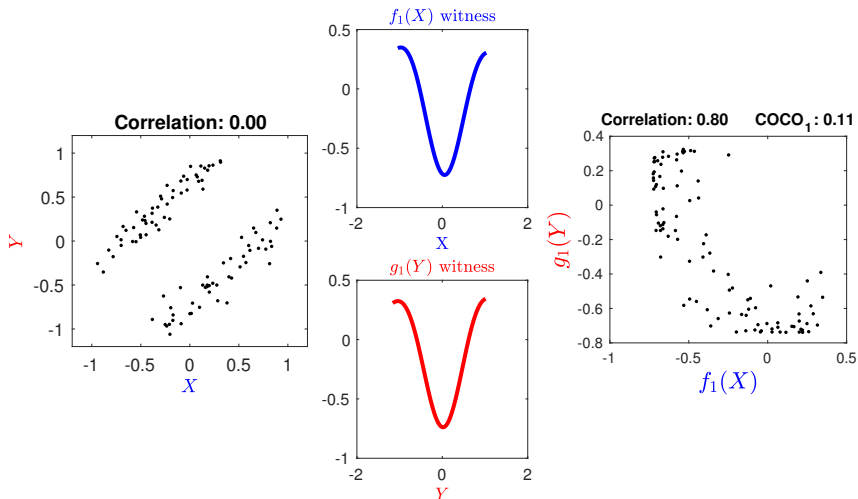
## Dependence largest when at “low” frequencies

- As dependence is encoded at **higher frequencies**, the **smooth mappings**  $f, g$  achieve lower linear dependence.
- Even for **independent variables**, COCO will not be zero at **finite sample sizes**, since some mild linear dependence will be found by  $f, g$  (**bias**)
- This **bias** will decrease with increasing sample size.

## Can we do better than COCO?

A second example with zero correlation.

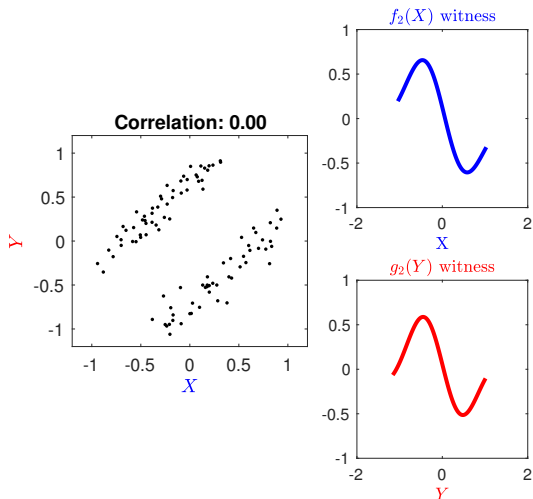
**First** singular value of feature covariance  $C_{\varphi(x)\phi(y)}$ :



## Can we do better than COCO?

A second example with zero correlation.

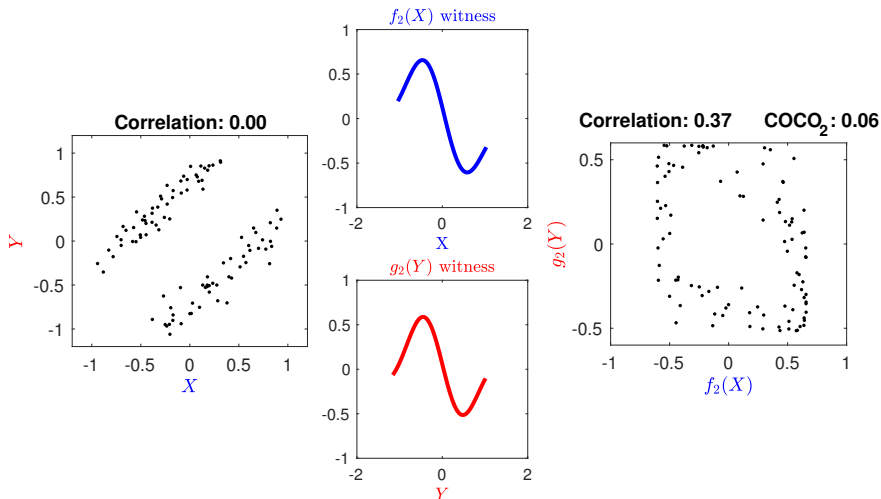
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**Second** singular value of feature covariance  $C_{\varphi(x)\phi(y)}$ :



# The Hilbert-Schmidt Independence Criterion

Writing the  $i$ th singular value of the feature covariance  $C_{\varphi(x)\phi(y)}$  as

$$\gamma_i := \text{COV}_i(P_{XY}; \mathcal{F}, \mathcal{G}),$$

define **Hilbert-Schmidt Independence Criterion (HSIC)**

$$\text{HSIC}^2(P_{XY}; \mathcal{F}, \mathcal{G}) = \sum_{i=1}^{\infty} \gamma_i^2.$$

AG, O. Bousquet, A. Smola, and B. Schoelkopf, ALT2005; AG, K. Fukumizu, C.H. Teo, L. Song, B. Schoelkopf, and A. Smola, NIPS 2007,.

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**HSIC is MMD with product kernel!**

$$\text{HSIC}^2(P_{XY}; \mathcal{F}, \mathcal{G}) = \text{MMD}^2(P_{XY}, P_X P_Y; \mathcal{H}_{\kappa})$$

where  $\kappa((x, y), (x', y')) = k(x, x')l(y, y')$ .

## Asymptotics of HSIC under independence

- Given sample  $\{(x_i, y_i)\}_{i=1}^n \stackrel{\text{i.i.d.}}{\sim} P_{XY}$ , what is empirical  $\widehat{HSIC}$ ?
- Empirical HSIC (biased)

$$\widehat{HSIC} = \frac{1}{n^2} \text{trace}(KL)$$

$K_{ij} = k(x_i, x_j)$  and  $L_{ij} = l(y_i, y_j)$  ( $K$  and  $L$  computed with empirically centered features)

- Statistical testing: given  $P_{XY} = P_X P_Y$ , what is the threshold  $c_\alpha$  such that  $P(\widehat{HSIC} > c_\alpha) < \alpha$  for small  $\alpha$ ?
- Asymptotics of  $\widehat{HSIC}$  when  $P_{XY} = P_X P_Y$ :

$$n\widehat{HSIC} \xrightarrow{D} \sum_{l=1}^{\infty} \lambda_l z_l^2, \quad z_l \sim \mathcal{N}(0, 1) \text{ i.i.d.}$$

where  $\lambda_l \psi_l(z_j) = \int h_{ijqr} \psi_l(z_i) dF_{i,q,r}$ ,  $h_{ijqr} = \frac{1}{4!} \sum_{(t,u,v,w)}^{(i,j,q,r)} k_{tu} l_{tv} + k_{tu} l_{vw} - 2k_{tu} l_{tv}$



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- Given  $P_{XY} = P_X P_Y$ , what is the threshold  $c_\alpha$  such that  $P(\widehat{HSIC} > c_\alpha) < \alpha$  for small  $\alpha$  (prob. of false positive)?

- Original time series:

$X_1 X_2 X_3 X_4 X_5 X_6 X_7 X_8 X_9 X_{10}$   
 $Y_1 Y_2 Y_3 Y_4 Y_5 Y_6 Y_7 Y_8 Y_9 Y_{10}$

- Permutation:

$X_1 X_2 X_3 X_4 X_5 X_6 X_7 X_8 X_9 X_{10}$   
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- Null distribution via permutation

- Compute HSIC for  $\{x_i, y_{\pi(i)}\}_{i=1}^n$  for random permutation  $\pi$  of indices  $\{1, \dots, n\}$ . This gives HSIC for independent variables.
- Repeat for many different permutations, get empirical CDF
- Threshold  $c_\alpha$  is  $1 - \alpha$  quantile of empirical CDF

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- **Permutation:**

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  - Repeat for many different permutations, get empirical CDF
  - Threshold  $c_\alpha$  is  $1 - \alpha$  quantile of empirical CDF

# Application: dependence detection across languages

Testing task: detect dependence between English and French text

X	Y
Honourable senators, I have a question for the Leader of the Government in the Senate	Honorables sénateurs, ma question s'adresse au leader du gouvernement au Sénat
No doubt there is great pressure on provincial and municipal governments	Les ordres de gouvernements provinciaux et municipaux subissent de fortes pressions
In fact, we have increased federal investments for early childhood development.	Au contraire, nous avons augmenté le financement fédéral pour le développement des jeunes
• • •	• • •

# Application: dependence detection across languages

Testing task: detect dependence between **English** and **French** text

$k$ -spectrum kernel,  $k = 10$ , sample size  $n = 10$

X

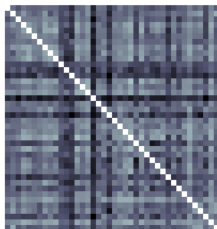
Y

Honourable senators, I  
have a question for the  
Leader of the Government  
in the Senate

No doubt there is great  
pressure on provincial and  
municipal governments

In fact, we have increased  
federal investments for  
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development.

•  
•  
•



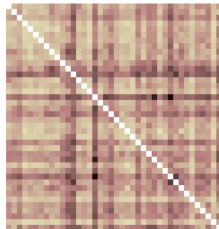
K

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•  
•  
•



L

$$\widehat{HSIC} = \frac{1}{n^2} \text{trace}(KL)$$

( $K$  and  $L$  column centered)



## Application: Dependence detection across languages

Results (for  $\alpha = 0.05$ )

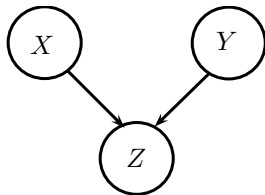
- k-spectrum kernel: average Type II error 0
- Bag of words kernel: average Type II error 0.18

Settings: Five line extracts, averaged over 300 repetitions, for “Agriculture” transcripts. Similar results for Fisheries and Immigration transcripts.

# Testing higher order interactions

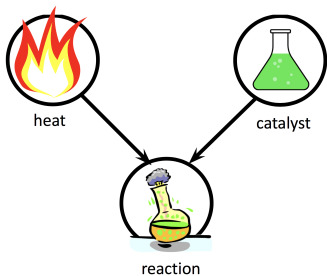
## Detecting higher order interaction

How to detect V-structures with pairwise weak individual dependence?



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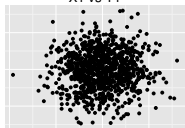


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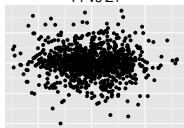
How to detect V-structures with pairwise weak individual dependence?

$$X \perp\!\!\!\perp Y, Y \perp\!\!\!\perp Z, X \perp\!\!\!\perp Z$$

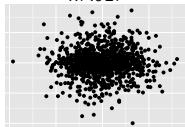
X1 vs Y1



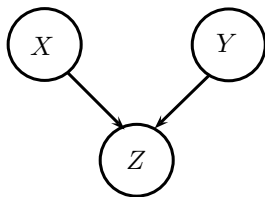
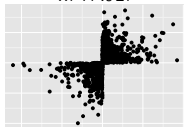
Y1 vs Z1



X1 vs Z1



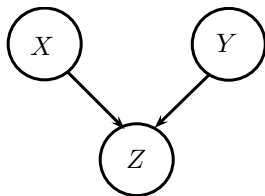
X1\*Y1 vs Z1



- $X, Y \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1)$
- $Z | X, Y \sim \text{sign}(XY) \text{Exp}\left(\frac{1}{\sqrt{2}}\right)$

**Fine print:** Faithfulness violated here!

## V-structure discovery



Assume  $X \perp\!\!\!\perp Y$  has been established.

V-structure can then be detected by:

- Consistent CI test:  $H_0 : X \perp\!\!\!\perp Y | Z$  [Fukumizu et al. 2008, Zhang et al. 2011]
- Factorisation test:  $H_0 : (X, Y) \perp\!\!\!\perp Z \vee (X, Z) \perp\!\!\!\perp Y \vee (Y, Z) \perp\!\!\!\perp X$   
(multiple standard two-variable tests)

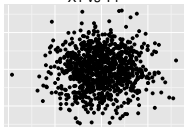
How well do these work?

## Detecting higher order interaction

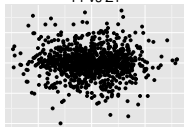
Generalise earlier example to  $p$  dimensions

$$X \perp\!\!\!\perp Y, Y \perp\!\!\!\perp Z, X \perp\!\!\!\perp Z$$

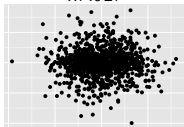
X1 vs Y1



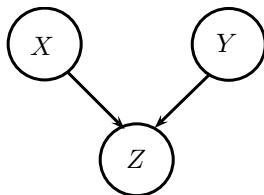
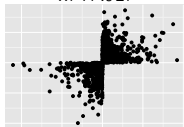
Y1 vs Z1



X1 vs Z1



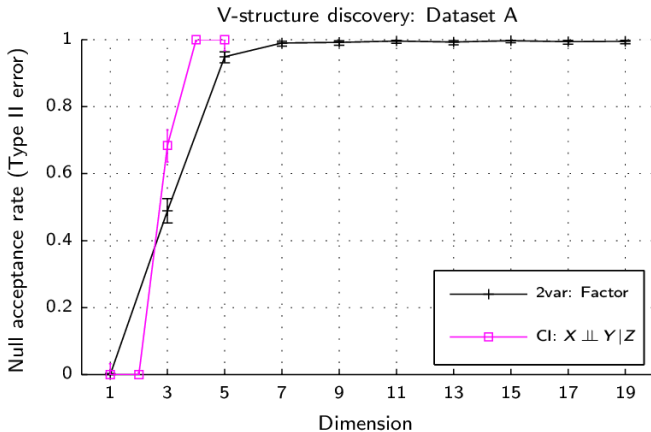
X1\*Y1 vs Z1



- $X, Y \stackrel{i.i.d.}{\sim} \mathcal{N}(0, 1)$
- $Z | X, Y \sim \text{sign}(XY) \text{Exp}(\frac{1}{\sqrt{2}})$
- $X_{2:p}, Y_{2:p}, Z_{2:p} \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \mathbf{I}_{p-1})$

**Fine print:** Faithfulness violated here!

## V-structure discovery



CI test for  $X \perp Y | Z$  from [Zhang et al. \(2011\)](#), and a factorisation test,  $n = 500$



## Lancaster interaction measure

Lancaster interaction measure of  $(X_1, \dots, X_D) \sim P$  is a signed measure  $\Delta P$  that **vanishes** whenever  $P$  can be factorised non-trivially.

$$D = 2: \quad \Delta_L P = P_{XY} - P_X P_Y$$

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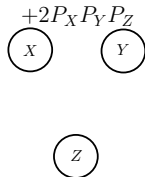
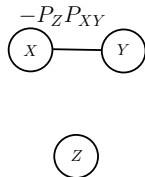
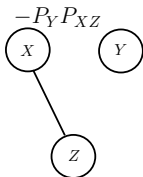
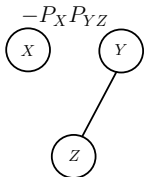
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$$\Delta_L P =$$

$$P_{XYZ}$$

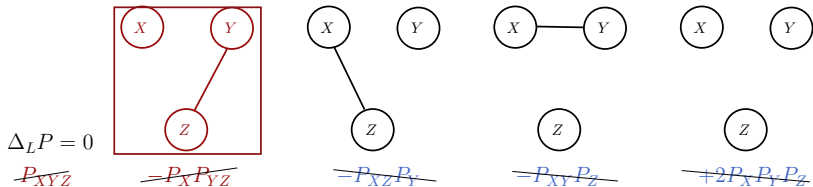


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Case of  $P_X \perp\!\!\!\perp P_{YZ}$

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$$(X, Y) \perp\!\!\!\perp Z \vee (X, Z) \perp\!\!\!\perp Y \vee (Y, Z) \perp\!\!\!\perp X \Rightarrow \Delta_L P = 0.$$

...so what might be missed?

## Lancaster interaction measure

Lancaster interaction measure of  $(X_1, \dots, X_D) \sim P$  is a signed measure  $\Delta P$  that **vanishes** whenever  $P$  can be factorised non-trivially.

$$D = 2: \quad \Delta_L P = P_{XY} - P_X P_Y$$

$$D = 3: \quad \Delta_L P = P_{XYZ} - P_X P_{YZ} - P_Y P_{XZ} - P_Z P_{XY} + 2P_X P_Y P_Z$$

$$\Delta_L P = 0 \not\Rightarrow (X, Y) \perp\!\!\!\perp Z \vee (X, Z) \perp\!\!\!\perp Y \vee (Y, Z) \perp\!\!\!\perp X$$

Example:

$P(0,0,0) = 0.2$	$P(0,0,1) = 0.1$	$P(1,0,0) = 0.1$	$P(1,0,1) = 0.1$
$P(0,1,0) = 0.1$	$P(0,1,1) = 0.1$	$P(1,1,0) = 0.1$	$P(1,1,1) = 0.2$

## A kernel test statistic using Lancaster Measure

Construct a test by estimating  $\|\mu_\kappa(\Delta_L P)\|_{\mathcal{H}_\kappa}^2$ , where  $\kappa = k \otimes l \otimes m$ :

$$\begin{aligned} & \|\mu_\kappa(P_{XYZ} - P_{XY}P_Z - \dots)\|_{\mathcal{H}_\kappa}^2 = \\ & \langle \mu_\kappa P_{XYZ}, \mu_\kappa P_{XYZ} \rangle_{\mathcal{H}_\kappa} - 2 \langle \mu_\kappa P_{XYZ}, \mu_\kappa P_{XY}P_Z \rangle_{\mathcal{H}_\kappa} \dots \end{aligned}$$

## A kernel test statistic using Lancaster Measure

$\nu \setminus \nu'$	$P_{XYZ}$	$P_{XY}P_Z$	$P_{XZ}P_Y$	$P_{YZ}P_X$	$P_X P_Y P_Z$
$P_{XYZ}$	$(K \circ L \circ M)_{++}$	$((K \circ L)M)_{++}$	$((K \circ M)L)_{++}$	$((M \circ L)K)_{++}$	$\text{tr}(K_{++} \circ L_{++} \circ M_{++})$
$P_{XY}P_Z$		$(K \circ L)_{++} M_{++}$	$(MKL)_{++}$	$(KLM)_{++}$	$(KL)_{++} M_{++}$
$P_{XZ}P_Y$			$(K \circ M)_{++} L_{++}$	$(KML)_{++}$	$(KM)_{++} L_{++}$
$P_{YZ}P_X$				$(L \circ M)_{++} K_{++}$	$(LM)_{++} K_{++}$
$P_X P_Y P_Z$					$K_{++} L_{++} M_{++}$

Table:  $V$ -statistic estimators of  $\langle \mu_\kappa \nu, \mu_\kappa \nu' \rangle_{\mathcal{H}_\kappa}$  (without terms  $P_X P_Y P_Z$ ).  $H$  is centering matrix  $I - n^{-1}$

**Lancaster interaction statistic:** D. Sejdinovic, AG, W. Bergsma, NIPS13

$$\|\mu_\kappa(\Delta_L P)\|_{\mathcal{H}_\kappa}^2 = \frac{1}{n^2} \boxed{(HKH \circ H L H \circ H M H)_{++}}.$$



## A kernel test statistic using Lancaster Measure

$\nu \setminus \nu'$	$P_{XYZ}$	$P_{XY}P_Z$	$P_{XZ}P_Y$	$P_{YZ}P_X$	$P_X P_Y P_Z$
$P_{XYZ}$	$(K \circ L \circ M)_{++}$	$((K \circ L)M)_{++}$	$((K \circ M)L)_{++}$	$((M \circ L)K)_{++}$	$\text{tr}(K_{++} \circ L_{++} \circ M_{++})$
$P_{XY}P_Z$		$(K \circ L)_{++} M_{++}$	$(MKL)_{++}$	$(KLM)_{++}$	$(KL)_{++} M_{++}$
$P_{XZ}P_Y$			$(K \circ M)_{++} L_{++}$	$(KML)_{++}$	$(KM)_{++} L_{++}$
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$P_X P_Y P_Z$					$K_{++} L_{++} M_{++}$

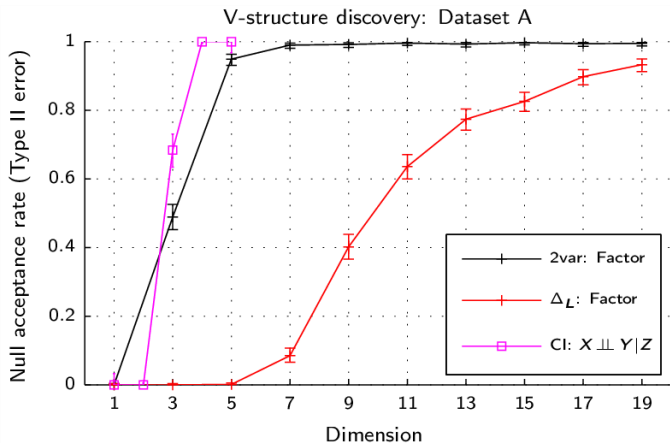
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$$\|\mu_\kappa(\Delta_L P)\|_{\mathcal{H}_\kappa}^2 = \frac{1}{n^2} \boxed{(H \mathbf{K} H \circ H \mathbf{L} H \circ H \mathbf{M} H)_{++}}.$$

Empirical joint central moment in the feature space

## V-structure discovery



Lancaster test, CI test for  $X \perp\!\!\!\perp Y|Z$  from Zhang et al. (2011), and a factorisation test,  $n = 500$

## Interaction for $D \geq 4$

- Interaction measure valid for all  $D$ :

(Streitberg, 1990)

$$\Delta_S P = \sum_{\pi} (-1)^{|\pi|-1} (|\pi| - 1)! J_{\pi} P$$

- For a partition  $\pi$ ,  $J_{\pi}$  associates to the joint the corresponding factorisation, e.g.,  $J_{13|2|4} P = P_{X_1 X_3} P_{X_2} P_{X_4}$ .

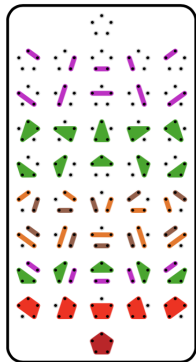
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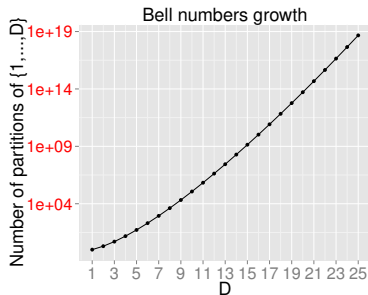
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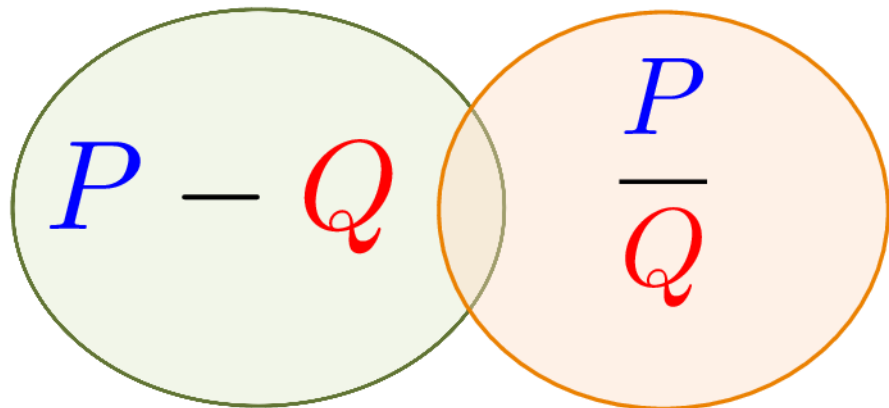


## Part 4: Advanced topics

## Advanced topics

- testing on time series
- testing for conditional dependence
- regression and conditional mean embedding

## Measures of divergence





## Measures of divergence

Integral prob. metrics

$$D_{\mathcal{H}}(P, Q) \\ = \sup_{g \in \mathcal{H}} |\mathbf{E}_{X \sim P} g(X) - \mathbf{E}_{Y \sim Q} g(Y)|$$

$\mathcal{F}$ -divergences

$$D_f(P, Q) \\ = \int_{\mathcal{X}} q(x) f\left(\frac{p(x)}{q(x)}\right) dx$$

## Measures of divergence

Integral prob. metrics

wasserstein

$$D_{\mathcal{H}}(P, Q) \\ = \sup_{g \in \mathcal{H}} |\mathbf{E}_{X \sim P} g(X) - \mathbf{E}_{Y \sim Q} g(Y)|$$

MMD

$\mathcal{F}$ -divergences

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## Measures of divergence

Integral prob. metrics

wasserstein

$$D_{\mathcal{H}}(P, Q) = \sup_{g \in \mathcal{H}} |\mathbf{E}_{X \sim P} g(X) - \mathbf{E}_{Y \sim Q} g(Y)|$$

MMD

f-divergences

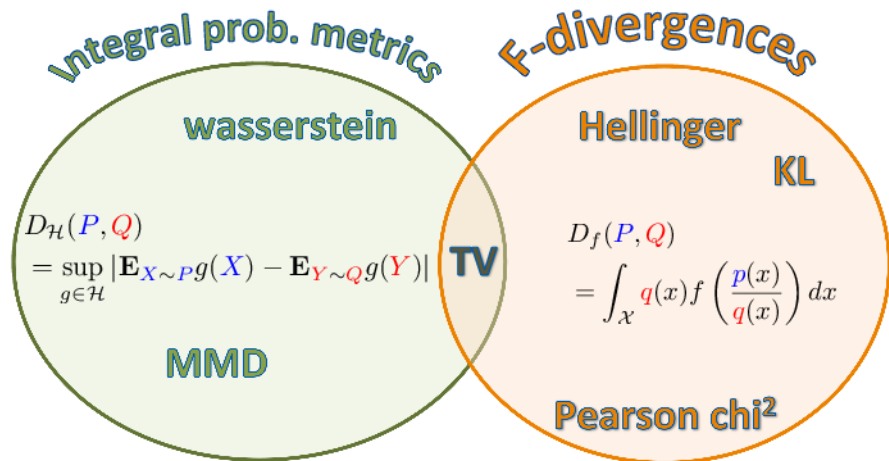
Hellinger

KL

$$D_f(P, Q) = \int_{\mathcal{X}} q(x) f\left(\frac{p(x)}{q(x)}\right) dx$$

Pearson  $\chi^2$

## Measures of divergence



Sriperumbudur, Fukumizu, G, Schoelkopf, Lanckriet (2012)

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Questions?