## The Shattered Gradients Problem: If resnets are the answer, then what is the question?

Balduzzi et al., ICML 2017

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#### Background

training deep networks isn't easy

- problems can be mitigated by:
  - unsupervised pre-training
  - correct initialization of weights
  - batch normalization
  - **skip connections** i.e., activation functions of the form:

$$f(x) = \underbrace{\rho(x)}_{\text{non linearity}} + x$$

SOTA results achieved by architectures which include skip connections: this paper tries of understand why

#### Background

some examples of *skip connections*:

res-nets [He et al.,, 2015]



denseNets [Huang et al.,, 2017]



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also highway nets [Srivastava et al., 2015)], etc

## Background

# current ideas/intuitions about why *skip connections* are so effective:

Raiko et al., [2012] show that such maps help to make Fisher info matrix more diagonal

- improves gradient flow (due to linear nature)
- (this paper) avoids shattered gradients

#### shattered gradients

the gradients in deep networks behave like white noise. Bad news for first-order algorithms that assume that gradients at nearby points are similar!

#### Shattered gradients

they focus on the following class of networks:

$$f_{w,b}(x) = w^T \operatorname{ReLU}(x \cdot v - b)$$
  
=  $w^T \max(0, x \cdot v - b)$ 

where  $v = (1, \dots, 1)$  and initialize  $w, b \sim \mathcal{N}(0, \sigma^2)$ 

• study  $\frac{\partial f_w}{\partial x}$  for different values of x

not realistic, but provide a sandbox where gradients can be isolated and studied.

all results studied at initialization (i.e., no training)

#### Shattered gradients



(a) 1-layer feedforward. (b) 24-layer feedforward.

(c) 50-layer resnet.

 $\frac{\partial f_w}{\partial x}$  behaving like white noise makes neuron's effect on output very unstable

#### Shattered gradients



(c) Resnet with batch normalization.

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#### Batch norm without skip connections makes gradients less Lipschitz

#### Theory

• define 
$$\nabla_i = \frac{\partial f_w}{\partial n} (x^{(i)})$$
 and study  $\mathcal{R}(i,j) = \frac{\mathbb{E}[\nabla_i \nabla_j]}{\sqrt{\mathbb{E}[\nabla_i^2] \cdot \mathbb{E}[\nabla_j^2]}}$ 

recall  $x^{(i)} \in \mathbb{R}$  is the univariate input

• **Theorem 1**: in feed-forward networks with weights initialized with variance  $\sigma^2 = \frac{2}{N}$  (e.g., Xavier) then:

$$\mathcal{R}^{fnn}(i,j) = \frac{1}{2^L}$$

• **Theorem 2**: in a network with skip connections with batch norm and weights initialized with variance  $\sigma^2 = \frac{2}{N}$  then:

$$\mathcal{R}^{skip}(i,j) \sim \frac{1}{\sqrt{L}}$$

## Empirical example: CIFAR-10

- covariance matrices for resnet (with skip connections) and feedforward network
- training examples ordered based on k-means clustering



(a) Depth = 2 (b) Depth = 50

## Looks-linear (LL) initialization

propose to train networks with the activation function:

$$f(x) = W_1^T \operatorname{ReLU}(x) + W_2^T \operatorname{ReLU}(-x)$$

and initialize with  $W_1 = W_2$  so that f(x) = x

 claim LL initialization avoids shattering



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