# Exploring patterns enriched in a dataset with contrastive principal component analysis

Abubakar Abid, Martin J. Zhang, Vivek K. Bagaria & James Zou

Nature Communications, 2018

18th Feb, 2019

# Background

- Dimensionality reduction is a fundamental tool for exploratory data analysis and visualization.
- While there are many dimensionality reduction methods these methods typically assume a single dataset.
- However, it is often the case we have multiple datasets and wish to find projections which exhibit interesting differences between the datasets.

# Background

- Dimensionality reduction is a fundamental tool for exploratory data analysis and visualization.
- While there are many dimensionality reduction methods these methods typically assume a single dataset.
- However, it is often the case we have multiple datasets and wish to find projections which exhibit interesting differences between the datasets.



## Contrastive PCA

- ▶ We observe target data  $\{\mathbf{x}_i \in \mathbb{R}^d\}$  and background data  $\{\mathbf{y}_i \in \mathbb{R}^d\}$  with sample covariances  $C_X$  and  $C_Y$ .
- For any unit vector **v**, define:

$$\lambda_X(\mathbf{v}) = \mathbf{v}^T C_X \mathbf{v}$$
$$\lambda_Y(\mathbf{v}) = \mathbf{v}^T C_Y \mathbf{v}$$

Standard PCA simply maximizes λ<sub>X</sub>(v) ⇒ problematic if leading eigenvectors are shared in C<sub>X</sub> and C<sub>Y</sub>.

## Contrastive PCA

- ▶ We observe target data  $\{\mathbf{x}_i \in \mathbb{R}^d\}$  and background data  $\{\mathbf{y}_i \in \mathbb{R}^d\}$  with sample covariances  $C_X$  and  $C_Y$ .
- For any unit vector **v**, define:

$$\lambda_X(\mathbf{v}) = \mathbf{v}^T C_X \mathbf{v}$$
$$\lambda_Y(\mathbf{v}) = \mathbf{v}^T C_Y \mathbf{v}$$

- Standard PCA simply maximizes λ<sub>X</sub>(v) ⇒ problematic if leading eigenvectors are shared in C<sub>X</sub> and C<sub>Y</sub>.
- For a fixed α ∈ ℝ<sub>+</sub>, contrastive PCA solves the following optimization:

$$\mathbf{v}^* = \underset{\mathbf{v}}{\operatorname{argmax}} \left\{ \lambda_X(\mathbf{v}) - \alpha \lambda_Y(\mathbf{v}) \right\}$$
$$= \underset{\mathbf{v}}{\operatorname{argmax}} \left\{ \mathbf{v}^T (C_X - \alpha C_Y) \mathbf{v} \right\}$$

#### Special case: simultaneously diagonalizable system

• We assume  $C_X$  and  $C_Y$  have shared eigen-structure such that:

$$C_X = Q \Lambda_X Q^T$$
 and  $C_Y = Q \Lambda_Y Q^T$ 

for  $\Lambda_X = \text{diag}(\lambda_{X,1}, \dots, \lambda_{X,d})$  and where  $\mathbf{q}_1, \dots, \mathbf{q}_d$  are eigenvectors.

► Then we can write any unit vector in terms of the basis defined by Q as:  $\mathbf{v} = \sum_{i=1}^{d} \sqrt{c_i} \mathbf{q}_i$  where  $\sum_{i=1}^{d} c_i = 1$ .

### Special case: simultaneously diagonalizable system

• We assume  $C_X$  and  $C_Y$  have shared eigen-structure such that:

$$C_X = Q\Lambda_X Q^T$$
 and  $C_Y = Q\Lambda_Y Q^T$ 

for  $\Lambda_X = \text{diag}(\lambda_{X,1}, \dots, \lambda_{X,d})$  and where  $\mathbf{q}_1, \dots, \mathbf{q}_d$  are eigenvectors.

► Then we can write any unit vector in terms of the basis defined by Q as:  $\mathbf{v} = \sum_{i=1}^{d} \sqrt{c_i} \mathbf{q}_i$  where  $\sum_{i=1}^{d} c_i = 1$ .

- Thus  $\lambda_X(\mathbf{v}) = \sum_{i=1}^d c_i \lambda_{X,i}$  and similarly for  $\lambda_Y(\mathbf{v})$ .
- v<sup>\*</sup> will be along bottom right of figure ⇒ convex hull of eigenvalues, will be piecewise linear



### Final example

