

# K2-ABC: Approximate Bayesian Computation with Kernel Embeddings

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## Approximate Bayesian Computation (ABC)

- Given: prior  $p(\boldsymbol{\theta})$ , **intractable** likelihood  $p(\mathbf{Y}|\boldsymbol{\theta})$ , observations  $\mathbf{Y}$ .
- Goal: Sample from  $p(\boldsymbol{\theta}|\mathbf{Y}) \propto p(\boldsymbol{\theta})p(\mathbf{Y}|\boldsymbol{\theta})$ .
- Problem: Cannot evaluate  $p(\mathbf{Y}|\boldsymbol{\theta})$ . But, can sample  $\mathbf{X} \sim p(\cdot|\boldsymbol{\theta})$ .

Example: a complicated dynamical system for blow fly population

$$N_{t+1} = PN_{t-\tau} \exp\left(-\frac{N_{t-\tau}}{N_0}\right) e_t + N_t \exp(-\delta \epsilon_t)$$

where  $e_t \sim \text{Gamma}\left(\frac{1}{\sigma_p^2}, \sigma_P^2\right)$  and  $\epsilon_t \sim \text{Gamma}\left(\frac{1}{\sigma_d^2}, \sigma_d^2\right)$ .

- $\boldsymbol{\theta} := \{P, N_0, \sigma_d, \sigma_p, \tau, \delta\}$
- Given  $\mathbf{Y} = \{N_1, \dots, N_T\}$ , want to sample from  $p(\boldsymbol{\theta}|\mathbf{Y})$ .

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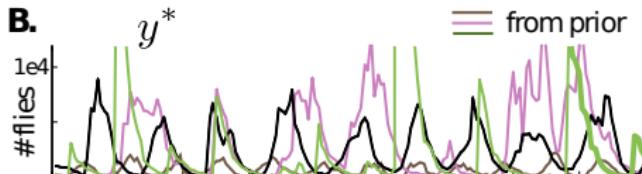
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## ABC Likelihood $p_\epsilon(\mathbf{Y}|\boldsymbol{\theta})$

- Observe a dataset  $\mathbf{Y}$ ,

$$p(\mathbf{Y}|\boldsymbol{\theta}) = \int p(\mathbf{X}|\boldsymbol{\theta})\delta(\mathbf{X} - \mathbf{Y}) d\mathbf{X}$$

$$\begin{aligned} (\text{ABC likelihood}) &\approx \int p(\mathbf{X}|\boldsymbol{\theta})\kappa_\epsilon(\mathbf{X}, \mathbf{Y}) d\mathbf{X} := p_\epsilon(\mathbf{Y}|\boldsymbol{\theta}) \\ &\approx \kappa_\epsilon(\mathbf{X}^\boldsymbol{\theta}, \mathbf{Y}) \text{ where } \mathbf{X}^\boldsymbol{\theta} \sim p(\cdot|\boldsymbol{\theta}), \end{aligned}$$

where  $\kappa_\epsilon(\mathbf{X}, \mathbf{Y})$  defines similarity between  $\mathbf{X}$  and  $\mathbf{Y}$ .

- ABC algorithms sample from  $p_\epsilon(\boldsymbol{\theta}|\mathbf{Y}) \propto p(\boldsymbol{\theta})p_\epsilon(\mathbf{Y}|\boldsymbol{\theta})$
- Rejection ABC sets

$$\kappa_\epsilon(\mathbf{X}, \mathbf{Y}) := \mathbf{1}[\|s(\mathbf{X}) - s(\mathbf{Y})\|_2 < \epsilon],$$

- $s$ : function to compute summary statistics
- $\mathbf{1}[\cdot] \in \{0, 1\}$ : indicator function

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## Summary Statistics $s(\cdot)$

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- More statistics give high sufficiency.
- But, higher rejection rate.

- Insufficient will  $s(\cdot)$  lead to an incorrect posterior.

### Contribution:

- Use a kernel-based distance to define  $\kappa_\epsilon$ . No need to design  $s(\cdot)$ .

Rejection ABC:

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K2-ABC (proposed):

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## Maximum Mean Discrepancy (MMD) [Gretton et al., 2006]

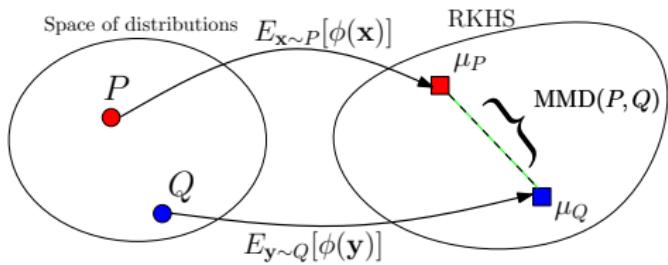
$$\widehat{\text{MMD}}^2(\mathbf{X}, \mathbf{Y}) = \left\| \overbrace{\frac{1}{n} \sum_{i=1}^n \phi(\mathbf{x}_i)}^{\hat{\mu}_P} - \overbrace{\frac{1}{n} \sum_{j=1}^n \phi(\mathbf{y}_j)}^{\hat{\mu}_Q} \right\|_{\text{RKHS}}^2$$

$$\begin{aligned} & (\text{unbiased}) \quad \frac{1}{n(n-1)} \sum_{i \neq j} k(\mathbf{x}_i, \mathbf{x}_j) + \frac{1}{n(n-1)} \sum_{i \neq j} k(\mathbf{y}_i, \mathbf{y}_j) - \frac{2}{n^2} \sum_{i,j=1}^n k(\mathbf{x}_i, \mathbf{y}_j) \end{aligned}$$

- If kernel  $k$  is characteristic (e.g., Gaussian kernel), MMD defines a distance i.e.,

$$\text{MMD}(P, Q) = 0 \iff P = Q.$$

- $k(\mathbf{x}, \mathbf{y}) = \langle \phi(\mathbf{x}), \phi(\mathbf{y}) \rangle_{\text{RKHS}}$
- Intuitively,  $\mu_P$  contains all moments of  $P$ .



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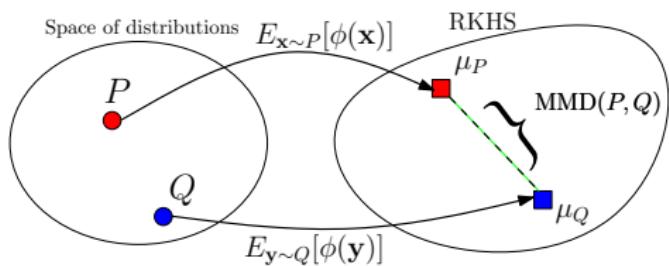
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## K2-ABC (Proposed Method)

- Recall ABC likelihood:  $p_\epsilon(\mathbf{Y}|\boldsymbol{\theta}) := \int p(\mathbf{X}|\boldsymbol{\theta})\kappa_\epsilon(\mathbf{X}, \mathbf{Y}) d\mathbf{X}$ .
- Use  $\kappa_\epsilon(\mathbf{X}, \mathbf{Y}) = \exp\left(-\frac{\widehat{\text{MMD}}^2(\mathbf{X}, \mathbf{Y})}{\epsilon}\right)$ . No rejection.

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1: for  $i = 1, \dots, M$  do
2:   Sample  $\boldsymbol{\theta}_i \sim p(\boldsymbol{\theta})$ 
3:   Sample pseudo dataset  $\mathbf{X}_i \sim p(\cdot | \boldsymbol{\theta}_i)$ 
4:    $\tilde{w}_i = \kappa_\epsilon(\mathbf{X}_i, \mathbf{Y}) = \exp\left(-\frac{\widehat{\text{MMD}}^2(\mathbf{X}_i, \mathbf{Y})}{\epsilon}\right)$ 
5: end for
6:  $w_i = \tilde{w}_i / \sum_{j=1}^M \tilde{w}_j$  for  $i = 1, \dots, M$ 
7: return  $\{\boldsymbol{\theta}_i\}_{i=1}^M$  with weights  $\{w_i\}_{i=1}^M$ 
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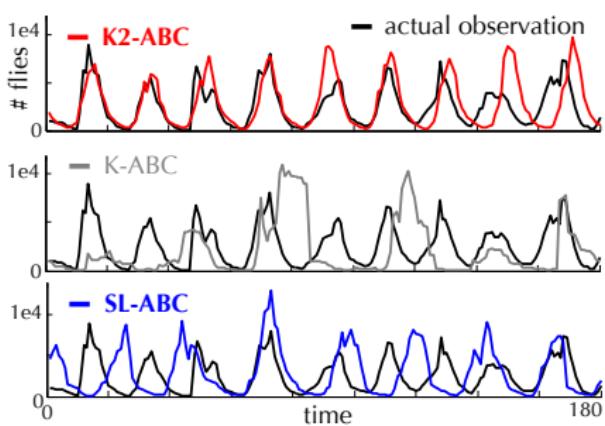
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# Blow Fly Population Modelling

Number of blow flies over time

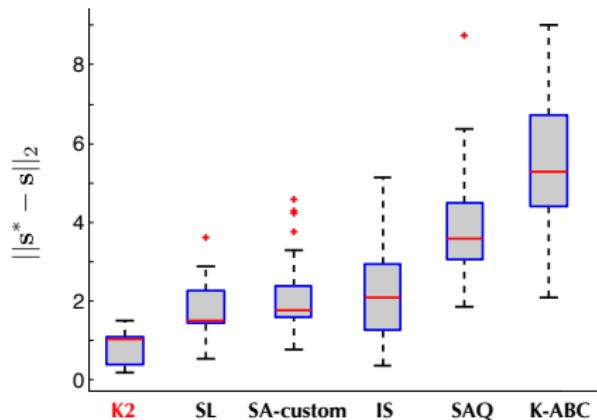
$$N_{t+1} = PN_{t-\tau} \exp\left(-\frac{N_{t-\tau}}{N_0}\right) e_t + N_t \exp(-\delta \epsilon_t)$$

- $e_t \sim \text{Gam}\left(\frac{1}{\sigma_p^2}, \sigma_p^2\right)$  and  $\epsilon_t \sim \text{Gam}\left(\frac{1}{\sigma_d^2}, \sigma_d^2\right)$ .
- Want  $\theta := \{P, N_0, \sigma_d, \sigma_p, \tau, \delta\}$ .



- $\leftarrow$  Simulated trajectories with inferred posterior mean of  $\theta$ 
  - Observed sample of size 180.
  - Other methods use handcrafted 10-dim. summary statistics.
- $s(\mathbf{X}) \in \mathbb{R}^{10}$  are as in [Meeds and Welling, 2014]
  - quantiles of the marginal distribution
  - quantiles of first-order differences
  - maximal peaks

## Errors on Summary Statistics



- $\tilde{\theta} :=$  posterior mean.
- Simulate  $\mathbf{X} \sim p(\cdot | \tilde{\theta})$  100 times.
- $s = s(\mathbf{X})$  and  $s^* = s(\mathbf{Y})$ .

- $\tilde{\theta}$  inferred by K2-ABC gives lowest error on  $s$ .
- Recall that K2-ABC does not use  $s$ , unlike others.

K2-ABC can infer the generative parameters without the need of summary statistics.

# Linear-Time K2-ABC

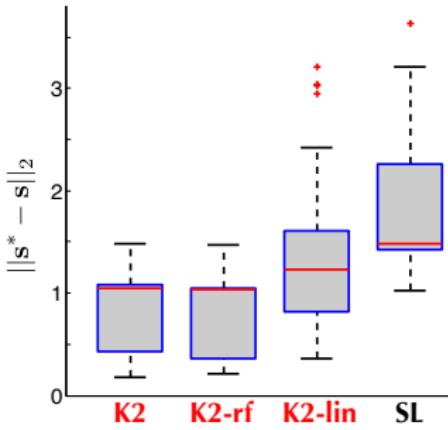
- $\widehat{\text{MMD}}^2(\mathbf{X}, \mathbf{Y})$  costs  $O(n^2)$  where  $n = \text{sample size}$ .

- 1 Linear-time unbiased estimator. Costs  $O(n)$ .

$$\widehat{\text{MMD}}_{\text{lin}}^2(\mathbf{X}, \mathbf{Y}) = \frac{1}{n-1} \sum_{i=1}^{n-1} k(\mathbf{x}_i, \mathbf{x}_{i+1}) + \frac{1}{n-1} \sum_{i=1}^{n-1} k(\mathbf{y}_i, \mathbf{y}_{i+1}) - \frac{2}{n} \sum_{i=1}^n k(\mathbf{x}_i, \mathbf{y}_i)$$

- 2 Random Fourier features  $\hat{\phi}(\mathbf{x}) \in \mathbb{R}^D$  such that  $k(\mathbf{x}, \mathbf{y}) \approx \hat{\phi}(\mathbf{x})^\top \hat{\phi}(\mathbf{y})$ . Costs  $O(Dn)$ . We set  $D = 50$ .

$$\begin{aligned} & \widehat{\text{MMD}}_{\text{rf}}^2(\mathbf{X}, \mathbf{Y}) \\ &= \left\| \frac{1}{n} \sum_{i=1}^n \hat{\phi}(\mathbf{x}_i) - \frac{1}{n} \sum_{j=1}^n \hat{\phi}(\mathbf{y}_j) \right\|_2^2 \end{aligned}$$



## Summary

ABC problem:

- Goal: Sample from  $p(\boldsymbol{\theta}|\mathbf{Y})$  where the likelihood is intractable.
- Can only sample from the likelihood.

Solution:

- Idea: Keep  $\boldsymbol{\theta}$  such that  $\mathbf{X} \sim p(\cdot|\boldsymbol{\theta})$  is “*similar*” to  $\mathbf{Y}$ .
- **Contribution**: K2-ABC uses kernel MMD to define the similarity.
  - No need to design summary statistics.
  - Capture all information of  $p(\cdot|\boldsymbol{\theta})$ .
- Code/Paper: <https://github.com/wittawatj/k2abc>

## Questions?

Thank you

## References I

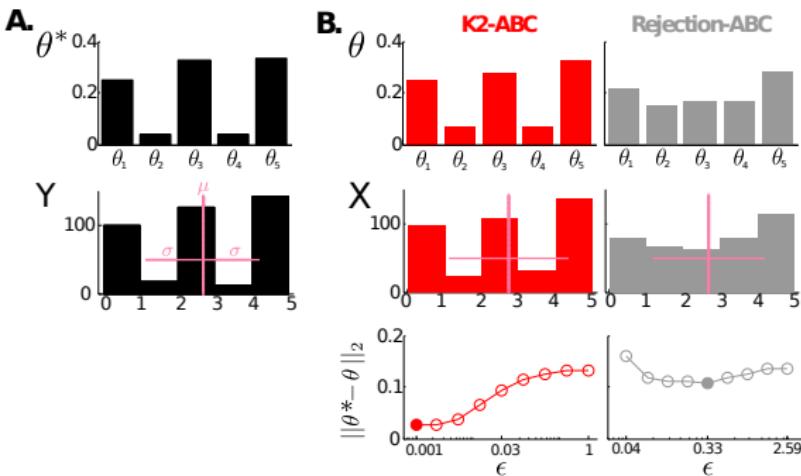
- K2-ABC on Arxiv: <http://arxiv.org/abs/1502.02558>
-  Gretton, A., Borgwardt, K. M., Rasch, M., Schölkopf, B., and Smola, A. J. (2006).  
A kernel method for the two-sample-problem.  
In *Advances in neural information processing systems*, pages 513–520.
-  Meeds, E. and Welling, M. (2014).  
GPS-ABC: Gaussian Process Surrogate Approximate Bayesian Computation.  
In *UAI*, volume 30, pages 593–601.

## Toy Problem: Failure of Insufficient Statistics

$$p(y|\theta) = \sum_{i=1}^5 \theta_i \text{Uniform}(y; [i-1, i])$$

$$\pi(\theta) = \text{Dirichlet}(\theta; \mathbf{1})$$

$\theta^*$  = (see figure A)



- $s(\mathbf{X}) = (\hat{\mathbb{E}}[x], \hat{\mathbb{V}}[x])^\top$  for Rejection and Soft ABC.
- Insufficient to represent  $p(y|\theta)$ .

## Rejection ABC Algorithm

- **Input:** observed dataset  $\mathbf{Y}$ , distance  $\rho$ , threshold  $\epsilon$
- **Output:** posterior sample  $\{\boldsymbol{\theta}_i\}_{i=1}^M$  from approximate posterior  $p_\epsilon(\boldsymbol{\theta}|\mathbf{Y}) \propto p(\boldsymbol{\theta})p_\epsilon(\mathbf{Y}|\boldsymbol{\theta})$

```
1: repeat
2:   Sample  $\boldsymbol{\theta} \sim p(\boldsymbol{\theta})$ 
3:   Sample a pseudo dataset  $\mathbf{X} \sim p(\cdot|\boldsymbol{\theta})$ 
4:   if  $\rho(\mathbf{X}, \mathbf{Y}) < \epsilon$  then
5:     Keep  $\boldsymbol{\theta}$ 
6:   end if
7: until we have  $M$  points
```

- **Notation:**  $\mathbf{Y}$  = observed set.  $\mathbf{X}$  = pseudo (generated) dataset.

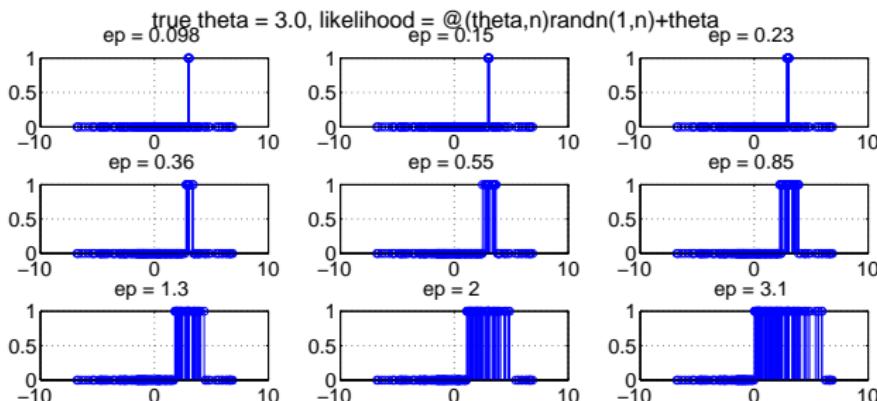
## Rejection ABC Example

$$p(y|\theta) = \mathcal{N}(y; \theta, 1)$$

$$p(\theta) = \mathcal{N}(\theta; 0, 8)$$

$$\theta^* = 3.0$$

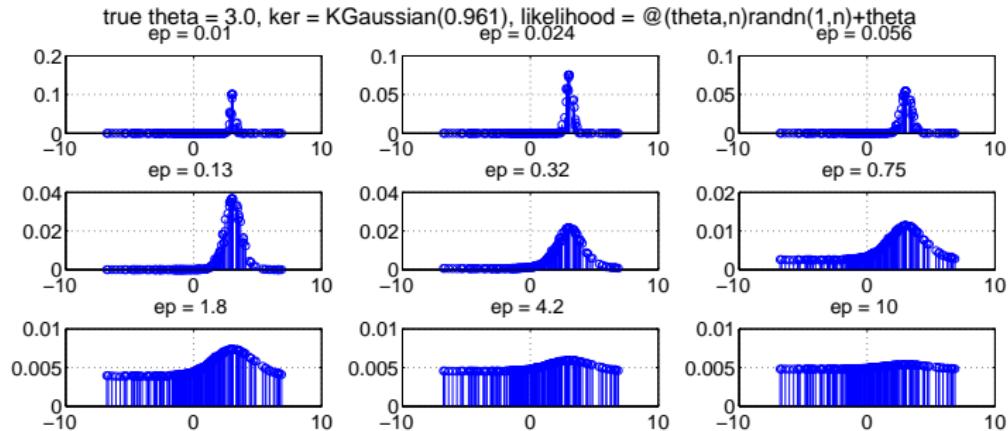
$$\rho(\mathbf{X}, \mathbf{Y}) = \left| \hat{\mathbb{E}}_{\mathbf{X}}[x] - \hat{\mathbb{E}}_{\mathbf{Y}}[y] \right|$$



- Low  $\epsilon \Rightarrow$  sample closely follows true posterior. High rejection rate.
- High  $\epsilon \Rightarrow$  get  $\theta$  sample from prior.

# 1D Gaussian Example with K2-ABC

$$\begin{aligned} p(y|\theta) &= \mathcal{N}(y; \theta, 1) \\ \pi(\theta) &= \mathcal{N}(\theta, 0, 8) \\ \theta^* &= 3.0 \end{aligned}$$



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