The Tradeoffs of Large Scale Learning

Leon Bottou, Olivier Bousquet

Arthur Gretton's notes

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When you have big data (tm) and not much time, what is the best way to learn?

- Gradient descent (first or second order)?
- Online (stochastic gradient descent, first or second order)?

"It is known" that for large-scale problems, stochastic methods are better. This paper proves why this should occur (for linear functions $f = w^{\top}x$). When you have big data (tm) and not much time, what is the best way to learn?

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Outline:

- How well can we learn with n samples?
- How do we trade off *time spent optimizing* and generalization performance?

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What is a learning problem?

Expected risk:

$$E(f) = \int \ell(f(x), y) dP(x, y)$$

for loss $\ell(f(x), y)$. Best possible function:

$$f^*(x) := \arg\min_{\hat{y}} \mathbb{E}\left[\ell(\hat{y}, y)|x\right].$$

If we're constrained to smaller function class ${\mathcal F},$ best answer:

$$f_{\mathcal{F}}^* := \arg\min_{f\in\mathcal{F}} E(f)$$

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Empirical risk:

$$E_n(f) = \frac{1}{n} \sum_{i=1}^n \ell(f(x_i), y_i).$$

Empirical risk minimizer:

$$f_n := \arg\min_{f\in\mathcal{F}} E_n(f).$$

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How well have we learned?

The excess error tells us how well we learned:

$$\mathcal{E} := \mathbb{E} \left[E(f_n) - E(f^*) \right]$$

= $\underbrace{\mathbb{E} \left[E(f_{\mathcal{F}}^*) - E(f^*) \right]}_{\mathcal{E}_{app}} + \underbrace{\mathbb{E} \left[E(f_n) - E(f_{\mathcal{F}}^*) \right]}_{\mathcal{E}_{est}}.$

- \mathcal{E}_{app} : approximation error (small for rich \mathcal{F})
- \mathcal{E}_{est} : estimation error (small for simple \mathcal{F})
- \mathbb{E} : expectation over *n*-sample (relevant in \mathcal{E}_{est})

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What if we learn only to some precision?

$$E_n(\tilde{f}_n) \leq E_n(f_n) + \rho$$

Additional term

$$\mathcal{E}_{\mathrm{opt}} = \mathbb{E}\left[E(\tilde{f}_n) - E(f_n)\right]$$

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New excess error

$$\mathcal{E} = \underbrace{\mathbb{E}\left[E(f_{\mathcal{F}}^*) - E(f^*)\right]}_{\mathcal{E}_{app}} + \underbrace{\mathbb{E}\left[E(f_n) - E(f_{\mathcal{F}}^*)\right]}_{\mathcal{E}_{est}} + \underbrace{\mathbb{E}\left[E(\tilde{f}_n) - E(f_n)\right]}_{\mathcal{E}_{opt}}.$$

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How well *can* we learn?

Our setting: $f := w^{\top} x$ for $w \in \mathbb{R}^d$, and x, y, ℓ bounded. Best bounds

$$\mathcal{E}_{\mathrm{app}} + \mathcal{E}_{\mathrm{est}} \leq c \left(\mathcal{E}_{\mathrm{app}} + \left(rac{d}{n} \log rac{n}{d}
ight)^{lpha}
ight) \qquad rac{1}{2} \leq lpha \leq 1,$$

if we are allowed to assume variance condition

$$\forall f \in \mathcal{F}, \quad \mathbb{E}\left(\ell(f(x), y) - \ell(f_{\mathcal{F}}^*(x), y)\right)^2 \leq c\left(E(f) - E(f_{\mathcal{F}}^*)\right)^{2-\alpha^{-1}}$$

(large α is easier).¹

¹Not very intuitive: for *classification*, clearer condition is Tsybakov noise condition, $\exists \mu > 0, \beta \in (0, \infty)$ s.t. $\forall \varepsilon > 0, \mathbb{P}(|\eta(x) - 1/2| \le \epsilon) \le \mu \epsilon^{\beta}$. $\exists \varepsilon \in \Xi > \exists \varepsilon \in \mathbb{R}$ Leon Bottou, Olivier Bousquet (Arthur C The Tradeoffs of Large Scale Learning January 8, 2015 6 / 12

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Then

$$\mathcal{E}_{\mathrm{app}} + \mathcal{E}_{\mathrm{est}} + \mathcal{E}_{\mathrm{opt}} \leq c \left(\mathcal{E}_{\mathrm{app}} + \left(rac{d}{n} \log rac{n}{d}
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Now to optimize: first some definitions

Recall $f_w = w^{\top} x$. Empirical cost function

$$C=E_n(f_w).$$

Empirical optimum occurs at w_n .

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Recall $f_w = w^{\top} x$. Empirical cost function

$$C=E_n(f_w).$$

Empirical optimum occurs at w_n . Hessian at optimum is

$$H = \frac{d^2 C}{dw^2}(w_n) \quad \text{eigenvalues} \in [\lambda_{\min}, \lambda_{\max}], \quad \text{condition} \# \kappa = \lambda_{\max} / \lambda_{\min}.$$

Gradient covariance at optimum

$$G = \mathbb{E}_n\left(\left(\frac{\partial \ell(f_{w_n}(x), y)}{\partial w}\right)\left(\frac{\partial \ell(f_{w_n}(x), y)}{\partial w}\right)^{\top}\right) \qquad \operatorname{tr}(G^{-1}H) \leq \nu.$$

(statements on eigenvalue range and bound on $tr(G^{-1}H)$ are w.h.p. since quantities are empirical).

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How fast to optimize to precision ρ ?

Block strategies:

• Gradient descent: precision ρ with steps² $O(\kappa \log(1/\rho))$,

$$w(t+1) = w(t) - \eta \frac{\partial C}{\partial w}(w(t)).$$

Time to reach ρ : O(nd $\kappa \log(1/\rho)$)

• "Magical" second order gradient descent (we are given H): ρ in steps $O(\log \log(1/\rho))$,

$$w(t+1) = w(t) - H^{-1} \frac{\partial C}{\partial w}(w(t)).$$

Time to reach ρ : $O((d^2 + nd) \log \log(1/\rho))$ (no κ , better dependence on ρ)

How fast to optimize to precision ρ ?

Stochastic gradient descent strategies:

• **Stochastic** gradient descent: precision ρ with steps³ $\nu \kappa^2 \rho^{-1} + o(1/\rho)$,

$$w(t+1) = w(t) - \frac{\eta}{t} \frac{\partial}{\partial w} \left[\ell(f_{w(t)}(x_t), y_t) \right].$$

Time to reach ρ : O(d $\nu \kappa^2 / \rho$), (note: no *n*.

• "Magical" second order *stochastic* gradient descent: ρ in steps $\nu \rho^{-1} + o(1/\rho)$,

$$w(t+1) = w(t) - \frac{1}{t}H^{-1}\frac{\partial}{\partial w}\left[\ell(f_{w(t)}(x_t), y_t)\right].$$

Time to reach ρ : $O(d^2\nu/\rho)$ (no κ , same dependence on ρ)

³Given stepsize $\eta = \lambda_{\min}^{-1}$

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Putting all the results together

What is time to get error ε above \mathcal{E}_{app} ? (use $n \sim d\varepsilon^{-1/\alpha} \log(\alpha^{-1})$ for batch)

 $\begin{array}{c} \text{Time to reach} \\ \underline{\mathcal{E}} \leq c \left(\mathcal{E}_{app} + \varepsilon \right) \\ \hline \\ & \mathbb{O} \left(\frac{d^2 \kappa}{\varepsilon^{1/\alpha}} \log^2 \frac{1}{\varepsilon} \right) \\ \mathbb{O} \left(\frac{d^2}{\varepsilon^{1/\alpha}} \log \frac{1}{\varepsilon} \log \log \frac{1}{\varepsilon} \right) \\ & \mathbb{O} \left(\frac{d \nu \kappa^2}{\varepsilon} \right) \\ & \mathbb{O} \left(\frac{d^2 \nu}{\varepsilon} \right) \\ \\ & \mathbb{O} \left(\frac{d^2 \nu}{\varepsilon} \right) \\ \end{array} \right) \\ \end{array}$

- Stochastic methods have the best generalization performance, despite having the worst optimization performance on the empirical cost.
- Fast convergence in SGD bounds doesn't depend on α (but watch out for constants!).

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Experiment 1: logistic loss

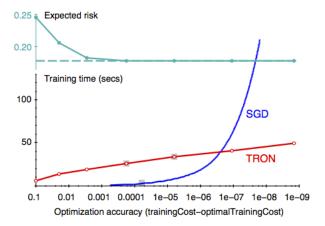


Figure: Superlinear batch method (TRON) vs SGD

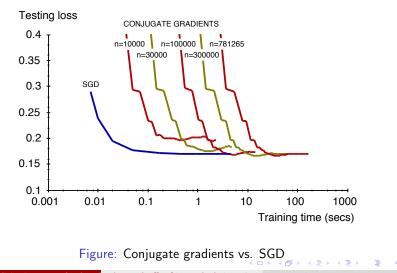
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Experiment 2:



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