Probabilistic & Unsupervised Learning

Belief Propagation

Maneesh Sahani

maneesh@gatsby.ucl.ac.uk

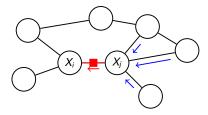
Gatsby Computational Neuroscience Unit, and MSc ML/CSML, Dept Computer Science University College London

Term 1, Autumn 2014

Loopy Belief Propagation

Joint distribution of undirected graph:

$$p(\mathcal{X}) = \frac{1}{Z} \prod_{\text{nodes } i} f_i(X_i) \prod_{\text{edges } (ij)} f_{ij}(X_i, X_j)$$



Messages computed recursively (with few guarantees of convergence):

$$M_{j \to i}(X_i) := \sum_{X_j} f_{ij}(X_i, X_j) f_j(X_j) \prod_{l \in \mathsf{ne}(j) \setminus i} M_{l \to j}(X_j)$$

Marginal distributions are approximate in general:

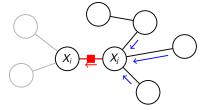
$$p(X_i) \approx b_i(X_i) \propto f_i(X_i) \prod_{k \in ne(i)} M_{k \to i}(X_i)$$

$$p(X_i, X_j) \approx b_{ij}(X_i, X_j) \propto f_{ij}(X_i, X_j) f_i(X_i) f_j(X_j) \prod_{k \in \mathsf{ne}(i) \setminus j} M_{k \to i}(X_i) \prod_{l \in \mathsf{ne}(j) \setminus i} M_{l \to j}(X_j)$$

Recall: Belief Propagation on undirected trees

Joint distribution of undirected tree:

$$p(\mathcal{X}) = \frac{1}{Z} \prod_{\text{nodes } i} f_i(X_i) \prod_{\text{edges } (ii)} f_{ij}(X_i, X_j)$$



Messages computed recursively:

$$M_{j o i}(X_i) := \sum_{X_j} f_{ij}(X_i, X_j) f_j(X_j) \prod_{l \in \mathsf{ne}(j) \setminus i} M_{l o j}(X_j)$$

Marginal distributions:

$$p(X_i) \propto f_i(X_i) \prod_{k \in \mathsf{ne}(i)} M_{k \to i}(X_i)$$

$$p(X_i, X_j) \propto f_{ij}(X_i, X_j) f_i(X_i) f_j(X_j) \prod_{k \in \mathsf{ne}(i) \setminus j} M_{k \to i}(X_i) \prod_{l \in \mathsf{ne}(j) \setminus i} M_{l \to j}(X_j)$$

Dealing with loops

- Accuracy: BP posterior marginals are approximate on all non-trees, but converged approximations are frequently found to be good.
- ► Convergence: no general guarantee, but BP does converge in some cases:
 - ► Trees.
 - Graphs with a single loop.
 - Distributions with sufficiently weak interactions.
 - Graphs with long (and weak) loops
 - Gaussian networks: means correct, variances may also converge.
- ▶ Damping: Common approach to encourage convergence (cf EP)

$$M_{i \to j}^{\mathsf{new}}(X_j) := (1 - \alpha) M_{i \to j}^{\mathsf{old}}(X_j) + \alpha \sum_{X_i} f_{ij}(X_i, X_j) f_i(X_i) \prod_{k \in \mathsf{ne}(i) \setminus j} M_{k \to i}(X_i)$$

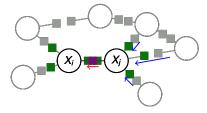
- Grouping variables: Variables can be grouped into cliques to improve accuracy.
 - Region graph approximations.
 - Cluster variational method.
 - Junction graph.

Different Interpretations of Loopy Belief Propagation

Loopy BP can be interpreted as a fixed point algorithm from a few different perspectives:

- Expectation propagation.
- Tree-based reparametrization.
- Bethe free energy.

Loopy BP as message-based EP



Then the EP updates to the messages are:

► Deletion:

$$q_{\neg ij}(X_i, X_j) = f_i(X_i) f_j(X_j) \prod_{k \in \mathsf{ne}(i) \setminus j} M_{k \to i}(X_i) \prod_{l \in \mathsf{ne}(j) \setminus i} M_{l \to j}(X_j) \prod_{s \neq i, j} f_s(X_s) \prod_{t \in \mathsf{ne}(s)} M_{t \to s}(X_s)$$

Projection:

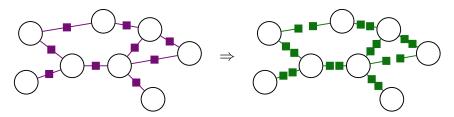
$$\{M_{i\rightarrow j}^{\text{new}}, M_{j\rightarrow i}^{\text{new}}\} = \operatorname{argmin} \mathbf{KL}[f_{ij}(X_i, X_j)q_{\neg ij}(X_i, X_j) \| M_{j\rightarrow i}(X_i)M_{i\rightarrow j}(X_j)q_{\neg ij}(X_i, X_j)]$$

Now, $q_{\neg ij}()$ factors \Rightarrow rhs factors \Rightarrow min is achieved by marginals of $f_{ij}()q_{\neg ij}()$

$$M_{j\rightarrow i}^{\mathsf{new}}(X_i)q_{\neg ij}(X_i) = \sum_{X_j} \left(f_{ij}(X_i, X_j) f_j(X_j) \prod_{l \in \mathsf{ne}(j) \setminus i} M_{l\rightarrow j}(X_j) \right) f_i(X_i) \prod_{k \in \mathsf{ne}(i) \setminus j} M_{k\rightarrow i}(X_i)$$

$$\Rightarrow M_{j\rightarrow i}^{\mathsf{new}}(X_i) = \sum_{X_j} \left(f_{ij}(X_i, X_j) f_j(X_j) \prod_{l \in \mathsf{ne}(j) \setminus i} M_{l\rightarrow j}(X_j) \right)$$

Loopy BP as message-based Expectation Propagation



Approximate pairwise factors f_{ij} by product of messages:

$$f_{ij}(X_i, X_j) \approx \tilde{f}_{ij}(X_i, X_j) = M_{i \to j}(X_j) M_{j \to i}(X_i)$$

Thus, the full joint is approximated by a factorised distribution:

$$\rho(\mathcal{X}) \approx \frac{1}{Z} \prod_{\text{nodes } i} f_i(X_i) \prod_{\text{edges } (ij)} \tilde{f}_{ij}(X_i, X_j) = \frac{1}{Z} \prod_{\text{nodes } i} \left(f_i(X_i) \prod_{j \in \text{ne}(i)} M_{j \to i}(X_i) \right) = \prod_{\text{nodes } i} b_i(X_i)$$

but with multiple factors for most X_i .

Loopy BP as tree-based reparametrisation

Tree-structured distributions can be parametrised in many ways:

$$p(\mathcal{X}) = \frac{1}{Z} \prod_{\text{nodes } i} f_i(X_i) \prod_{\text{edges}(ij)} f_{ij}(X_i, X_j) \qquad \text{undirected tree}$$
 (1)

$$= p(X_r) \prod_{i \neq r} p(X_i | X_{pa(i)})$$
 directed (rooted) tree (2)

$$= \prod_{\text{nodes } i} \rho(X_i) \prod_{\text{edges } (ij)} \frac{\rho(X_i, X_j)}{\rho(X_i)\rho(X_j)}$$
 pairwise marginals (3)

where (3) requires that $\sum_{X_i} p(X_i, X_j) = p(X_i)$.

The undirected tree representation is not unique—multiplying a factor $f_{ij}(X_i, X_j)$ by $g(X_i)$ and dividing $f_i(X_i)$ by the same $g(X_i)$ does not change the distribution.

BP can be seen as an iterative replacement of $f_i(X_i)$ by the local marginal of $p_{ij}(X_i, X_j)$, along with the corresponding reparametrisation of $f_{ij}(X_i, X_j)$. Cf. Hugin propagation.

Converged BP on a tree finds $p(X_i)$ and $p(X_i, X_i)$, allowing us to transform (1) to (3).

Reparametrisation on non-trees

► If BP converges on a non-tree, it will have successfully reparametrised the distribution to have locally consistent beliefs:

$$p(\mathcal{X}) = \prod_i b(X_i) \prod_{(ij)} \frac{b(X_i, X_j)}{b(X_i)b(X_j)} \quad \text{with} \quad \sum_{X_i} b(X_i, X_j) = b(X_i) \text{ etc.}$$

► However, the marginals will not usually be correct or globally consistent. That is

$$\sum_{\mathcal{X}_{\neg i}} \left(\prod_{i} b(X_i) \prod_{(ij)} \frac{b(X_i, X_j)}{b(X_i)b(X_j)} \right) \neq b(X_i)$$

- What can be said about these pseudomarginals?
- Consider the following (theoretical) message scheduling scheme:
 - ► Identify all the spanning trees of the graph.
 - Pass messages along edges of each spanning tree in turn.
 - Iterate over spanning trees to convergence

Loopy BP as tree-based reparametrisation

At convergence, loopy BP has reparametrised the joint distribution as:

$$p(\mathcal{X}) = \frac{1}{Z} \prod_{\text{nodes } i} f_i^{\infty}(X_i) \prod_{\text{edges } (ij)} f_{ij}^{\infty}(X_i, X_j)$$

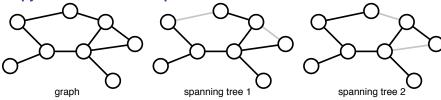
where for any tree T embedded in the graph,

$$f_i^{\infty}(X_i) = p^{T}(X_i)$$
$$f_{ij}^{\infty}(X_i, X_j) = \frac{p^{T}(X_i, X_j)}{p^{T}(X_i)p^{T}(X_j)}$$

Thus, the local marginals of all subtrees are locally consistent with each other, and the pseudomarginals represent valid beliefs for any of the subtrees.

$$p(\mathcal{X}) = \frac{1}{Z} \prod_{\text{nodes } i} b_i(X_i) \prod_{\text{edges } (ij)} \frac{b_{ij}(X_i, X_j)}{b_i(X_i)b_j(X_j)}$$

Loopy BP as tree-based reparametrisation



$$\begin{split} \rho(\mathcal{X}) &= \frac{1}{Z} \prod_{\mathsf{nodes}\ i} f_i^0(X_i) \prod_{\mathsf{edges}\ (ij)} f_{ij}^0(X_i, X_j) \\ &= \frac{1}{Z} \prod_{\mathsf{nodes}\ i \in \mathcal{T}_1} f_i^0(X_i) \prod_{\mathsf{edges}\ (ij) \in \mathcal{T}_1} f_{ij}^0(X_i, X_j) \prod_{\mathsf{edges}\ (ij) \not\in \mathcal{T}_1} f_{ij}^0(X_i, X_j) \\ &= \frac{1}{Z} \prod_{\mathsf{nodes}\ i \in \mathcal{T}_1} f_i^1(X_i) \prod_{\mathsf{edges}\ (ij) \in \mathcal{T}_1} f_{ij}^1(X_i, X_j) \prod_{\mathsf{edges}\ (ij) \not\in \mathcal{T}_1} f_{ij}^1(X_i, X_j) \end{split}$$

where
$$f_i^1(X_i) = \rho^{T_1}(X_i)$$
, $f_{ij}^1(X_i, X_j) = \frac{\rho^{T_1}(X_i, X_j)}{\rho^{T_1}(X_j)\rho^{T_1}(X_j)}$, $f_{ij}^1 = f_{ij}^0$.

$$= \frac{1}{Z} \prod_{\text{nodes } i \in T_2} f_i^1(X_i) \prod_{\text{edges } (ij) \in T_2} f_{ij}^1(X_i, X_j) \prod_{\text{edges } (ij) \notin T_2} f_{ij}^1(X_i, X_j)$$

Loopy BP and Bethe free energy

In the reparametrisation view, BP solves for marginal beliefs $b_{ij}(X_i, X_j)$ and $b_i(X_i) = \sum_{X_i} b_{ij}(X_i, X_j)$ such that

$$p(X) = \frac{1}{Z} \prod_{i} f_i(X_i) \prod_{(ij)} f_{ij}(X_i, X_j) = \prod_{i} b_i(X_i) \prod_{(ij)} \frac{b_{ij}(X_i, X_j)}{b_i(X_i)b_j(X_j)}$$

Another view of loopy BP is as a set of fixed point equations for finding stationary points of an objective function called the Bethe free energy, which is defined in terms of the locally consistent beliefs (or pseudomarginals) $b_i \ge 0$ and $b_{ij} \ge 0$:

$$\sum_{x_i} b_i(x_i) = 1$$
 $\forall i$ $\sum_{x_j} b_{ij}(x_i, x_j) = b_i(x_i)$ $\forall i, j \in \mathsf{ne}(i), x_i$

Loopy BP and Bethe free energy

Recall that the variational free energy is: $\mathcal{F}(q) = \langle \log P(\mathcal{X}) \rangle_q + \mathbf{H}[q]$

We define the (negative) Bethe free energy: $\mathcal{F}_{bethe}(b) = \mathcal{E}_{bethe}(b) + \mathcal{H}_{bethe}(b)$

The Bethe average energy is the expected log-joint evaluated as though the pseudomarginals were correct:

$$\mathcal{E}_{bethe}(b) = \sum_{i} \sum_{x_i} b_i(x_i) \log f_i(x_i) + \sum_{(ij)} \sum_{x_i, x_i} b_{ij}(x_i, x_j) \log f_{ij}(x_i, x_j)$$

 The Bethe entropy is approximate: it is the sum of the pseudomarginal entropies corrected for pairwise (pseudo)interactions, but neglecting higher

$$egin{aligned} \mathcal{H}_{\mathsf{bethe}}(b) &= \sum_i \mathsf{H}[b_i] - \sum_{(ij)} \mathsf{KL}[b_{ij} \| b_i b_j] \ &= - \sum_j \sum_{x_i} b_i(x_i) \log b_i(x_i) - \sum_{(ij)} \sum_{x_i, x_i} b_{ij}(x_i, x_j) \log rac{b_{ij}(x_i, x_j)}{b_i(x_i) b_j(x_j)} \end{aligned}$$

- ightharpoonup On a tree, both the beliefs and the Bethe entropy expression are correct, so $\mathcal{F}_{\mathsf{bethe}} = \mathcal{F}$.
- Message updates in loopy BP can now be derived by finding the stationary points of a Lagrangian with local consistency and normalisation constraints. The BP messages are related to the Lagrange multipliers.

Bethe fixed point messages

The Bethe Lagrangian fixed point equations are:

$$b_i(x_i) \propto f_i(x_i) \prod_{j \in \text{ne}(i)} e^{-\xi_{ij}(x_i)}$$
 $b_{ij}(x_i, x_i) \propto f_{ij}(x_i, x_j) b_i(x_i) b_i(x_j) e^{\xi_{ij}(x_i)} e^{\xi_{ij}(x_j)}$

Comparison with BP suggests that messages should have the form $M_{j o i}(x_i) = e^{-\xi_{ij}(x_i)}$.

Indeed, solving for $\xi_{ij}(x_i)$ by enforcing the constraint $\sum_{x_i} b_{ij}(x_i, x_j) = b_i(x_i)$ we have:

$$\sum_{x_j} b_{ij}(x_i, x_j) \propto \sum_{x_j} f_{ij}(x_i, x_j) b_i(x_i) b_j(x_j) e^{\xi_{ij}(x_i)} e^{\xi_{ji}(x_j)}$$

$$\Rightarrow b_i(x_i) \propto b_i(x_i) e^{\xi_{ij}(x_i)} \sum_{x_j} f_{ij}(x_i, x_j) b_j(x_j) e^{\xi_{ji}(x_j)}$$

$$\Rightarrow e^{-\xi_{ij}(x_i)} \propto \sum_{x_j} f_{ij}(x_i, x_j) b_j(x_j) e^{\xi_{ji}(x_j)}$$

$$= \sum_{x_i} f_{ij}(x_i, x_j) f_j(x_j) \prod_{l \in ne(j) \setminus i} e^{-\xi_{ji}(x_j)}$$

thus recovering the BP message passing rules.

Bethe fixed point equations

The Bethe free-energy Lagrangian is:

$$\mathcal{L} = \sum_{i} \sum_{x_{i}} b_{i}(x_{i}) \log f_{i}(x_{i}) + \sum_{(ij)} \sum_{x_{i}, x_{j}} b_{ij}(x_{i}, x_{j}) \log f_{ij}(x_{i}, x_{j})$$

$$- \sum_{i} \sum_{x_{i}} b_{i}(x_{i}) \log b_{i}(x_{i}) - \sum_{(ij)} \sum_{x_{i}, x_{j}} b_{ij}(x_{i}, x_{j}) \log \frac{b_{ij}(x_{i}, x_{j})}{b_{i}(x_{i})b_{j}(x_{j})}$$

$$+ \sum_{i} \xi_{i} \left(\sum_{x_{j}} b_{i}(x_{i}) - 1\right)$$

$$+ \sum_{(ij)} \left[\sum_{x_{i}} \xi_{ij}(x_{i}) \left(\sum_{x_{j}} b_{ij}(x_{i}, x_{j}) - b_{i}(x_{i})\right) + \sum_{x_{j}} \xi_{ji}(x_{j}) \left(\sum_{x_{i}} b_{ij}(x_{i}, x_{j}) - b_{j}(x_{j})\right)\right]$$

$$\left[\text{marg } \forall i, j, x_{i}\right]$$

Setting derivatives wrt beliefs to 0 gives

$$\frac{\partial \mathcal{L}}{\partial b_{i}(x_{i})} = \log f_{i}(x_{i}) - \log b_{i}(x_{i}) + \sum_{j \in \text{ne}(i)} \underbrace{\sum_{x_{j}} \frac{b_{ij}(x_{i}, x_{j})}{b_{i}(x_{i})}}_{=1 \text{ by constraint}} + \xi_{i} - \sum_{j \in \text{ne}(i)} \xi_{ij}(x_{i}) + const = 0$$

$$\Rightarrow b_{i}(x_{i}) \propto f_{i}(x_{i}) \prod_{j \in \text{ne}(i)} e^{-\xi_{ij}(x_{i})}$$

$$\frac{\partial \mathcal{L}}{\partial b_{ij}(x_{i}, x_{j})} = \log f_{ij}(x_{i}, x_{j}) - \log b_{ij}(x_{i}, x_{j}) + \log b_{i}(x_{i})b_{j}(x_{j}) + \xi_{ij}(x_{i}) + \xi_{ji}(x_{j}) + const = 0$$

$$\Rightarrow b_{ij}(x_{i}, x_{j}) \propto f_{ij}(x_{i}, x_{j})b_{i}(x_{i})b_{j}(x_{j})e^{\xi_{ij}(x_{i})}e^{\xi_{ij}(x_{j})}$$

Loopy BP and Bethe free energy

- Fixed points of loopy BP are exactly the stationary points of the Bethe free energy.
- Stable fixed points of loopy BP are local maxima of Bethe free enegy (note the negative definition of free energy for consistency with the variational free energy).
- For binary attractive networks, Bethe free energy at fixed points of loopy BP provides an upper bound on the log partition function log Z—this is useful for learning undirected graphical models as it leads to a lower bound on the log likelihood.

Loopy BP vs variational approximation

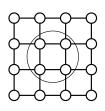
- Beliefs b_i and b_{ij} in loopy BP are only locally consistent pseudomarginals, not necessarily consistent marginals of the implied joint distribution.
- Bethe free energy accounts for interactions between different sites, while variational free energy assumes independence.
- ► The loop series or Plefka expansion of the log partition function Z: the variational free energy forms the first order terms, while Bethe free energy contains higher order terms (involving generalized loops).
- ▶ Loopy BP tends to be signficantly more accurate whenever it converges.

References

- Probabilistic Reasoning in Intelligent Systems. J. Pearl. Morgan Kaufman, 1988.
- Turbo decoding as an instance of Pearl's belief propagation algorithm. R. J. McEliece, D. J. C. MacKay and J. F. Cheng. IEEE Journal on Selected Areas in Communication, 1998, 16(2):140-152.
- Iterative decoding of compound codes by probability propagation in graphical models. F. Kschischang and B. Frey. IEEE Journal on Selected Areas in Communication, 1998, 16(2):219-230.
- A family of algorithms for approximate Bayesian inference. T. Minka. PhD Thesis, 2001.
- ► Tree-based reparameterization framework for analysis of sum-product and related algorithms. M. J. Wainwright, T. S. Jaakkola and A. S. Willsky. IEEE Transactions on Information Theory, 2004, 49(5).
- Constructing free energy approximations and generalized belief propagation algorithms.
 J. S. Yedidia, W. T. Freeman and Y. Weiss. IEEE Transactions on Information Theory, 2005. 51:2282-2313.

Extensions and variations

- Generalized BP: group variables together to treat their interactions exactly.
- Convergent alternatives: Fixed points of loopy BP are stationary points of the Bethe free enegy. We can also derive algorithms that increase the Bethe free energy at every step, and are thus are guaranteed to converge.



- Convex alternatives: We can derive convex cousins of the negative of the Bethe free energy. These give rise to algorithms that will converge to a unique global maximum.
- We have considered sum-product loopy BP to compute marginals. The treatment of loopy Viterbi or max-product algorithms is different.