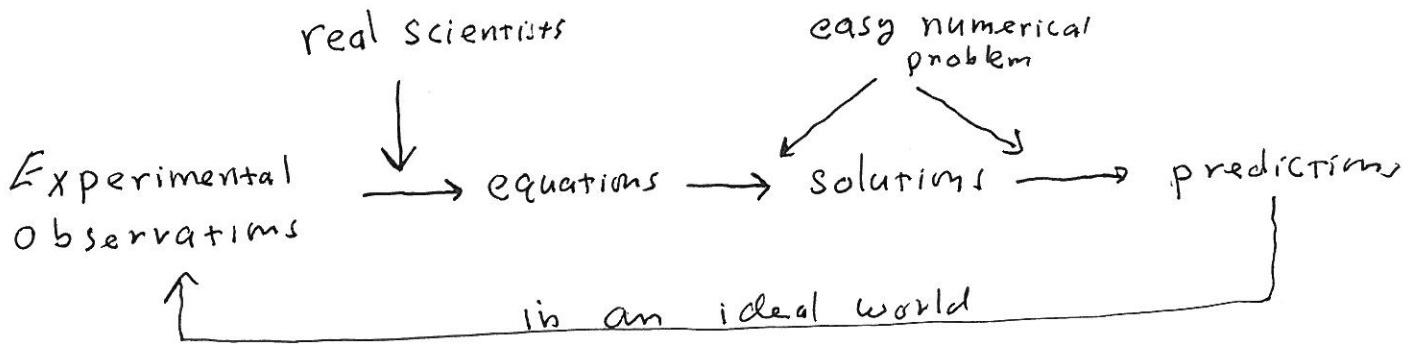


①

10/19/04



Two things changed this view:

1. The open question is: how do low level eqns. (e.g. HH) describe high level behavior (e.g. people).
2. "Easy" numerical problem isn't. Often easy should be replaced by impossible.

So, people started studying equations and their solutions. (Dynamical systems a.k.a. chaos theory).

Questions:

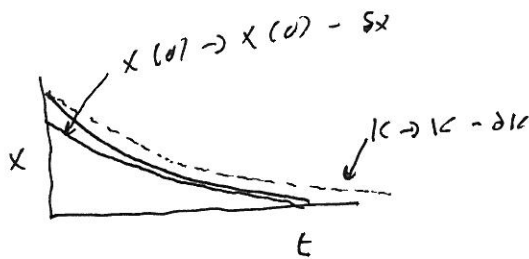
1. Do equations fall into distinct classes, w/ each class having characteristic solutions?
2. What equations can be solved?
3. What does question (2) mean?
4. Are solutions to equations sensitive to
 - a) initial conditions?
 - b) parameters? ~~of eqn~~

Sort of
depends on
eqn
hard
~~usually~~
almost
always

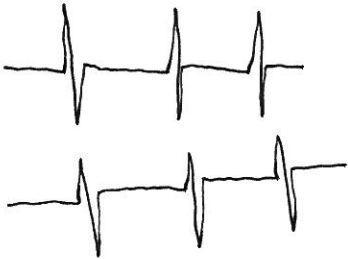
(2)

Example 1:

$$\frac{dx}{dt} = -kx$$



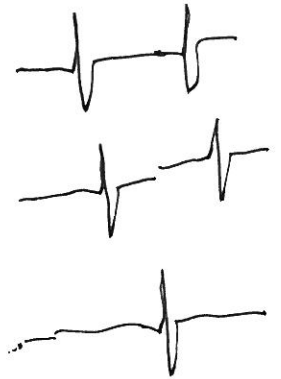
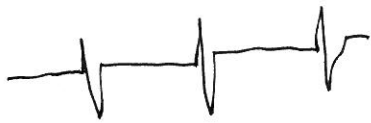
diff'n D.C.



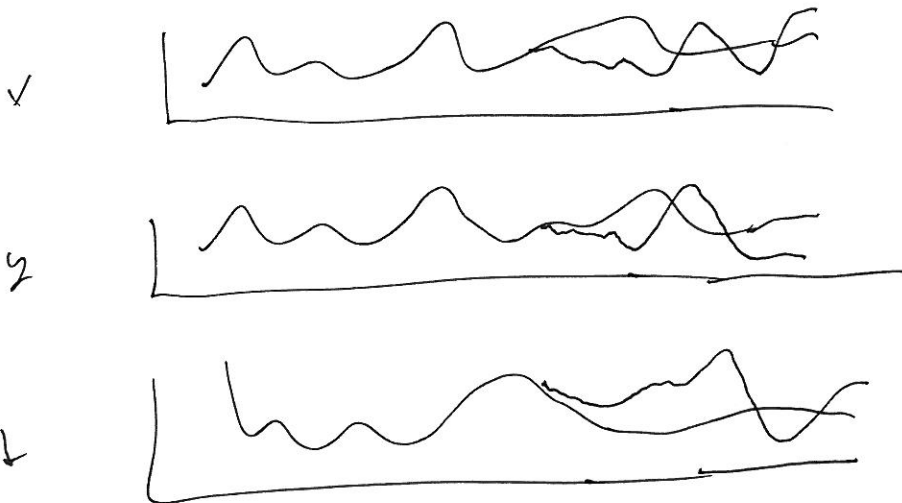
diff'n D.C.

diff'n

diff'n param



Edward Lorenz (~1960)



~~etc~~

Brush of a field

(3)

We're going to use some of these techniques to examine spiking neurons, starting with HH.

$$\tau \frac{dv}{dt} = F(V, m, h, n) + I$$

$$F(V, m, h, n) = - (V - E_L) \bar{g}_L + \bar{p}_{Na} m^3 h (V - E_{Na}) - \bar{p}_K n^4 (V - E_{K0})$$

$$\tau = \frac{C_m}{\bar{g}_L} = C_m R_m$$

$$\bar{p}_{Na} = \frac{\bar{g}_{Na}}{\bar{g}_L} \quad \bar{p}_K = \frac{\bar{g}_K}{\bar{g}_L}$$

$$\tau_m(v) \frac{dm}{dt} = m_\infty(v) - m$$

$$\tau_h(v) \frac{dh}{dt} = h_\infty(v) - h$$

$$\tau_n(v) \frac{dn}{dt} = n_\infty(v) - n$$

4-D ODE!!!

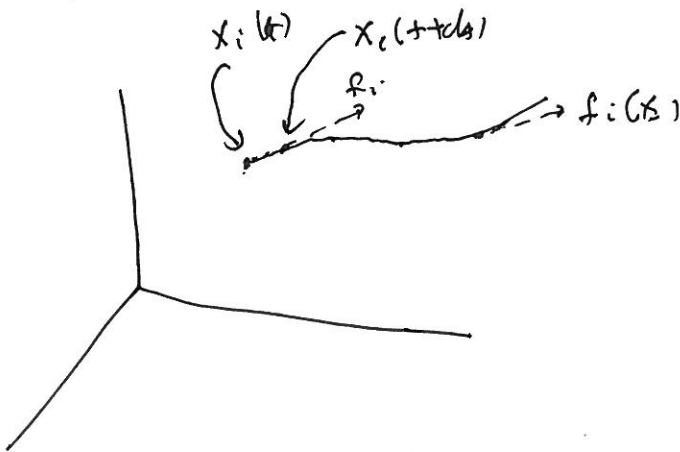
(4)

111

Aside on solutions to equations

$$\frac{dx_i}{dt} = f_i(\underline{x}) \quad \leftarrow x_1, x_2, \dots$$

$$\begin{aligned} x_i(t+dt) &\approx x_i(t) + \frac{dx_i}{dt} dt \\ &= x_i(t) + f_i(x) dt \end{aligned}$$



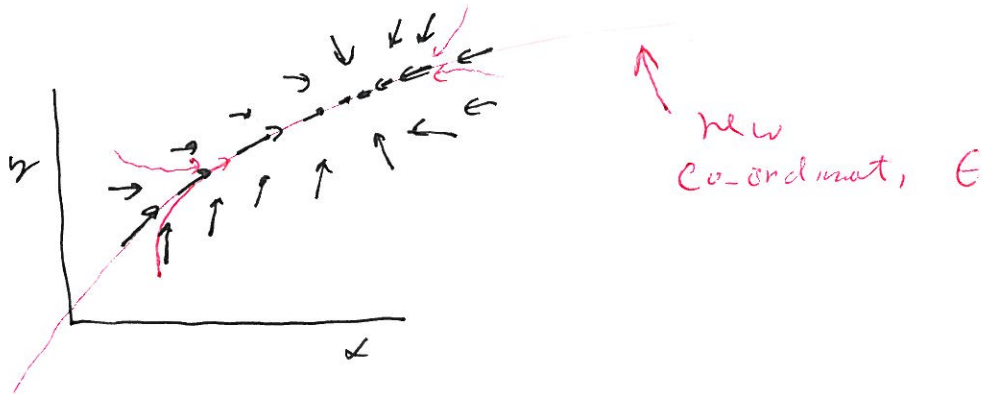
- Solutions are trajectories
- f is vector field

Problem: go from vector field to trajectories

112

(5)

Dimensionality reduction



$$\frac{dx}{dt} = f_x(x, y)$$

$$\frac{dy}{dt} = f_y(x, y)$$

$$\Rightarrow \frac{d\theta}{dt} = F(\theta)$$

The plan: find ~~strangely attractors~~ attractors

∞ -dimensional ODE's (AKA PDE's) can have finite dimensional attractors!

- reduce 4-D HH \rightarrow 2-D

⑥

Approximation #1: $\tau \gg \tau_m, \tau_h, \tau_n$ (high resistance cell).

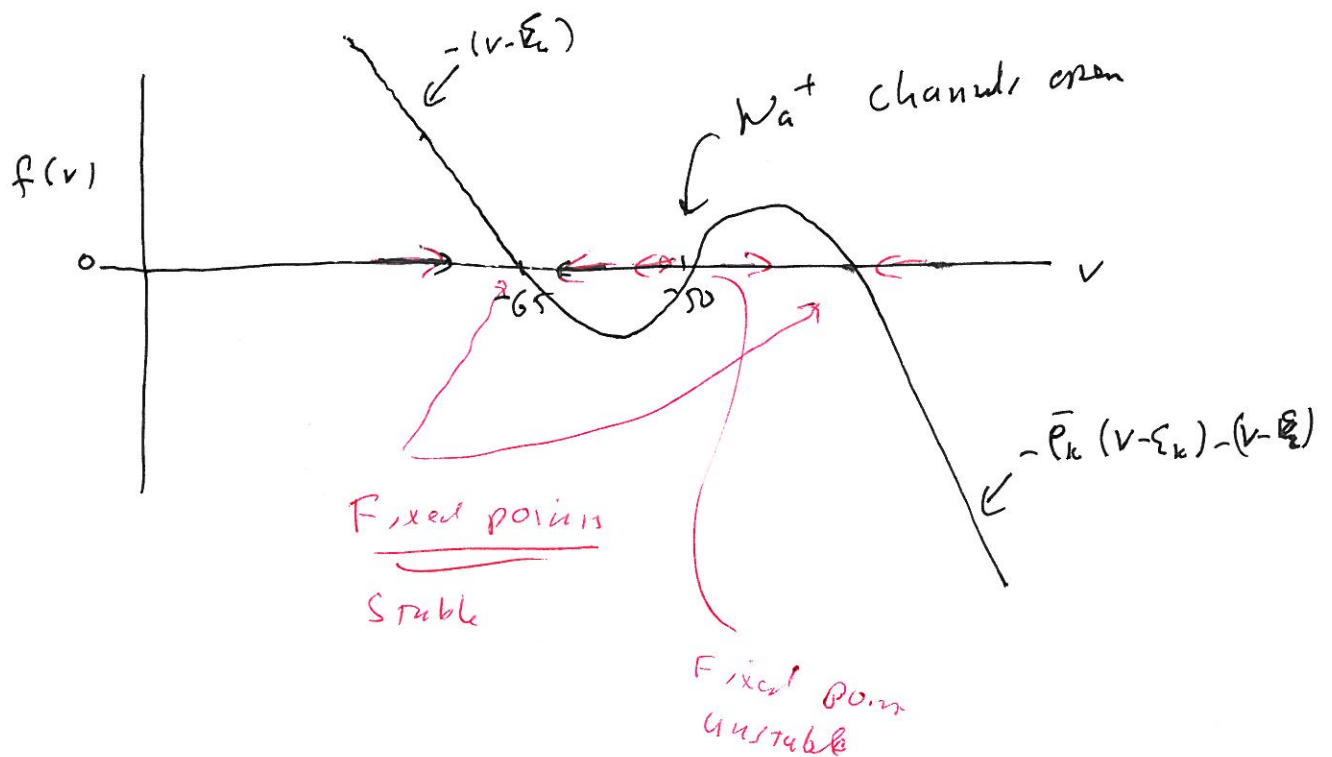
$$\Rightarrow m \approx m_\infty(v)$$

$$n \approx n_\infty(v)$$

$$h \approx h_\infty(v)$$

$$\tau \frac{dv}{dt} = F(v, m_\infty(v), h_\infty(v), n_\infty(v)) + I$$
$$= f(v) + I$$

What does $f(v)$ look like?



(7)

$$\tau \frac{dv}{dt} = f(v) + I$$

$$f(v_0) + I = 0 \quad (\text{fixed point})$$

$$v = v_0 + \delta v, \quad \delta v \ll v_0 \text{ small}$$

$$\begin{aligned} \tau \frac{d}{dt} v &= \tau \frac{d}{dt} (v_0 + \delta v) = \tau \frac{d\delta v}{dt} = f(v_0 + \delta v) + I \\ &\approx f(v_0) + \delta v f'(v_0) + I \end{aligned}$$

$$\tau \frac{d\delta v}{dt} = f'(v_0) \delta v \Rightarrow \delta v(t) = \delta v(0) e^{\frac{f'(v_0)t}{\tau}}$$

$$f'(v_0) < 0 \Rightarrow \text{stable}$$

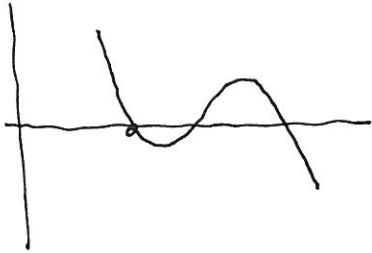
$$f'(v_0) > 0 \Rightarrow \text{unstable}$$

///

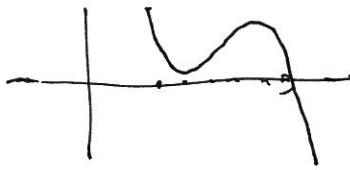
8

No repetitive firings!!!!

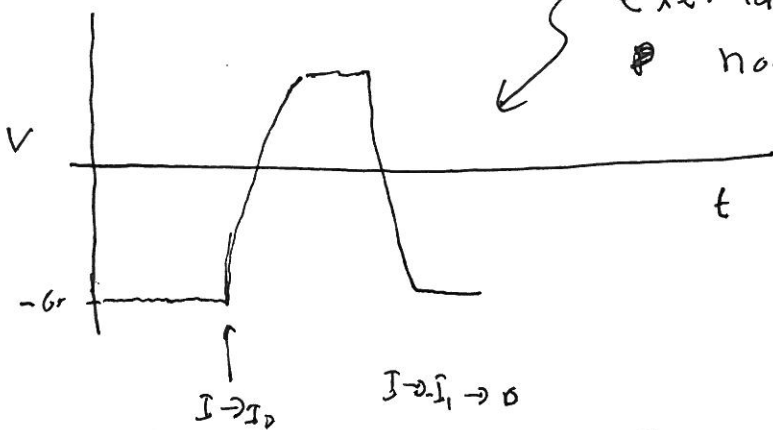
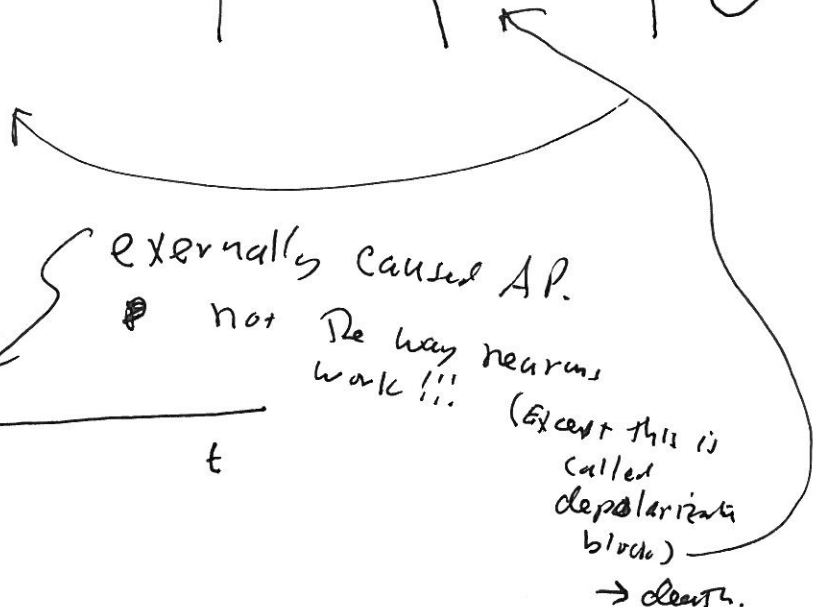
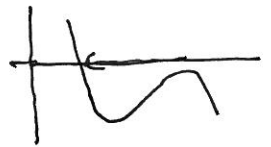
$I = 0$



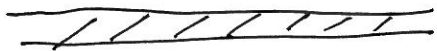
$I \rightarrow I_0$



$I \rightarrow -I_1$



externally caused AP.
 not the way neurons work!!!
 (except this is called depolarization block)
 → death.



Approx. #1 was a good idea, but it didn't work!!

- that "explains" why $J \sim J_m, J_h, J_n \dots$

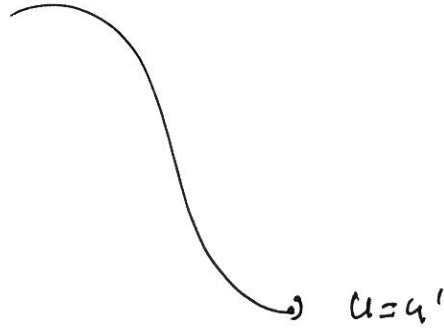
(9)

Approx. # 2:

$$m = m_{\infty}(v)$$

$$h = h_{\infty}(u)$$

$$n \approx n_{\infty}(u')$$



$$\frac{dh}{dt} = \frac{1}{\tau_h} (h_{\infty}(v) - h) = \frac{dh_{\infty}(u)}{du} \frac{du}{dt}$$

$$\frac{du}{dt} = \frac{\frac{h_{\infty}(v) - h_{\infty}(u)}{\tau_h(v)}}{\frac{dh_{\infty}(u)}{du}} \xrightarrow{v = u + v - u} \frac{v - u}{\tau_h(v)}$$

$$\frac{du'}{dt} = \frac{\frac{n_{\infty}(v) - n_{\infty}(u')}{\tau_n(v)}}{\frac{dn_{\infty}(u')}{du'}} \longrightarrow \frac{v - u'}{\tau_n(v)}$$

u, u' relax toward v w/ given time constants $\tau_h(v), \tau_n(v)$.

$$\frac{d}{dt}(u - u') = \frac{v}{\tau_h} - \frac{v}{\tau_n} - \left(\frac{u}{\tau_h} - \frac{u'}{\tau_n} \right)$$

OK APP

(10)

$$\gamma \frac{dv}{dt} = F(V, m_\Delta(v), h_\Delta(u), n_\Delta(u)) + \mathbb{I}$$

$F_{\text{true}}(v, m_\Delta(v), h, n) \leftarrow \text{true}$

~~Kepler~~ Abbott & Kepler:

$$\left. \frac{dF_{\text{true}}}{dt} \right|_{v, u, i} = \left. \frac{dF}{dt} \right|_{v, u, i}$$

$n = h_\Delta,$
 $v = v_\Delta$

$$= \frac{\partial F}{\partial h} \frac{dh}{dt} + \frac{\partial F}{\partial n} \frac{dn}{dt} = \left[\frac{\partial F}{\partial h_\Delta} \frac{dh_\Delta}{dt} + \frac{\partial F}{\partial n_\Delta} \frac{dn_\Delta}{dt} \right] \frac{du}{dt}$$

$$\frac{du}{dt} = \frac{\frac{\partial F}{\partial h_\Delta(u)} \frac{h_\Delta(v) - h_\Delta(u)}{T_h(v)} + \frac{\partial F}{\partial n_\Delta(u)} \frac{n_\Delta(v) - n_\Delta(u)}{T_n(v)}}{\frac{\partial F}{\partial h_\Delta} \frac{dh_\Delta}{dt} + \frac{\partial F}{\partial n_\Delta} \frac{dn_\Delta}{dt}}$$

$$\frac{du}{dt} = g(v, u)$$

(11)

$$T \frac{dv}{dt} = f(v, u) + I$$

$$\frac{du}{dt} = g(v, u)$$

$g(v, 0) = 0$ $v = u$ is equilibrium.

//////

Nullcline analysis:

1st question: what are the fixed points???

$$\frac{dv}{dt} = \frac{du}{dt} = 0$$

nullclines:

$$\frac{dv}{dt} = 0$$

$$\frac{du}{dt} = 0$$

}

define curves
in 2-D space;
intersections are fixed
points.

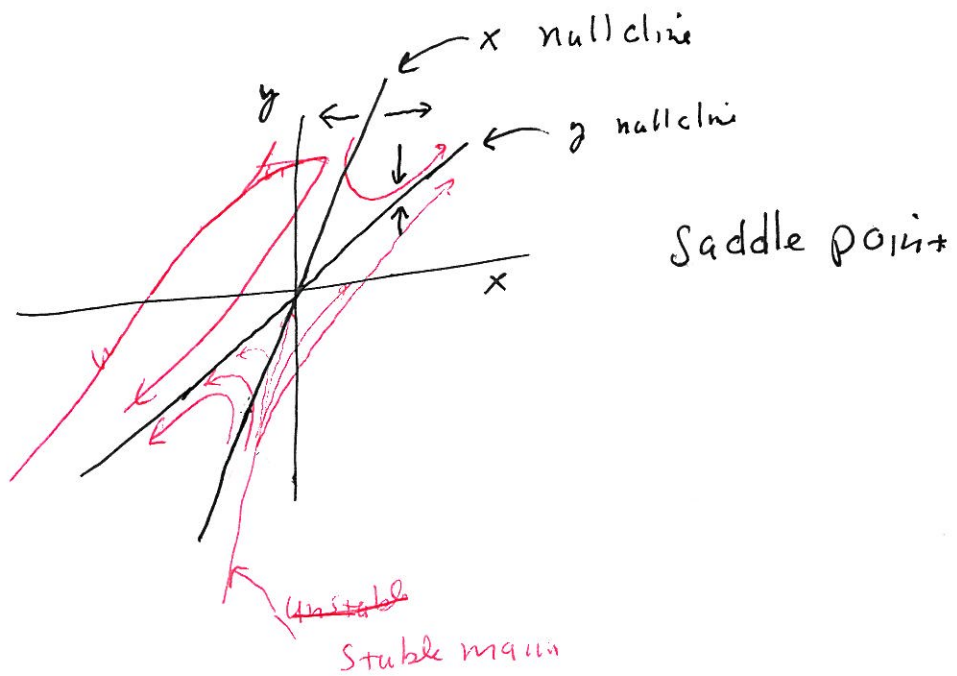
Example

$$\frac{dx}{dt} = ax - by$$

$$\frac{dy}{dt} = cx - dy$$

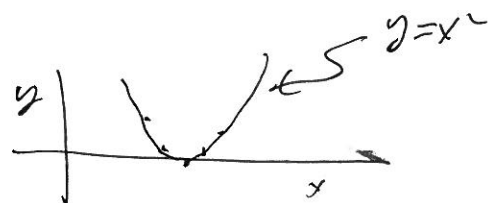
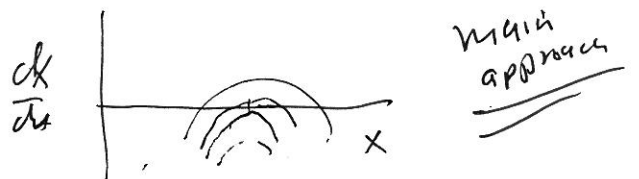
$$\frac{dx}{dt} = 0 \Rightarrow y = \frac{a}{b} x$$

$$\frac{dy}{dt} = 0 \Rightarrow y = \frac{c}{d} x$$

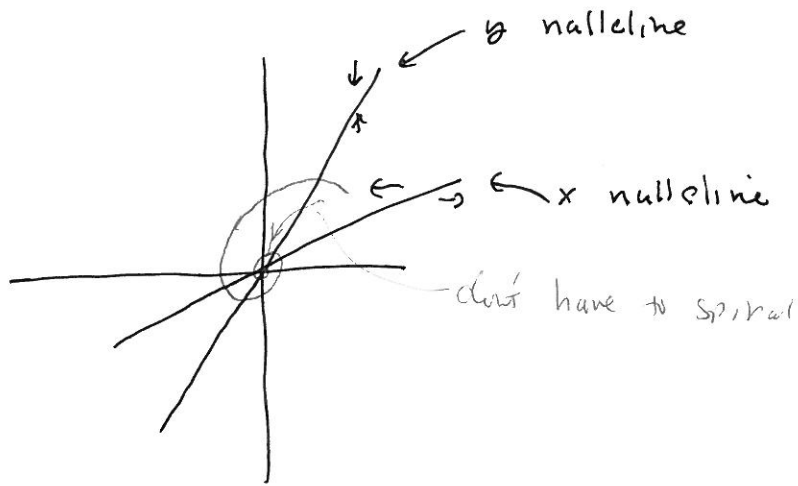


$$\frac{dx}{dt} = y - x^2$$

$$\frac{dy}{dt} = x - y$$

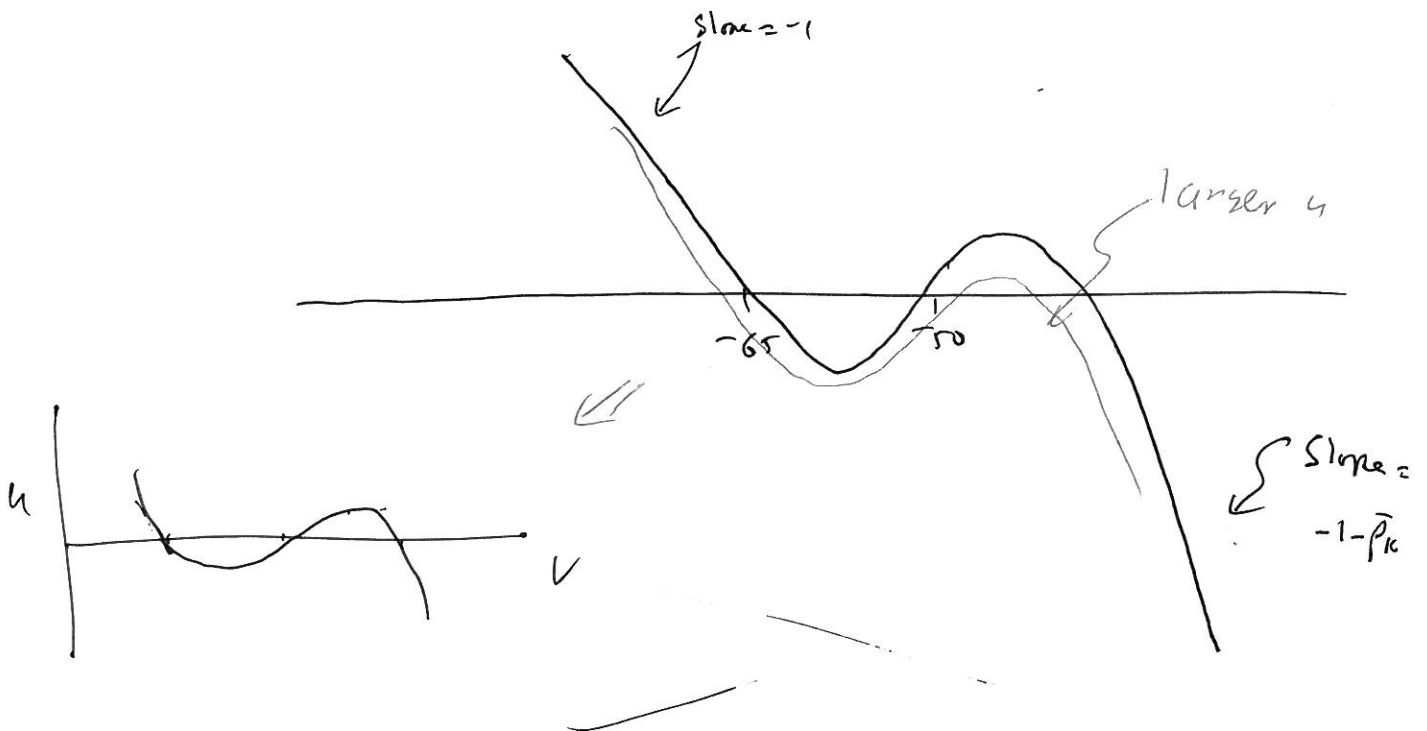


(13)



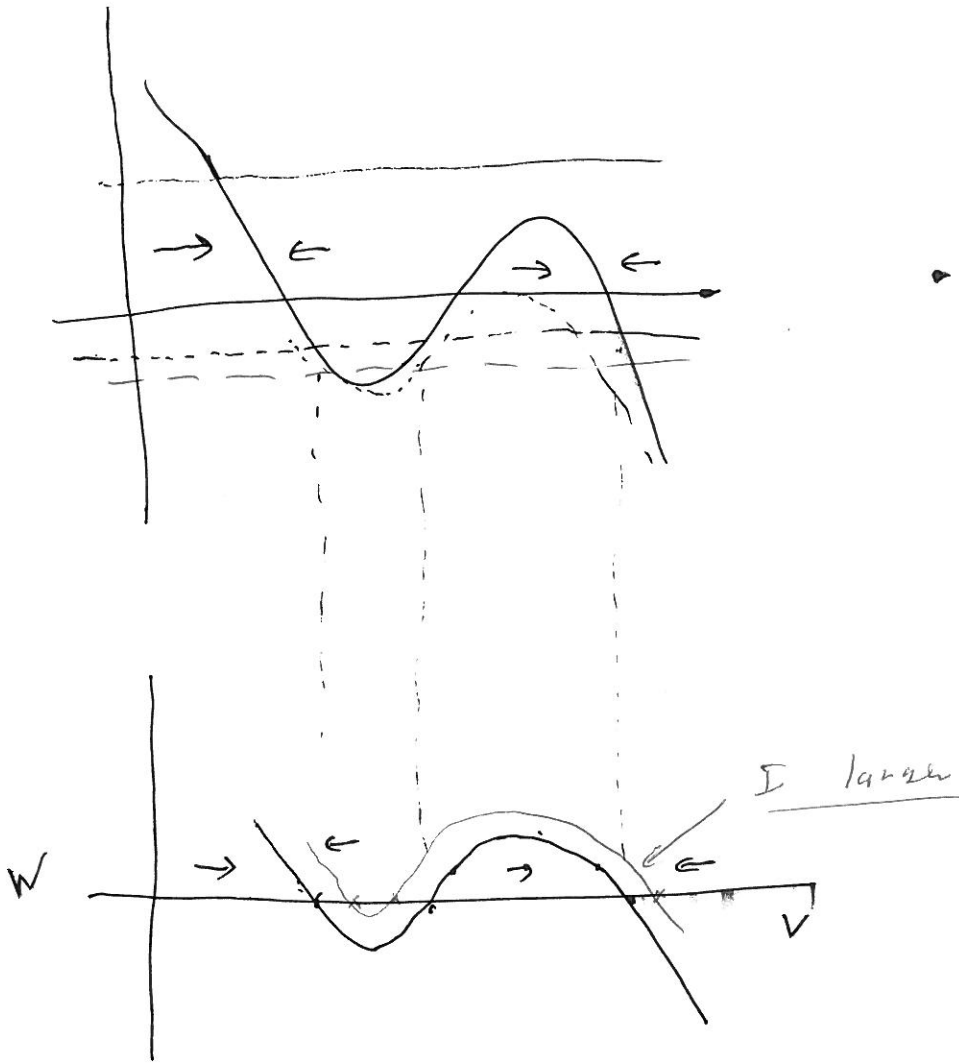
What does $f(v, u)$ look like?

$$f(v, u) = -(v - \Sigma_L) - \bar{\rho}_{w_a} M_{\infty}^3(v) h_{\infty}(u) (v - \Sigma_{w_a}) - \bar{\rho}_{i_c} M_{\infty}^4(u) (v - \Sigma_{i_c})$$



(14)

$$\frac{dv}{dt} = 0 \Rightarrow f(v, w) \stackrel{+}{=} I = 0$$



(15)

FitzHugh - Nagumo:

$$\dot{V} = V - \frac{V^3}{3} - w + I$$

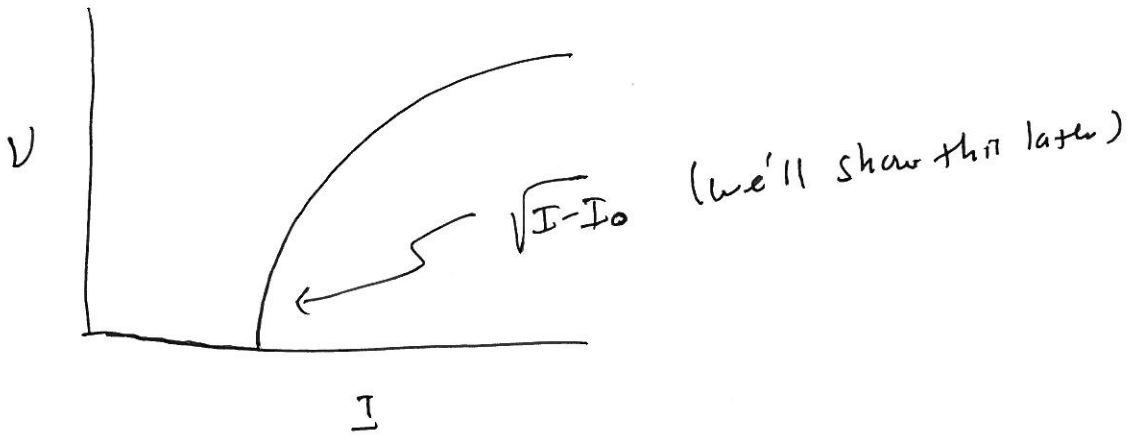
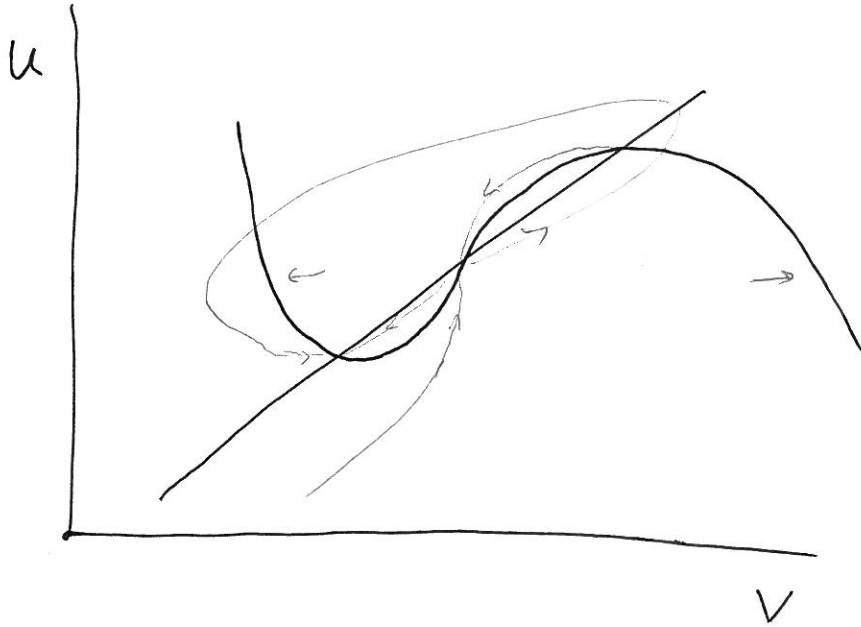
$$\dot{w} = \phi(V + a - bw)$$

Morris - Lecar

$$C_m \frac{dv}{dt} = - \left[\bar{g}_{Ca} M_\infty(v) (v - E_{Ca}) + \bar{g}_{K} w (v - E_{K}) \right] - \bar{g}_L (v - E_L) + I$$

$$J_w(v) \frac{dw}{dt} = \frac{w_\infty(v) - w}{J_w(v)}$$

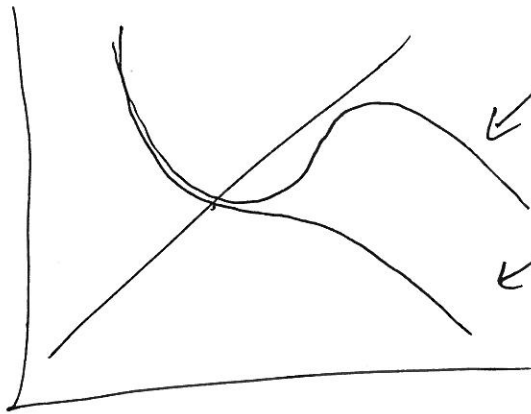
15



Type I!!

all-or-none

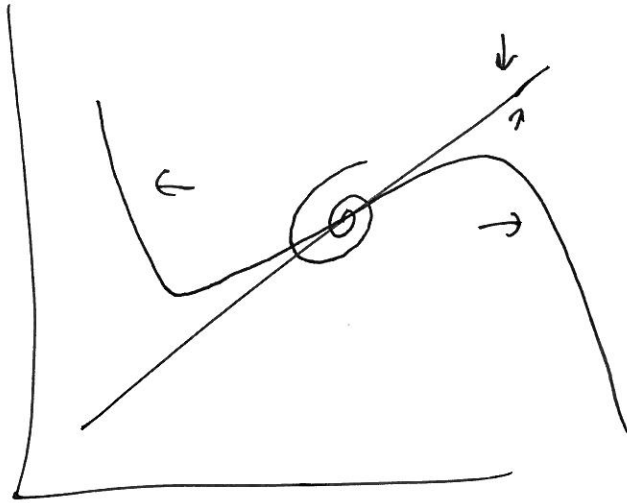
(17)



not enough
 Na^{++} channels -

no spikes!!!
(at least no
all-or-none)

18



Hopf - eigenvalues - subcritical

