

Top-down particle filtering for Bayesian decision trees

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Outline

Introduction

Sequential prior over decision trees

Bayesian inference: Top-down particle filtering

Experiments

- Design choices in the SMC algorithm

- SMC vs MCMC

Conclusion

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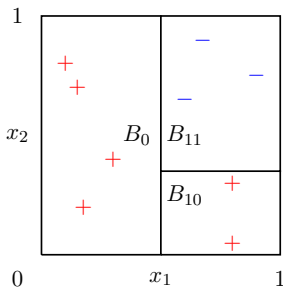
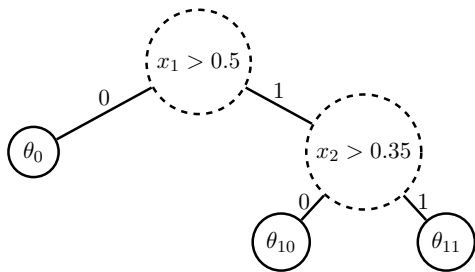
Introduction

- ▶ **Input:** attributes $X = \{x_i\}_{i=1}^N$, labels $Y = \{y_i\}_{i=1}^N$ (i.i.d)
- ▶ $y_i \in \{1, \dots, K\}$ (classification) or $y_i \in \mathbb{R}$ (regression)
- ▶ **Goal:** Model $p(y|x)$

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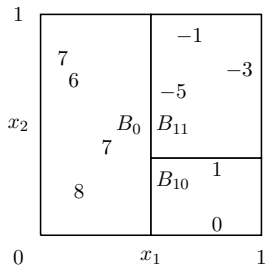
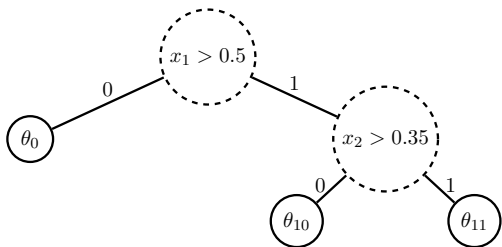
- ▶ **Input:** attributes $X = \{x_i\}_{i=1}^N$, labels $Y = \{y_i\}_{i=1}^N$ (i.i.d)
- ▶ $y_i \in \{1, \dots, K\}$ (classification) or $y_i \in \mathbb{R}$ (regression)
- ▶ **Goal:** Model $p(y|x)$
- ▶ Assume $p(y|x)$ is specified by decision tree \mathcal{T}
- ▶ **Bayesian decision trees:**
 - ▶ Posterior: $p(\mathcal{T}|Y, X) \propto \underbrace{p(Y|\mathcal{T}, X)}_{\text{likelihood}} \underbrace{p(\mathcal{T}|X)}_{\text{prior}}$
 - ▶ Prediction: $p(y_*|x_*) = \sum_{\mathcal{T}} p(\mathcal{T}|Y, X) p(y_*|x_*, \mathcal{T})$

Example: Classification tree



θ : Multinomial parameters at leaf nodes

Example: Regression tree



θ : Gaussian parameters at leaf nodes

Motivation

- ▶ Classic non-Bayesian induction algorithms (e.g. CART) learn a single tree in a top-down manner using greedy heuristics (post-pruning and/or bagging necessary)
- ▶ MCMC for Bayesian decision trees: [Chipman et al., 1998]: local Monte Carlo modifications to the tree structure (less prone to over fitting but slow to mix)
- ▶ **Our contribution:** Sequential Monte Carlo (SMC) algorithm that approximates the posterior, in a top-down manner
- ▶ **Take home message:** SMC provides better computation vs predictive performance tradeoff than MCMC

Bayesian decision trees: likelihood

$$p(\mathcal{T}|Y, X) \propto \underbrace{p(Y|\mathcal{T}, X)}_{\text{likelihood}} \underbrace{p(\mathcal{T}|X)}_{\text{prior}}$$

Likelihood

- ▶ Assume x_n falls in the j^{th} leaf node of \mathcal{T}
- ▶ Likelihood for n^{th} data point: $p(y_n | x_n, \mathcal{T}, \theta) = p(y_n | \theta_j, x_n)$

$$p(Y | \mathcal{T}, X, \Theta) = \prod_n p(y_n | x_n, \mathcal{T}, \theta) = \prod_{j \in \text{leaves}(\mathcal{T})} \prod_{n \in N(j)} p(y_n | \theta_j)$$

Likelihood

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$$p(Y | \mathcal{T}, X, \Theta) = \prod_n p(y_n | x_n, \mathcal{T}, \theta) = \prod_{j \in \text{leaves}(\mathcal{T})} \prod_{n \in N(j)} p(y_n | \theta_j)$$

- ▶ Better: integrate out θ_j , use marginal likelihood

$$p(Y | \mathcal{T}, X) = \prod_{j \in \text{leaves}(\mathcal{T})} \int_{\theta_j} \prod_{n \in N(j)} p(y_n | \theta_j) p(\theta_j) d\theta_j$$

- ▶ Classification: Dirichlet - Multinomial
- ▶ Regression: Normal - Normal Inverse Gamma

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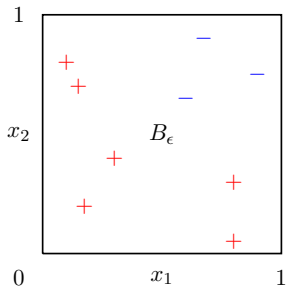
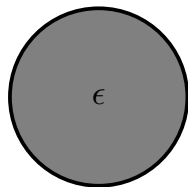
Conclusion

Bayesian decision trees: prior

$$p(T|Y, X) \propto \underbrace{p(Y|T, X)}_{\text{likelihood}} \underbrace{p(T|X)}_{\text{prior}}$$

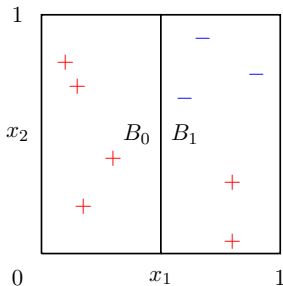
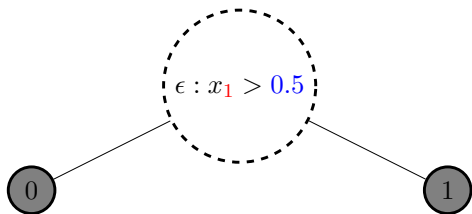
Partial trees

0. Start with empty tree.



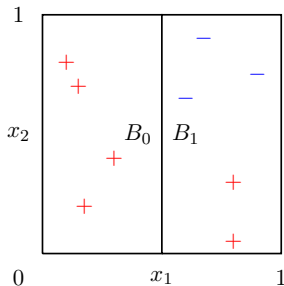
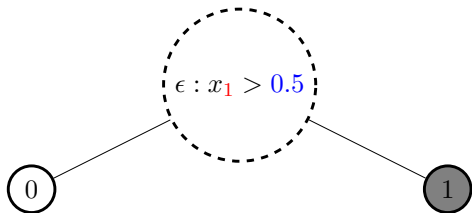
Partial trees

1. Choose to split root node with feature 1 and threshold 0.5.



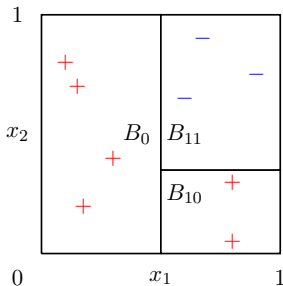
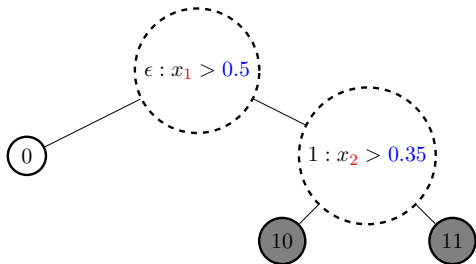
Partial trees

2. Choose to not split node 0.



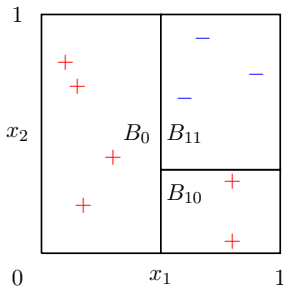
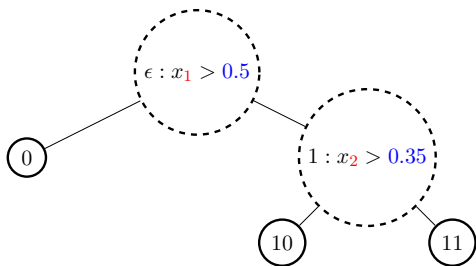
Partial trees

3. Choose to split node 1 with with feature 2 and threshold 0.35.

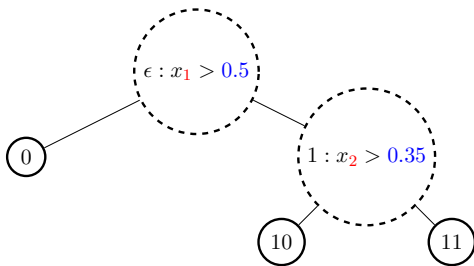


Partial trees

4. Choose to not split node 10.
5. Choose to not split node 11.



Sequence of random variables for a tree



1. $\rho_\epsilon = 1, \kappa_\epsilon = 1, \tau_\epsilon = 0.5$
2. $\rho_0 = 0$
3. $\rho_1 = 1, \kappa_1 = 2, \tau_1 = 0.35$
4. $\rho_{10} = 0$
5. $\rho_{11} = 0$

Sequential prior over decision trees

- ▶ Probability of split (assuming a valid split exists):

$$p(\text{j split}) = \alpha_s \cdot \left(1 + \text{depth}(j)\right)^{-\beta_s} \quad \alpha_s \in (0, 1), \beta_s \in [0, \infty)$$

- ▶ κ_j, τ_j sampled uniformly from the range of valid splits

Sequential prior over decision trees

- ▶ Probability of split (assuming a valid split exists):

$$p(j \text{ split}) = \alpha_s \cdot \left(1 + \text{depth}(j)\right)^{-\beta_s} \quad \alpha_s \in (0, 1), \beta_s \in [0, \infty)$$

- ▶ κ_j, τ_j sampled uniformly from the range of valid splits
- ▶ Prior distribution:

$$\begin{aligned} p(T, \kappa, \tau | X) &= \prod_{j \in \text{leaves}(T)} p(j \text{ not split}) \\ &\quad \times \prod_{j \in \text{nonleaves}(T)} p(j \text{ split}) p(\kappa_j, \tau_j) \end{aligned}$$

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Bayesian decision trees: posterior

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SMC algorithm for Bayesian decision trees

- ▶ Importance sampler: Draw $\mathcal{T}^{(c)} \sim q(\cdot)$

$$p(Y|X) = \sum_{\mathcal{T}} p(Y, \mathcal{T}|X) \approx \sum_{c=1}^C \underbrace{\frac{1}{C} \frac{p(\mathcal{T}^{(c)})}{q(\mathcal{T}^{(c)})} p(Y|X, \mathcal{T}^{(c)})}_{w^{(c)}}$$

SMC algorithm for Bayesian decision trees

- ▶ Importance sampler: Draw $\mathcal{T}^{(c)} \sim q(\cdot)$

$$p(Y|X) = \sum_{\mathcal{T}} p(Y, \mathcal{T}|X) \approx \sum_{c=1}^C \frac{1}{C} \underbrace{\frac{p(\mathcal{T}^{(c)})}{q(\mathcal{T}^{(c)})} p(Y|X, \mathcal{T}^{(c)})}_{w^{(c)}}$$

- ▶ Normalize: $\bar{w}^{(c)} = \frac{w^{(c)}}{\sum_{c'} w^{(c')}}$
- ▶ Approximate posterior:

$$p(\mathcal{T}|Y, X) \approx \sum_c \bar{w}^{(c)} \delta(\mathcal{T} = \mathcal{T}^{(c)})$$

SMC algorithm for Bayesian decision trees (contd.)

- ▶ Sequential importance sampler (SIS):

$$p(\mathcal{T}_n) = p(\mathcal{T}_0) \prod_{n'=1}^n p(\mathcal{T}_{n'} | \mathcal{T}_{n'-1}) \quad q(\mathcal{T}_n) = q_0(\mathcal{T}_0) \prod_{n'=1}^n q_{n'}(\mathcal{T}_{n'} | \mathcal{T}_{n'-1})$$
$$p(Y|X, \mathcal{T}_n) = \cancel{p(Y|X, \mathcal{T}_0)} \frac{p(Y|X, \mathcal{T}_1)}{\cancel{p(Y|X, \mathcal{T}_0)}} \dots \frac{p(Y|X, \mathcal{T}_n)}{\cancel{p(Y|X, \mathcal{T}_{n-1})}}$$

SMC algorithm for Bayesian decision trees (contd.)

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$$p(\mathcal{T}_n) = p(\mathcal{T}_0) \prod_{n'=1}^n p(\mathcal{T}_{n'} | \mathcal{T}_{n'-1}) \quad q(\mathcal{T}_n) = q_0(\mathcal{T}_0) \prod_{n'=1}^n q_{n'}(\mathcal{T}_{n'} | \mathcal{T}_{n'-1})$$

$$p(Y|X, \mathcal{T}_n) = \frac{p(Y|X, \mathcal{T}_0) \cancel{p(Y|X, \mathcal{T}_1)}}{\cancel{p(Y|X, \mathcal{T}_0)}} \cdots \frac{p(Y|X, \mathcal{T}_n)}{\cancel{p(Y|X, \mathcal{T}_{n-1})}}$$

$$\begin{aligned} w &= \frac{1}{C} \frac{p(\mathcal{T}_n)}{q(\mathcal{T}_n)} p(Y|X, \mathcal{T}_n) \\ &= w_0 \prod_{n'=1}^n \frac{p(\mathcal{T}_{n'} | \mathcal{T}_{n'-1})}{q_{n'}(\mathcal{T}_{n'} | \mathcal{T}_{n'-1})} \underbrace{\frac{p(Y|X, \mathcal{T}_{n'})}{p(Y|X, \mathcal{T}_{n'-1})}}_{\text{local likelihood}} \end{aligned}$$

- ▶ Sequential Monte Carlo (SMC): SIS + adaptive resampling steps
- ▶ Every node is processed just once: no **multi-path** issues

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Experimental setup

- ▶ Datasets:
 - ▶ *magic-04*: $N = 19K$, $D = 10$, $K = 2$.
 - ▶ *pendigits*: $N = 11K$, $D = 16$, $K = 10$.
- ▶ 70% - 30% train-test split
- ▶ Numbers averaged across 10 different initializations

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SMC design choices

- ▶ Proposals

- ▶ *prior* proposal: $q_n(\rho_j, \kappa_j, \tau_j) = p(\rho_j, \kappa_j, \tau_j)$
- ▶ *optimal* proposal:

$$\begin{aligned} q_n(\rho_j = \text{stop}) &\propto p(\text{j not split})p(Y_{N(j)}|X_{N(j)}), \\ q_n(\rho_j = \text{split}, \kappa_j, \tau_j) &\propto p(\text{j split})p(\kappa_j, \tau_j) \\ &\quad \times \underbrace{p(Y_{N(j0)}|X_{N(j0)})}_{\text{left child}} \underbrace{p(Y_{N(j1)}|X_{N(j1)})}_{\text{right child}}. \end{aligned}$$

- ▶ Set of nodes considered for expansion at iteration n
 - ▶ *node-wise*: next node
 - ▶ *layer-wise*: all nodes at depth n
- ▶ Multinomial resampling

Effect of SMC design choices

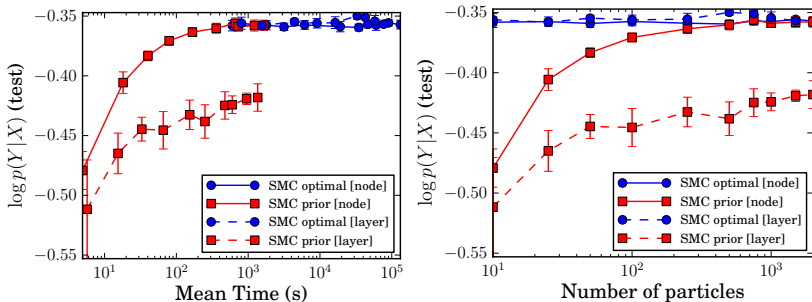


Figure: Results on *magic-04* dataset

Effect of irrelevant features on SMC design choices

madelon: $N = 2.6K$, $D = 500$, $K = 2$

(96% of the features are irrelevant)

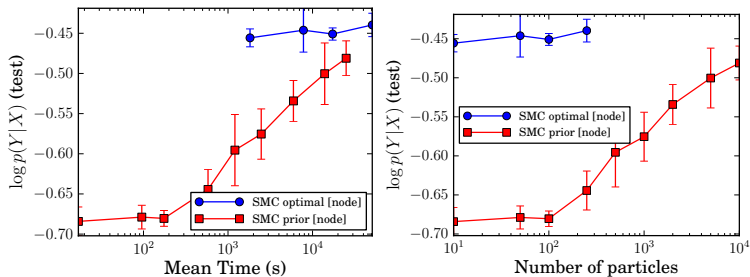


Figure: Results on *madelon* dataset

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Predictive performance vs computation: SMC vs MCMC

- ▶ Fix hyper parameters $\alpha = 5, \alpha_s = 0.95, \beta_s = 0.5$
- ▶ MCMC [Chipman et al., 1998]: one of the 4 proposals:
 - ▶ *grow*
 - ▶ *prune*
 - ▶ *change*
 - ▶ *swap*
- ▶ MCMC averages predictions over all previous trees
- ▶ Vary number of particles in SMC, number of MCMC iterations and compare runtime vs performance

Predictive performance vs computation: SMC vs MCMC

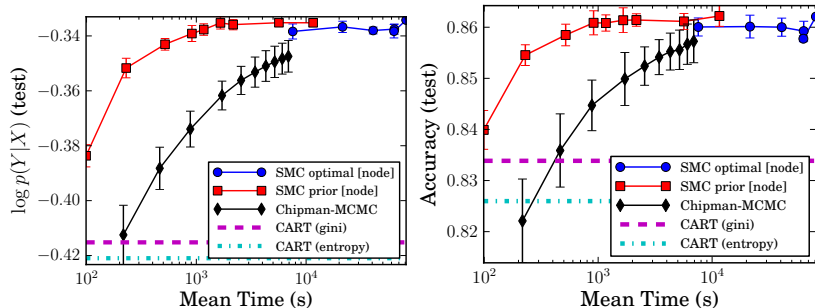


Figure: Results on *magic-04* dataset

Take home message

SMC (*prior, node-wise*) is **at least an order of magnitude faster** than MCMC

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- ▶ SMC for fast Bayesian inference for decision trees
 - ▶ mimic the top-down generative process of decision trees
 - ▶ use 'local' likelihoods + resampling steps to guide tree growth
 - ▶ For a fixed computational budget, SMC outperforms MCMC

Conclusion

- ▶ SMC for fast Bayesian inference for decision trees
 - ▶ mimic the top-down generative process of decision trees
 - ▶ use 'local' likelihoods + resampling steps to guide tree growth
 - ▶ For a fixed computational budget, SMC outperforms MCMC
- ▶ Future directions
 - ▶ Particle-MCMC for Bayesian Additive Regression Trees
 - ▶ Mondrian process prior: projective and exchangeable prior for decision trees [Roy and Teh, 2009]

Thank you!

Code available at

<http://www.gatsby.ucl.ac.uk/~balaji>



Chipman, H. A., George, E. I., and McCulloch, R. E. (1998).
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