

# Bayesian Approaches to Distribution Regression

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## Distribution regression

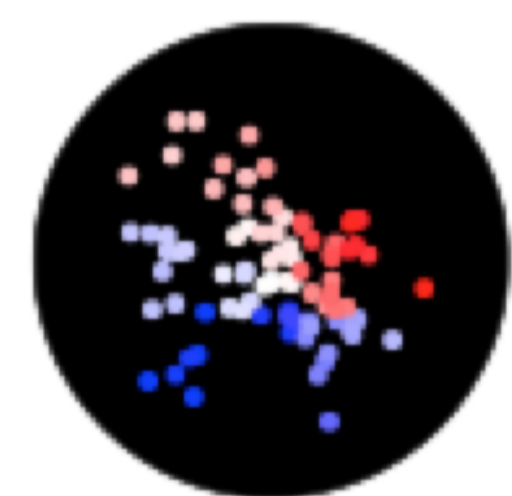
Inputs are sample sets from distributions [e.g. 7]:

$$y_i = f^*(\mathbb{P}_i) + \varepsilon \quad \mathbf{X}_i \stackrel{iid}{\sim} \mathbb{P}_i \quad \hat{y}_i = f(\mathbf{X}_i)$$

Examples:

$\mathbb{P}_i$	$\mathbf{X}_i$	$y_i$																				
Multivariate distribution [7]	Sample from distribution	Entropy of a projection																				
Demographics of county population [2, 3]	<table border="1"> <thead> <tr> <th>AGEP</th> <th>SEX</th> <th>PINCP</th> <th>WKHP</th> </tr> </thead> <tbody> <tr> <td>45</td> <td>2</td> <td>14418.0</td> <td>30.0</td> </tr> <tr> <td>37</td> <td>1</td> <td>120152.0</td> <td>40.0</td> </tr> <tr> <td>63</td> <td>1</td> <td>11314.0</td> <td>NaN</td> </tr> <tr> <td>38</td> <td>2</td> <td>73092.0</td> <td>40.0</td> </tr> </tbody> </table>	AGEP	SEX	PINCP	WKHP	45	2	14418.0	30.0	37	1	120152.0	40.0	63	1	11314.0	NaN	38	2	73092.0	40.0	30.3% Clinton 9.9% Trump 59.8% none/other
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Galaxy velocities in a cluster [4, 5]



Cluster mass:  
 $7 \times 10^{14} M_{\odot}$

## Standard approach [e.g. 7]

- Kernel mean embeddings: kernel  $k$ , RKHS  $\mathcal{H}$ ,

$$\mu_{\mathbb{P}} = \mathbb{E}_{X \sim \mathbb{P}} [k(\cdot, X)] \in \mathcal{H}$$

- $\mu_{\mathbb{P}}$  fully characterizes  $\mathbb{P}$  for many  $k$

- Empirical mean estimator:

$$\hat{\mu}_{\mathbb{P}} = \frac{1}{N} \sum_{j=1}^N k(\cdot, X^{(j)})$$

- Ridge regression from  $\hat{\mu}_{\mathbb{P}}$  to  $y_i$ :

$$\begin{aligned} f(\hat{\mu}_{\text{test}}) &= \sum_{i=1}^n \alpha_i \langle \hat{\mu}_{\text{test}}, \hat{\mu}_i \rangle_{\mathcal{H}} \\ &= \sum_{i=1}^n \alpha_i \sum_{j=1}^{N_{\text{test}}} \sum_{j'=1}^{N_i} k(X_j^{\text{test}}, X_{j'}^i) \end{aligned}$$

- We make a landmark approximation (RBF net):

$$f(\hat{\mu}) = \beta^{\top} \hat{\mu}(\mathbf{u}) = \sum_{\ell=1}^s \beta_{\ell} \hat{\mu}(u_{\ell})$$

## Sources of uncertainty

- Uncertainty about regression weights  $\alpha$
- Mean embeddings  $\mu_i$  not seen exactly
  - Should “trust” points with small  $N_i$  less

## Bayesian linear regression

- Standard BLR model (similar to e.g. [3])
  - Handles regression weight  $\beta$  uncertainty
  - Assumes  $\hat{\mu}_i$  known exactly
- Normal prior over regression weights  $\beta \sim \mathcal{N}(0, \rho^2)$
- Observations  $y_i \mid \mathbf{X}_i, \beta \sim \mathcal{N}(\beta^{\top} \hat{\mu}_i(\mathbf{u}), \sigma^2)$
- Gives normal  $y_i \mid \mathbf{X}_i$  with hyperparameters  $\sigma, \rho$

## Shrinkage

- New model
  - Handles  $\hat{\mu}_i$  uncertainty
  - Point estimate for  $\beta$  to retain conjugacy
- Uses Bayesian nonparametric model for  $\hat{\mu}_i$  [1]:

- Prior:  $\mu_i \sim \mathcal{GP}(m_0, \eta r(\cdot, \cdot))$

- Likelihood: “observed” at points  $\mathbf{u}$ , CLT:

$$\hat{\mu}_i(\mathbf{u}) \mid \mu_i(\mathbf{u}) \sim \mathcal{N}(\mu_i(\mathbf{u}), \Sigma_i)$$

- Closed-form GP posterior for  $\hat{\mu}_i \mid \mathbf{X}_i$
- Similar to James-Stein shrinkage

- Observations  $y_i \mid \mu_i, f \sim \mathcal{N}(\langle f, \mu_i \rangle_{\mathcal{H}}, \sigma^2)$

- Say  $f(\cdot) = \sum_{\ell=1}^s \alpha_{\ell} k(\cdot, z_{\ell})$  (representer theorem)

- Predictive:  $y_i \mid \mathbf{X}_i, \alpha, \mathbf{z} \sim \mathcal{N}(\xi_i^{\alpha}, \nu_i^{\alpha})$

$$\xi_i^{\alpha} = \alpha^{\top} R_{\mathbf{z}} \left( R + \frac{\Sigma_i}{N_i} \right)^{-1} (\hat{\mu}_i - m_0) + \alpha^{\top} m_0$$

$$\nu_i^{\alpha} = \alpha^{\top} \left( R_{\mathbf{z}\mathbf{z}} - R_{\mathbf{z}} \left( R + \frac{\Sigma_i}{N_i} \right)^{-1} R_{\mathbf{z}}^{\top} \right) \alpha + \sigma^2$$

- MAP estimate for  $\alpha, \sigma$ , maybe  $\mathbf{z}$ , kernel params. . .

- Optimise with backprop (TensorFlow)

## Bayesian Distribution Regression

- Full uncertainty model (BDR)
  - Shrinkage posterior for  $\hat{\mu}_i$
  - BLR-like posterior for weights  $\alpha$
- Not conjugate
- MCMC for inference about  $\alpha$  (Stan)

## Results on synthetic data

- Toy problem to examine input uncertainty:
  - Labels  $y_i$  uniform over  $[4, 8]$
  - 5d data points:  $[x_j^i]_{\ell} \mid y_i \stackrel{iid}{\sim} \frac{1}{y_i} \Gamma\left(\frac{y_i}{2}, \frac{1}{2}\right)$
  - $(s_5, 25, 25, 100 - s_5)\%$  have  $N_i = (5, 20, 100, 1000)$
- BDR  $\approx$  shrinkage  $<$  BLR in NLL, MSE:

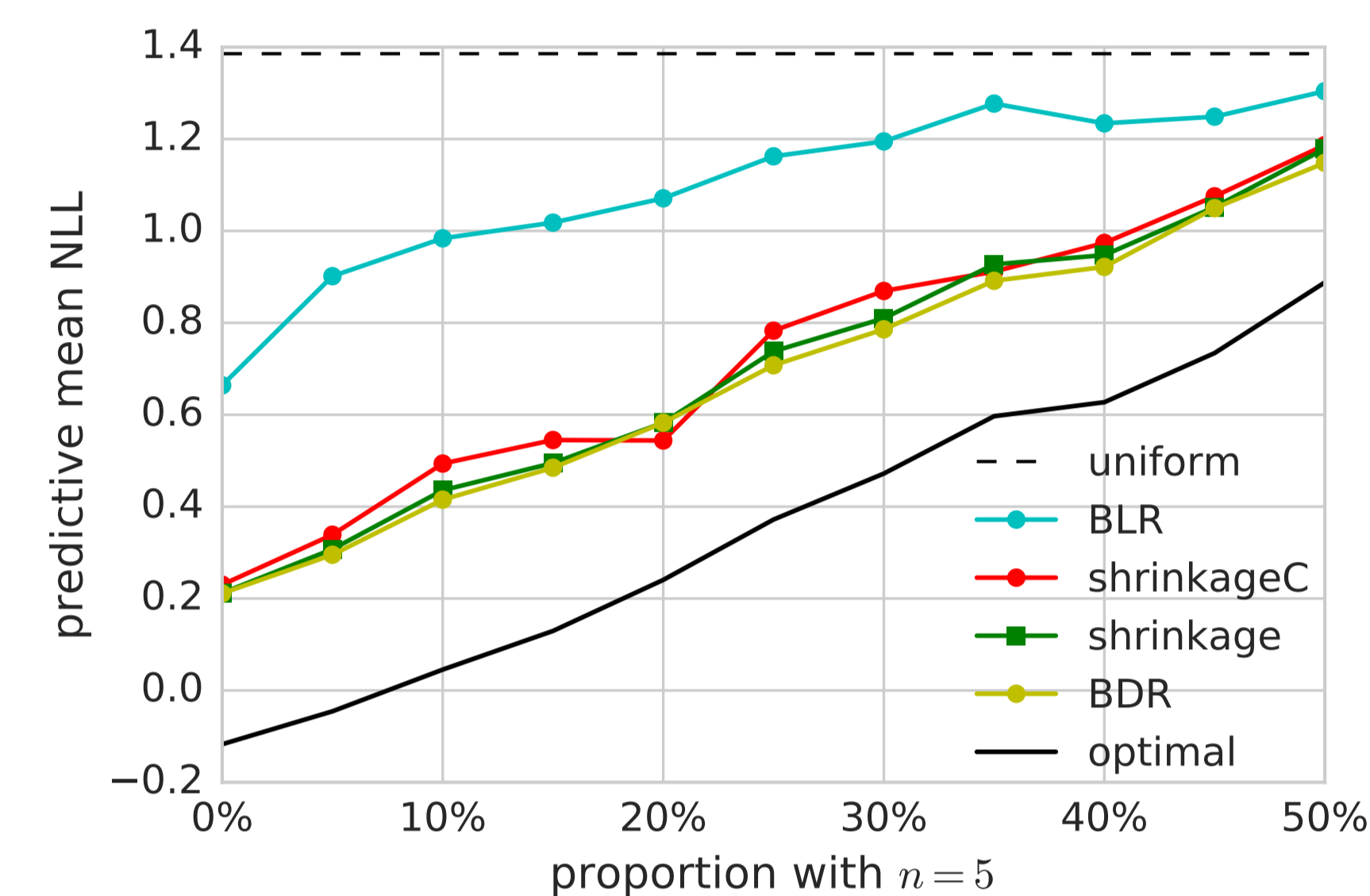


Figure: Negative log predictive likelihoods.

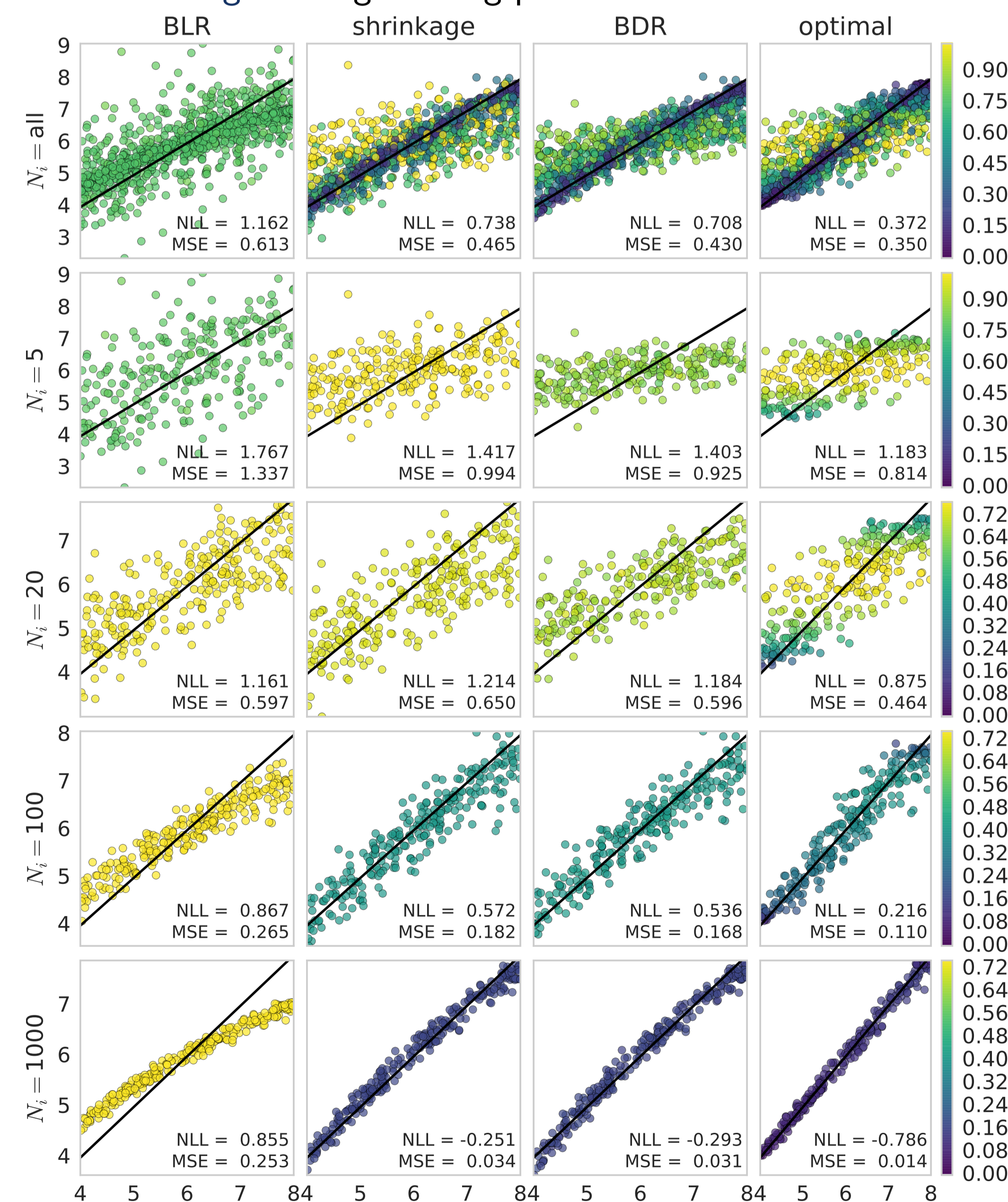
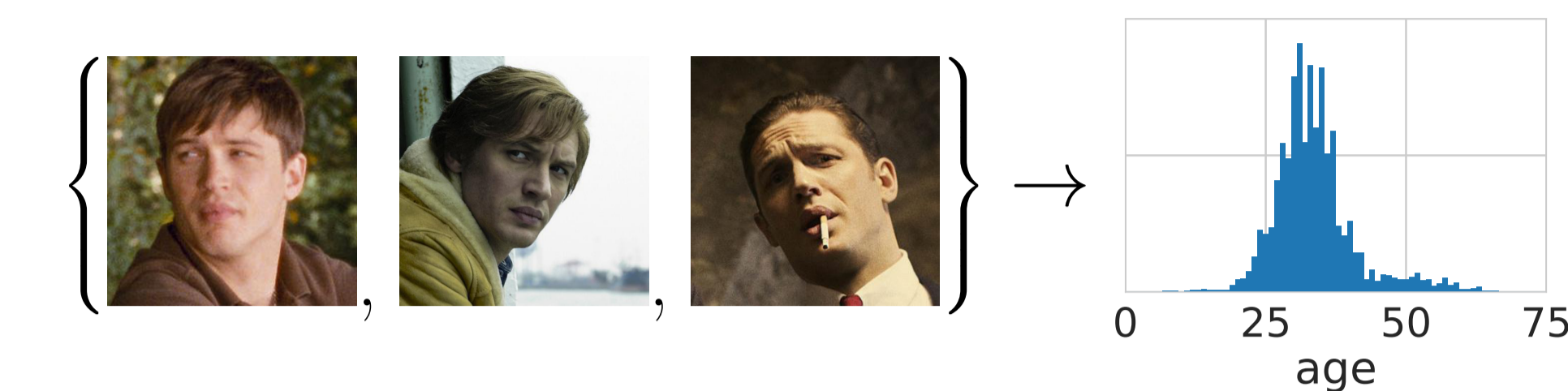


Figure: Bags are dots: horizontal position is true  $y_i$ , vertical is predictive mean, colour is predictive std.  $s_5 = 25$ .

- Similar experiment with constant  $N_i$ , added noise:
  - BDR  $\approx$  BLR  $<$  shrinkage in NLL, MSE
- BDR able to take advantage of both settings

## Age prediction from images



- IMDb database from [6]
  - Very noisy labels in the dataset
- Group pictures of actors, predict mean age
- Features: last hidden layer from [6]’s CNN
- Lots of variation in  $N_i$ :

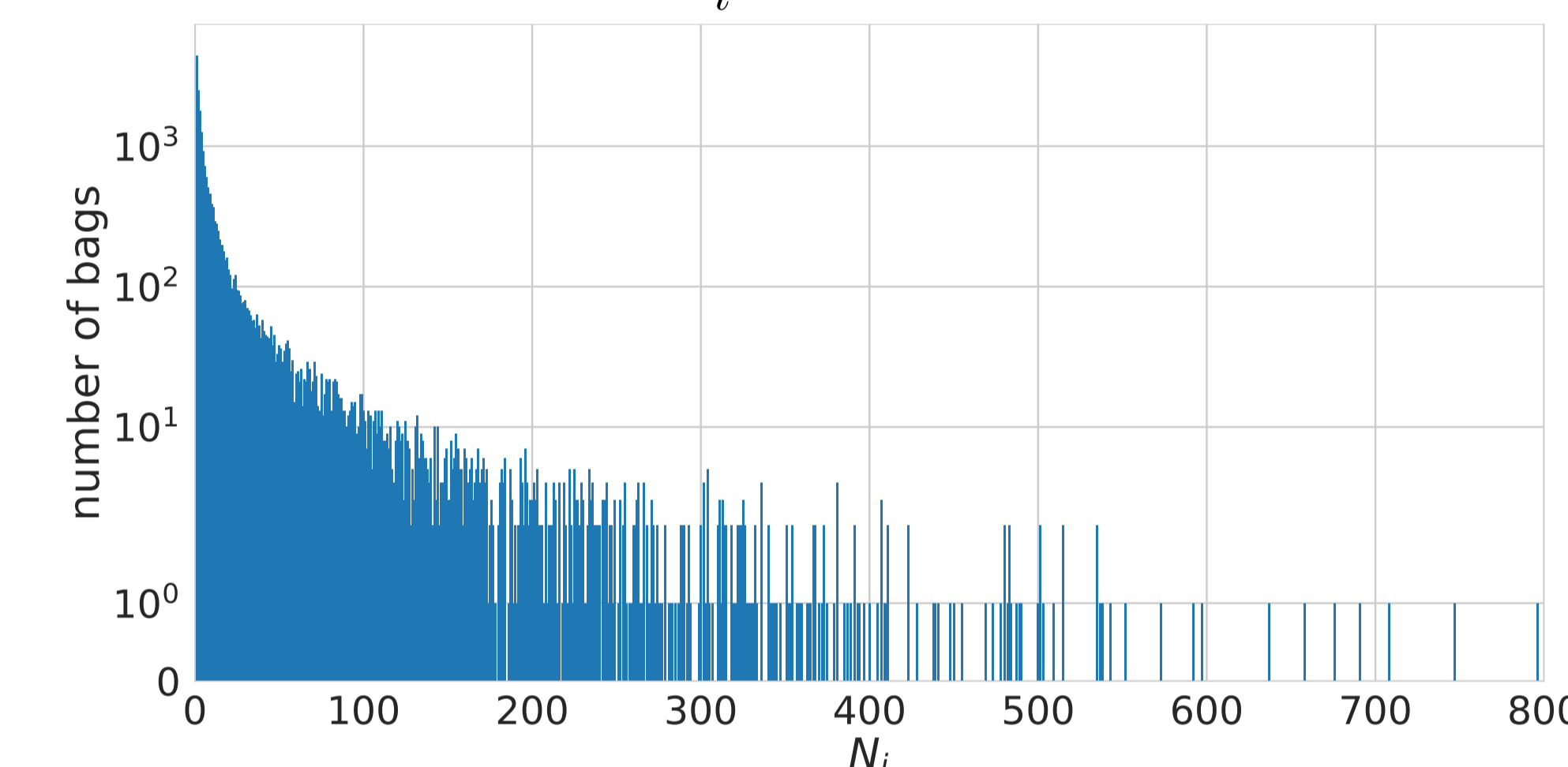


Figure: Histogram of  $N_i$ . 22% have  $N_i = 1$ .

- Shrinkage really helps!

Method	NLL	RMSE
CNN	3.80 (0.03)	10.25 (0.22)
RBF network	–	9.51 (0.20)
BLR	3.68 (0.02)	9.55 (0.19)
<b>shrinkage</b>	<b>3.54 (0.02)</b>	<b>9.28 (0.20)</b>

Table: Results across ten data splits (means and standard deviations). Here **shrinkage** performs the best across all 10 runs in both metrics. CNN takes the mean of the predictive distributions of [6].

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