## Introduction to Machine Learning: Kernels Part 2: Convex optimization, support vector machines

### Arthur Gretton

Gatsby Unit, CSML, UCL

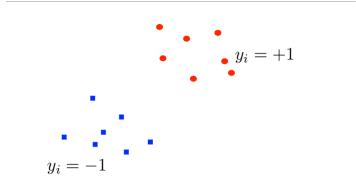
May 23, 2017

Arthur Gretton Introduction to Machine Learning: Kernels

- Review of convex optimization
- Support vector classification, the C-SV machine

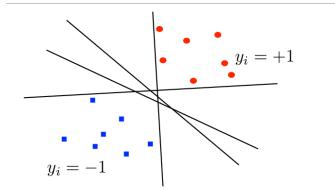
### Why we need optimization: SVM idea

Classify two clouds of points, where there exists a hyperplane which linearly separates one cloud from the other without error.



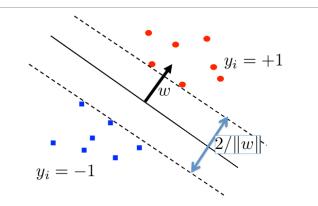
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## Why we need optimization: SVM idea

Classify two clouds of points, where there exists a hyperplane which linearly separates one cloud from the other without error.



Smallest distance from each class to the separating hyperplane  $w^{\top}x + b$  is called the margin.

This problem can be expressed as follows:

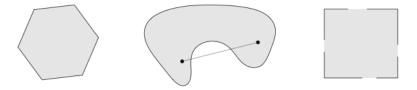
$$\max_{w,b} (\operatorname{margin}) = \max_{w,b} \left( \frac{2}{\|w\|} \right) \quad \text{or} \quad \min_{w,b} \|w\|^2 \tag{1}$$

subject to

$$\begin{cases} w^{\top} x_i + b \ge 1 & i : y_i = +1, \\ w^{\top} x_i + b \le -1 & i : y_i = -1. \end{cases}$$
(2)

This is a convex optimization problem.

Short overview of convex optimization



(Figure from Boyd and Vandenberghe)

Leftmost set is convex, remaining two are not.

Every point in the set can be seen from any other point in the set, along a straight line that never leaves the set.

### Definition

*C* is convex if for all  $x_1, x_2 \in C$  and any  $0 \leq \theta \leq 1$  we have  $\theta x_1 + (1 - \theta)x_2 \in C$ , i.e. every point on the line between  $x_1$  and  $x_2$  lies in *C*.

## Convex function: no local optima



(Figure from Boyd and Vandenberghe)

### Definition (Convex function)

A function f is convex if its domain domf is a convex set and if  $\forall x, y \in \text{dom} f$ , and any  $0 \le \theta \le 1$ ,

$$f( heta x + (1- heta)y) \leq heta f(x) + (1- heta)f(y).$$

The function is **strictly convex** if the inequality is strict for  $x \neq y$ .

Optimization problem on  $x \in \mathbb{R}^n$ ,

 $\begin{array}{ll} \text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \leq 0 & \qquad i=1,\ldots,m \end{array} \tag{3}$ 

### • $p^*$ the optimal value of (3)

Ideally we would want an unconstrained problem

minimize 
$$f_0(x) + \sum_{i=1}^m l_-(f_i(x))$$
,

where  $I_{-}(u) = \begin{cases} 0 & u \leq 0, \\ \infty & u > 0. \end{cases}$ Why is this hard to solve? Optimization problem on  $x \in \mathbb{R}^n$ ,

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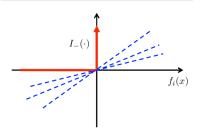
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Why is this hard to solve?

### Lower bound interpretation of Lagrangian

The Lagrangian  $L : \mathbb{R}^n \times \mathbb{R}^m \to \mathbb{R}$  is an (easier to optimize) lower bound on the original problem:

$$L(x,\lambda) := f_0(x) + \sum_{i=1}^m \underbrace{\lambda_i f_i(x)}_{\leq I_-(f_i(x))},$$

The  $\lambda_i$  are called **lagrange multipliers** or **dual variables**. To ensure a lower bound, we require  $\lambda \succeq 0$ .



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### Why bother?

- The original problem was very hard to solve (constraints). Minimizing the lower bound is easier (and can easily find the *closest* lower bound).
- Under "some conditions", the closest lower bound is tight: here minimum of L(x, λ) at true x\* corresponding to p\*.

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The Lagrange dual function: minimize Lagrangian When  $\lambda \succeq 0$  and  $f_i(x) \le 0$ , Lagrange dual function is

$$g(\lambda) := \inf_{x} L(x, \lambda).$$
(4)

We will show: (next slides) for any  $\lambda \succeq 0$ 

 $g(\lambda) \leq f_0(x)$ 

wherever

$$\begin{array}{ll} f_i(x) &\leq 0\\ g_i(x) &= 0 \end{array}$$

(including at  $f_0(x^*) = p^*$ ).

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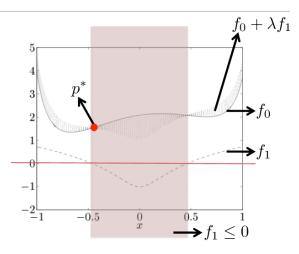
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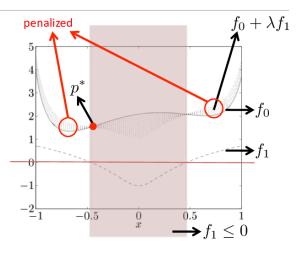
Simplest example: minimize over x the function  $L(x, \lambda) = f_0(x) + \lambda f_1(x)$ (Figure from Boyd and Vandenberghe)



#### Reminders:

- *f*<sub>0</sub> is function to be minimized.
- $f_1 \leq 0$  is inequality constraint
- $\lambda \ge 0$  is Lagrange multiplier
- *p*<sup>\*</sup> is minimum *f*<sub>0</sub> *in constraint set*

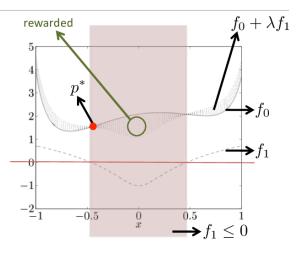
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Lagrange dual is lower bound on  $p^*$  (proof)

We now give a formal proof that Lagrange dual function  $g(\lambda, \nu)$  lower bounds  $p^*$ .

**Proof**: Define  $\tilde{x}$  as "some point" that is feasible, i.e.  $f_i(\tilde{x}) \leq 0$ ,  $\lambda \geq 0$ . Then

$$\sum_{i=1}^m \lambda_i f_i(\tilde{x}) \le 0$$

Thus

$$g(\lambda) := \inf_{x} \left( f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) \right)$$
  
$$\leq f_0(\tilde{x}) + \sum_{i=1}^m \lambda_i f_i(\tilde{x})$$
  
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### This holds for every feasible $\tilde{x}$ , hence lower bound holds.

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Closest (i.e. biggest) lower bound  $g(\lambda)$  on the optimal solution  $p^*$  of original problem: Lagrange dual problem

maximize 
$$g(\lambda)$$
  
subject to  $\lambda \succeq 0.$  (5)

**Dual optimal**: solutions  $\lambda^*$  maximizing dual,  $d^*$  is optimal value (dual always easy to maximize: next slide). Weak duality always holds:

$$d^* \leq p^*$$
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...but what is the point of finding a **biggest lower bound** on a **minimization problem**?

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### Best lower bound: maximize the dual

Best (i.e. biggest) lower bound  $g(\lambda)$  on the optimal solution  $p^*$  of original problem: Lagrange dual problem

maximize 
$$g(\lambda)$$
  
subject to  $\lambda \succeq 0.$  (6)

**Dual optimal**: solutions  $\lambda^*$  to the dual problem,  $d^*$  is optimal value (dual always easy to maximize: next slide). Weak duality always holds:

$$d^* \leq p^*$$
.

Strong duality: (does not always hold, conditions given later):

$$d^* = p^*$$

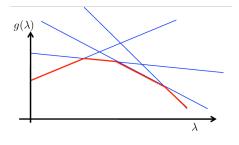
If S.D. holds: solve the easy (concave) dual problem to find  $p^*$ .

### Maximizing the dual is always easy

The Lagrange dual function: minimize Lagrangian (lower bound)

$$g(\lambda) = \inf_{x \in \mathcal{D}} L(x, \lambda).$$

Dual function is a pointwise infimum of affine functions of  $\lambda$ , hence **concave** in  $\lambda$  with convex constraint set  $\lambda \succeq 0$ .



#### Example:

One inequality constraint,

$$L(x,\lambda) = f_0(x) + \lambda f_1(x),$$

and assume there are only four possible values for x. Each line represents a different x.

Conditions under which strong duality holds are called **constraint qualifications** (they are sufficient, but not necessary) (Probably) best known sufficient condition: Strong duality holds if

• Primal problem is convex, i.e. of the form

 $\begin{array}{ll} \text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \leq 0 & \qquad i=1,\ldots,n \end{array}$ 

for convex  $f_0$ , affine  $f_1, \ldots, f_m$ .

## A consequence of strong duality...

Assume primal is equal to the dual. What are the consequences?

- x\* solution of original problem (minimum of f<sub>0</sub> under constraints),
- $\lambda^*$  solution to dual

$$\begin{array}{rcl} f_0(x^*) & = & g(\lambda^*) \\ & & \\ & \underset{(\text{g definition})}{=} & \inf_{x} \left( f_0(x) + \sum_{i=1}^m \lambda_i^* f_i(x) \right) \\ & \\ & \underset{(\text{inf definition})}{\leq} & f_0(x^*) + \sum_{i=1}^m \lambda_i^* f_i(x^*) \\ & \\ & \leq & f_0(x^*), \end{array}$$

(4):  $(x^*, \lambda^*)$  satisfies  $\lambda^* \succeq 0$ , and  $f_i(x^*) \le 0$ .

From previous slide,

$$\sum_{i=1}^{m} \lambda_i^* f_i(x^*) = 0,$$
 (7)

which is the condition of complementary slackness. This means

$$egin{array}{lll} \lambda_i^* > 0 & \Longrightarrow & f_i(x^*) = 0, \ f_i(x^*) < 0 & \Longrightarrow & \lambda_i^* = 0. \end{array}$$

From  $\lambda_i$ , read off which inequality constraints are strict.

## KKT conditions for global optimum

Assume functions  $f_i$  are differentiable and strong duality. Since  $x^*$  minimizes  $L(x, \lambda^*)$ , derivative at  $x^*$  is zero,

$$\nabla f_0(x^*) + \sum_{i=1}^m \lambda_i^* \nabla f_i(x^*) = 0.$$

**KKT conditions definition**: we are at global optimum,  $(x, \lambda, \nu) = (x^*, \lambda^*)$  when (a) strong duality holds, and (b)

$$f_i(x) \leq 0, i = 1, \dots, m$$
  

$$\lambda_i \geq 0, i = 1, \dots, m$$
  

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### In summary: if

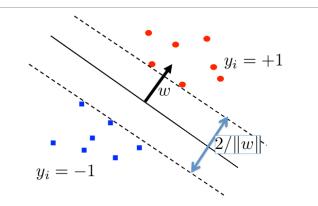
- primal problem convex and
- inequality constraints affine
- then strong duality holds. If in addition
  - functions *f<sub>i</sub>* differentiable

then KKT conditions necessary and sufficient for optimality.

# Support vector classification

### Reminder: linearly separable points

Classify two clouds of points, where there exists a hyperplane which linearly separates one cloud from the other without error.



Smallest distance from each class to the separating hyperplane  $w^{\top}x + b$  is called the margin.

### Maximum margin classifier, linearly separable case

This problem can be expressed as follows:

$$\max_{w,b} (\operatorname{margin}) = \max_{w,b} \left( \frac{2}{\|w\|} \right)$$
(8)

subject to

$$\begin{cases} w^{\top} x_i + b \ge 1 & i : y_i = +1, \\ w^{\top} x_i + b \le -1 & i : y_i = -1. \end{cases}$$
(9)

The resulting classifier is

$$y = \operatorname{sign}(w^{\top}x + b),$$

We can rewrite to obtain

$$\max_{w,b} \frac{1}{\|w\|} \quad \text{or} \quad \min_{w,b} \|w\|^2$$

subject to

$$y_i(w \mid x_i + D) \geq 1.$$

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subject to

$$y_i(w^{\top}x_i+b) \geq 1.$$
 (10)

Allow "errors": points within the margin, or even on the wrong side of the decision boundary. Ideally:

$$\min_{w,b}\left(\frac{1}{2}\|w\|^2+C\sum_{i=1}^n\mathbb{I}[y_i\left(w^{\top}x_i+b\right)<0]\right),$$

where C controls the tradeoff between maximum margin and loss.

...but this is too hard! (Why?)

### Maximum margin classifier: with errors allowed

Allow "errors": points within the margin, or even on the wrong side of the decision boudary. Ideally:

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where *C* controls the tradeoff between maximum margin and loss. Replace with **convex upper bound**:

$$\min_{w,b}\left(\frac{1}{2}\|w\|^2+C\sum_{i=1}^n\theta\left(y_i\left(w^\top x_i+b\right)\right)\right).$$

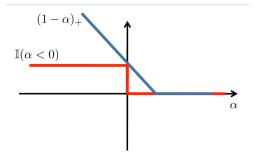
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# Hinge loss

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Substituting in the hinge loss, we get

$$\min_{w,b} \left( \frac{1}{2} \|w\|^2 + C \sum_{i=1}^n \theta \left( y_i \left( w^\top x_i + b \right) \right) \right).$$

How do you implement hinge loss with simple inequality constraints (i.e. for convex optimization)?

$$\min_{w,b,\xi} \left( \frac{1}{2} \|w\|^2 + C \sum_{i=1}^n \xi_i \right)$$
(11)

subject to<sup>1</sup>

$$\xi_i \ge 0$$
  $y_i\left(w^{\top}x_i+b\right) \ge 1-\xi_i$ 

<sup>1</sup>Either  $y_i(w^{\top}x_i + b) \ge 1$  and  $\xi_i = 0$  as before, or  $y_i(w^{\top}x_i + b) < 1$ , and then  $\xi_i > 0$  takes the value satisfying  $y_i(w^{\top}x_i + b) = 1 - \xi_i$ .

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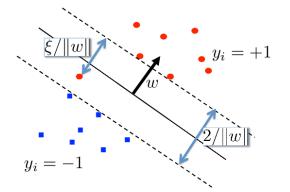
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**Output Output Description Descriptio** 

$$\begin{array}{ll} \text{minimize} & f_0(w, b, \xi) := \frac{1}{2} \|w\|^2 + C \sum_{i=1}^n \xi_i \\ \text{subject to} & 1 - \xi_i - y_i \left( w^\top x_i + b \right) \leq 0 & i = 1, \dots, n \\ & -\xi_i \leq 0 & i = 1, \dots, n \end{array}$$

( $f_0$  is convex,  $f_1, \ldots, f_n$  are affine).

**Strong duality** holds, **and** the problem is differentiable, hence the KKT conditions hold at the global optimum.

**Or Convex optimization problem** over the variables  $w, b, \xi$ :

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The Lagrangian:  $L(w, b, \xi, \alpha, \lambda)$ 

$$= \frac{1}{2} \|w\|^2 + C \sum_{i=1}^n \xi_i + \sum_{i=1}^n \alpha_i \left( 1 - y_i \left( w^\top x_i + b \right) - \xi_i \right) + \sum_{i=1}^n \lambda_i (-\xi_i)$$

with dual variable constraints

$$\alpha_i \geq 0, \qquad \lambda_i \geq 0.$$

#### Minimize wrt the primal variables w, b, and $\xi$ .

Derivative wrt w:

$$\frac{\partial L}{\partial w} = w - \sum_{i=1}^{n} \alpha_i y_i x_i = 0 \qquad w = \sum_{i=1}^{n} \alpha_i y_i x_i.$$
(12)

Derivative wrt b:

$$\frac{\partial L}{\partial b} = \sum_{i} y_i \alpha_i = 0.$$
(13)

The Lagrangian:  $L(w, b, \xi, \alpha, \lambda)$ 

$$= \frac{1}{2} \|w\|^2 + C \sum_{i=1}^n \xi_i + \sum_{i=1}^n \alpha_i \left( 1 - y_i \left( w^\top x_i + b \right) - \xi_i \right) + \sum_{i=1}^n \lambda_i (-\xi_i)$$

with dual variable constraints

$$\alpha_i \geq 0, \qquad \lambda_i \geq 0.$$

Minimize wrt the primal variables w, b, and  $\xi$ . Derivative wrt w:

$$\frac{\partial L}{\partial w} = w - \sum_{i=1}^{n} \alpha_i y_i x_i = 0 \qquad w = \sum_{i=1}^{n} \alpha_i y_i x_i.$$
(12)

Derivative wrt b:

$$\frac{\partial L}{\partial b} = \sum_{i} y_{i} \alpha_{i} = 0.$$
(13)

Derivative wrt  $\xi_i$ :

$$\frac{\partial L}{\partial \xi_i} = C - \alpha_i - \lambda_i = 0 \qquad \alpha_i = C - \lambda_i.$$
(14)

Noting that  $\lambda_i \geq 0$ ,

$$\alpha_i \leq C.$$

Now use complementary slackness:

**Non-margin SVs:**  $\alpha_i = C \neq 0$ :

- We immediately have  $1 \xi_i = y_i (w^\top x_i + b)$ .
- 2 Also, from condition α<sub>i</sub> = C λ<sub>i</sub>, we have λ<sub>i</sub> = 0, hence possibly ξ<sub>i</sub> > 0.
- Margin SVs:  $0 < \alpha_i < C$ :
  - We again have  $1 \xi_i = y_i \left( w^\top x_i + b \right)$

② This time, from  $\alpha_i = C - \lambda_i$ , we have  $\lambda_i \neq 0$ , hence  $\xi_i = 0$ . Non-SVs:  $\alpha_i = 0$ 

- We can allow:  $y_i (w^\top x_i + b) > 1 \xi_i$
- 2) From  $\alpha_i = C \lambda_i$ , we have  $\lambda_i \neq 0$ , hence  $\xi_i = 0$ .

Derivative wrt  $\xi_i$ :

$$\frac{\partial L}{\partial \xi_i} = C - \alpha_i - \lambda_i = 0 \qquad \alpha_i = C - \lambda_i.$$
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2 This time, from  $\alpha_i = C - \lambda_i$ , we have  $\lambda_i \neq 0$ , hence  $\xi_i = 0$ . Non-SVs:  $\alpha_i = 0$ 

- We can allow:  $y_i (w^\top x_i + b) > 1 \xi_i$
- **2** From  $\alpha_i = C \lambda_i$ , we have  $\lambda_i \neq 0$ , hence  $\xi_i = 0$ .

We observe:

- The solution is sparse: points which are not on the margin, or "margin errors", have  $\alpha_i = 0$
- The support vectors: only those points on the decision boundary, or which are margin errors, contribute.
- Influence of the non-margin SVs is bounded, since their weight cannot exceed C.

# Support vector classification: dual function

Thus, our goal is to maximize the dual,

$$g(\alpha, \lambda) = \frac{1}{2} \|w\|^2 + C \sum_{i=1}^n \xi_i + \sum_{i=1}^n \alpha_i \left(1 - y_i \left(w^\top x_i + b\right) - \xi_i\right) \\ + \sum_{i=1}^n \lambda_i (-\xi_i) \\ = \frac{1}{2} \sum_{i=1}^m \sum_{j=1}^m \alpha_i \alpha_j y_i y_j x_i^\top x_j + C \sum_{i=1}^m \xi_i - \sum_{i=1}^m \sum_{j=1}^m \alpha_i \alpha_j y_i y_j x_i^\top x_j \\ - b \sum_{i=1}^m \alpha_i y_i + \sum_{i=1}^m \alpha_i - \sum_{i=1}^m \alpha_i \xi_i - \sum_{i=1}^m (C - \alpha_i) \xi_i \\ = \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i=1}^m \sum_{j=1}^m \alpha_i \alpha_j y_i y_j x_i^\top x_j.$$

# Support vector classification: dual function

Maximize the dual,

$$g(\alpha) = \sum_{i=1}^{m} \alpha_i - \frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} \alpha_i \alpha_j y_i y_j x_i^{\top} x_j,$$

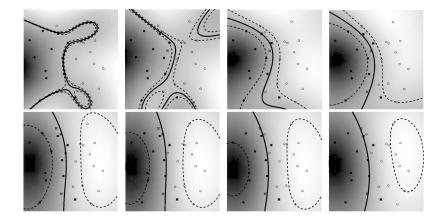
subject to the constraints

$$0 \leq \alpha_i \leq C, \quad \sum_{i=1}^n y_i \alpha_i = 0$$

This is a quadratic program.

Offset *b*: for the margin SVs, we have  $1 = y_i (w^{\top} x_i + b)$ . Obtain *b* from any of these, or take an average.

## Support vector classification: kernel version



Taken from Schoelkopf and Smola (2002)

Maximum margin classifier in RKHS: write the hinge loss formulation

$$\min_{w} \left( \frac{1}{2} \|w(\cdot)\|_{\mathcal{H}}^{2} + C \sum_{i=1}^{n} \theta\left( y_{i} \langle w(\cdot), \phi(x_{i}) \rangle_{\mathcal{H}} \right) \right)$$

for the RKHS  $\mathcal{H}$  with kernel  $k(x, \cdot)$ . Use the result of the representer theorem,

$$w(\cdot) = \sum_{i=1}^n \beta_i \phi(x_i).$$

Maximizing the margin equivalent to minimizing  $||w(\cdot)||_{\mathcal{H}}^2$ : for many RKHSs a smoothness constraint (e.g. Gaussian kernel).

# Support vector classification: kernel version

Substituting and introducing the  $\xi_i$  variables, get

$$\min_{\beta,\xi} \left( \frac{1}{2} \beta^{\top} \mathcal{K} \beta + C \sum_{i=1}^{n} \xi_i \right)$$
(15)

where the matrix K has i, jth entry  $K_{ij} = k(x_i, x_j)$ , subject to

$$\xi_i \geq 0$$
  $y_i \sum_{j=1}^n \beta_j k(x_i, x_j) \geq 1 - \xi_i$ 

Convex in  $\beta, \xi$  since K is positive definite. Dual:

$$g(\alpha) = \sum_{i=1}^{m} \alpha_i - \frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} \alpha_i \alpha_j y_i y_j k(x_i, x_j),$$

subject to the constraints  $0 \leq \alpha_i \leq C$ , and

$$w(\cdot) = \sum_{i=1}^{n} y_i \alpha_i \phi(x_i).$$

# Support vector classification: kernel version

Substituting and introducing the  $\xi_i$  variables, get

$$\min_{\beta,\xi} \left( \frac{1}{2} \beta^{\top} \mathcal{K} \beta + C \sum_{i=1}^{n} \xi_i \right)$$
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subject to the constraints  $0 \le \alpha_i \le C$ , and

$$w(\cdot) = \sum_{i=1}^n y_i \alpha_i \phi(x_i).$$



# Representer theorem

Given a set of paired observations  $(x_1, y_1), \ldots, (x_n, y_n)$  (regression or classification). Find the function  $f^*$  in the RKHS  $\mathcal{H}$  which satisfies

$$J(f^*) = \min_{f \in \mathcal{H}} J(f), \tag{16}$$

where

$$J(f) = L_{y}(f(x_1), \ldots, f(x_n)) + \Omega\left( \|f\|_{\mathcal{H}}^2 \right),$$

 $\Omega$  is non-decreasing, and y is the vector of  $y_i$ .

- Classification:  $L_y(f(x_1), \ldots, f(x_n)) = \sum_{i=1}^n \mathbb{I}_{y_i f(x_i) \le 0}$
- Regression:  $L_y(f(x_1), ..., f(x_n)) = \sum_{i=1}^n (y_i f(x_i))^2$

#### The representer theorem: solution to

$$\min_{f\in\mathcal{H}}\left[L_{y}(f(x_{1}),\ldots,f(x_{n}))+\Omega\left(\left\|f\right\|_{\mathcal{H}}^{2}\right)\right]$$

takes the form

$$f^* = \sum_{i=1}^n \alpha_i \phi(\mathbf{x}_i).$$

If  $\boldsymbol{\Omega}$  is strictly increasing, all solutions have this form.

**Proof:** Denote  $f_s$  projection of f onto the subspace

$$\operatorname{span}\left\{\phi(x_i):\ 1\leq i\leq n\right\},\tag{17}$$

such that

$$f=f_s+f_{\perp},$$

where  $f_s = \sum_{i=1}^{n} \alpha_i k(x_i, \cdot)$ . Regularizer:

$$\|f\|_{\mathcal{H}}^2 = \|f_s\|_{\mathcal{H}}^2 + \|f_{\perp}\|_{\mathcal{H}}^2 \ge \|f_s\|_{\mathcal{H}}^2,$$

then

$$\Omega\left(\left\|f\right\|_{\mathcal{H}}^{2}\right) \geq \Omega\left(\left\|f_{s}\right\|_{\mathcal{H}}^{2}\right),$$

so this term is minimized for  $f = f_s$ .

**Proof (cont.):** Individual terms  $f(x_i)$  in the loss:

$$f(\mathbf{x}_i) = \langle f, \phi(\mathbf{x}_i) \rangle_{\mathcal{H}} = \langle f_s + f_{\perp}, \phi(\mathbf{x}_i) \rangle_{\mathcal{H}} = \langle f_s, \phi(\mathbf{x}_i) \rangle_{\mathcal{H}},$$

SO

$$L_y(f(x_1),\ldots,f(x_n))=L_y(f_s(x_1),\ldots,f_s(x_n)).$$

Hence

- Loss *L*(...) only depends on the component of *f* in the data subspace,
- Regularizer  $\Omega(\ldots)$  minimized when  $f = f_s$ .
- If  $\Omega$  is strictly non-decreasing, then  $\|f_{\perp}\|_{\mathcal{H}} = 0$  is required at the minimum.

### Support vector classification: the $\nu$ -SVM

Hard to interpret C. Modify the formulation to get a more intuitive parameter  $\nu$ .

Again, we drop b for simplicity. Solve

$$\min_{w,\rho,\xi} \left( \frac{1}{2} \|w\|^2 - \nu\rho + \frac{1}{n} \sum_{i=1}^n \xi_i \right)$$

subject to

$$\begin{array}{rcl} \rho & \geq & 0 \\ \xi_i & \geq & 0 \\ y_i w^\top x_i & \geq & \rho - \xi_i, \end{array}$$

(now directly adjust margin width  $\rho$ ).

$$\frac{1}{2} \|w\|^2 + \frac{1}{n} \sum_{i=1}^n \xi_i - \nu \rho + \sum_{i=1}^n \alpha_i \left( \rho - y_i w^\top x_i - \xi_i \right) + \sum_{i=1}^n \beta_i (-\xi_i) + \gamma (-\rho)$$

for dual variables  $\alpha_i \geq 0$ ,  $\beta_i \geq 0$ , and  $\gamma \geq 0$ .

Differentiating and setting to zero for each of the primal variables  $w, \xi, \rho$ ,

$$w = \sum_{i=1}^{n} \alpha_i y_i x_i$$
  

$$\alpha_i + \beta_i = \frac{1}{n}$$
(18)  

$$\nu = \sum_{i=1}^{n} \alpha_i - \gamma$$
(19)

From  $\beta_i \geq 0$ , equation (18) implies

$$\frac{1}{2} \|w\|^2 + \frac{1}{n} \sum_{i=1}^n \xi_i - \nu \rho + \sum_{i=1}^n \alpha_i \left(\rho - y_i w^\top x_i - \xi_i\right) + \sum_{i=1}^n \beta_i (-\xi_i) + \gamma (-\rho)$$

n

for dual variables  $\alpha_i \geq 0$ ,  $\beta_i \geq 0$ , and  $\gamma \geq 0$ . Differentiating and setting to zero for each of the primal variables w,  $\xi$ ,  $\rho$ ,

$$w = \sum_{i=1}^{n} \alpha_i y_i x_i$$
  

$$\alpha_i + \beta_i = \frac{1}{n}$$
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$$\nu = \sum_{i=1}^{n} \alpha_i - \gamma$$
(19)

From  $\beta_i \geq 0$ , equation (18) implies

$$0\leq \alpha_i\leq n^{-1}.$$

### Complementary slackness conditions:

Assume  $\rho >$  0 at the global solution, hence  $\gamma =$  0, and

$$\sum_{i=1}^{n} \alpha_i = \nu. \tag{20}$$

Case of  $\xi_i > 0$ : complementary slackness states  $\beta_i = 0$ , hence from (18) we have  $\alpha_i = n^{-1}$ . Denote this set as  $N(\alpha)$ . Then

$$\sum_{i\in N(\alpha)}\frac{1}{n}=\sum_{i\in N(\alpha)}\alpha_i\leq \sum_{i=1}^n\alpha_i=\nu,$$

SO

and u is an upper bound on the number of non-margin SVs.

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$$\sum_{i\in N(\alpha)}\frac{1}{n}=\sum_{i\in N(\alpha)}\alpha_i\leq \sum_{i=1}^n\alpha_i=\nu,$$

 $\frac{|N(\alpha)|}{2} \leq \nu,$ 

SO

and 
$$u$$
 is an upper bound on the number of non-margin SVs.

Case of  $\xi_i = 0$ :  $\alpha_i < n^{-1}$ . Denote by  $M(\alpha)$  the set of points  $n^{-1} > \alpha_i > 0$ . Then from (20),

$$\nu = \sum_{i=1}^{n} \alpha_i = \sum_{i \in \mathcal{N}(\alpha)} \frac{1}{n} + \sum_{i \in \mathcal{M}(\alpha)} \alpha_i \le \sum_{i \in \mathcal{M}(\alpha) \cup \mathcal{N}(\alpha)} \frac{1}{n},$$

thus

$$u \leq \frac{|N(\alpha)| + |M(\alpha)|}{n},$$

and  $\nu$  is a lower bound on the number of support vectors with non-zero weight (both on the margin, and "margin errors").

# Dual for $\nu$ -SVM

Substituting into the Lagrangian, we get

$$\frac{1}{2}\sum_{i=1}^{m}\sum_{j=1}^{m}\alpha_{i}\alpha_{j}y_{i}y_{j}x_{i}^{\top}x_{j} + \frac{1}{n}\sum_{i=1}^{n}\xi_{i} - \rho\nu - \sum_{i=1}^{m}\sum_{j=1}^{m}\alpha_{i}\alpha_{j}y_{i}y_{j}x_{i}^{\top}x_{j}$$
$$+ \sum_{i=1}^{n}\alpha_{i}\rho - \sum_{i=1}^{n}\alpha_{i}\xi_{i} - \sum_{i=1}^{n}\left(\frac{1}{n} - \alpha_{i}\right)\xi_{i} - \rho\left(\sum_{i=1}^{n}\alpha_{i} - \nu\right)$$
$$= -\frac{1}{2}\sum_{i=1}^{m}\sum_{j=1}^{m}\alpha_{i}\alpha_{j}y_{i}y_{j}x_{i}^{\top}x_{j}$$

Maximize:

$$g(\alpha) = -\frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} \alpha_i \alpha_j y_i y_j x_i^{\top} x_j,$$

subject to

$$\sum_{i=1}^n \alpha_i \ge \nu \qquad 0 \le \alpha_i \le \frac{1}{n}.$$

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$$+ \sum_{i=1}^{n}\alpha_{i}\rho - \sum_{i=1}^{n}\alpha_{i}\xi_{i} - \sum_{i=1}^{n}\left(\frac{1}{n} - \alpha_{i}\right)\xi_{i} - \rho\left(\sum_{i=1}^{n}\alpha_{i} - \nu\right)$$
$$= -\frac{1}{2}\sum_{i=1}^{m}\sum_{j=1}^{m}\alpha_{i}\alpha_{j}y_{i}y_{j}x_{i}^{\top}x_{j}$$

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