Mini-course on representation theoretical methods in ML

Lecture 1: Groups

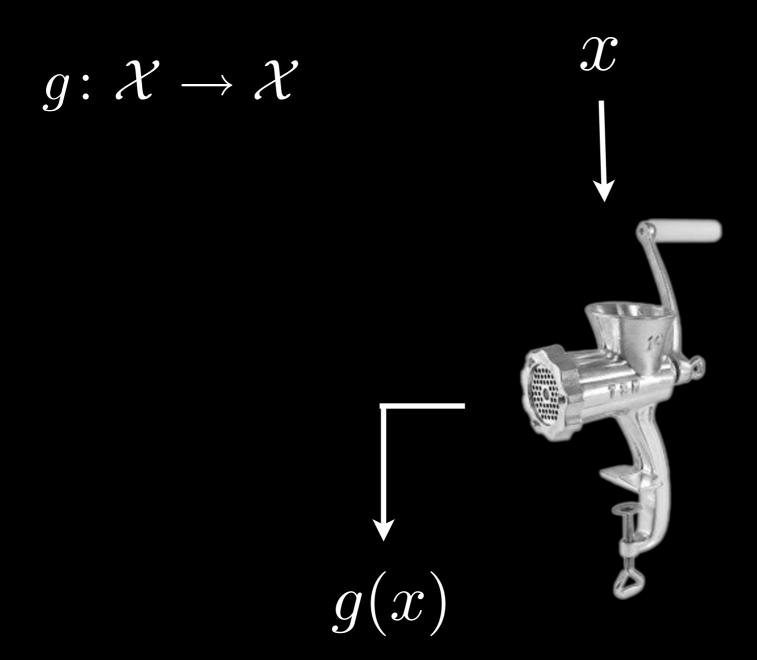
Risi Kondor (Gatsby Unit)

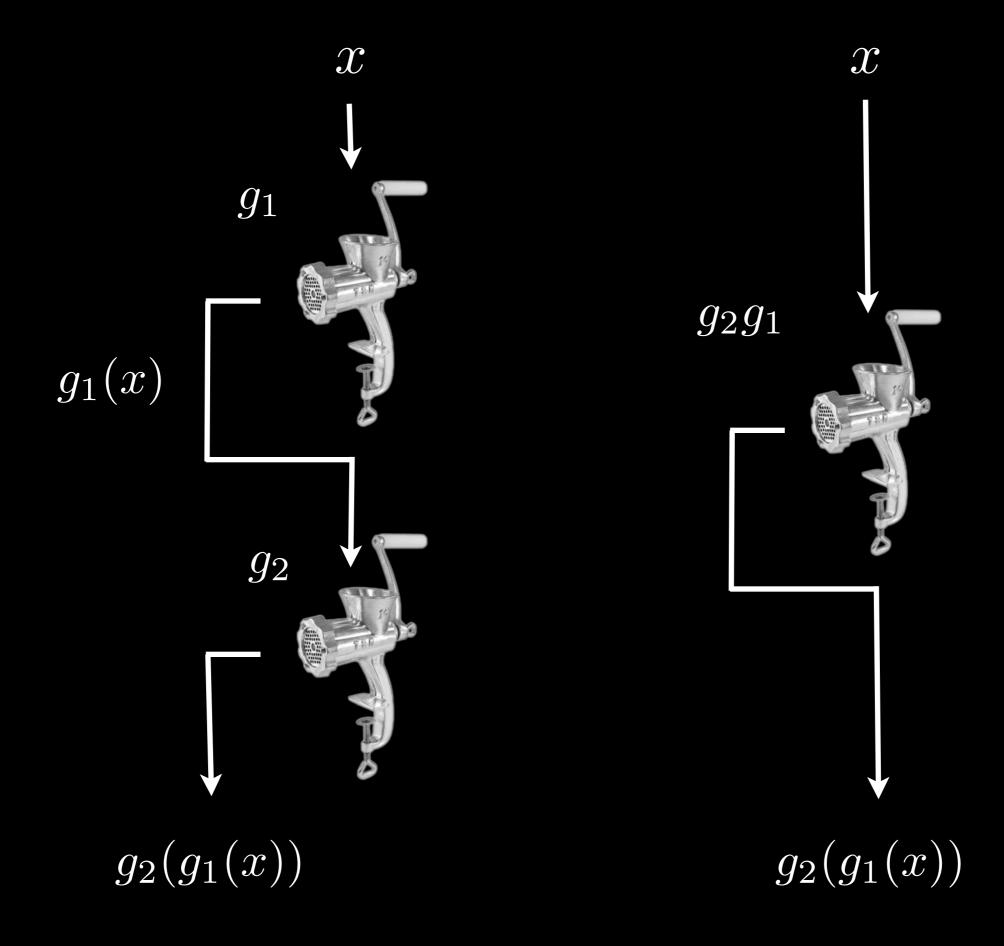
What is a group?

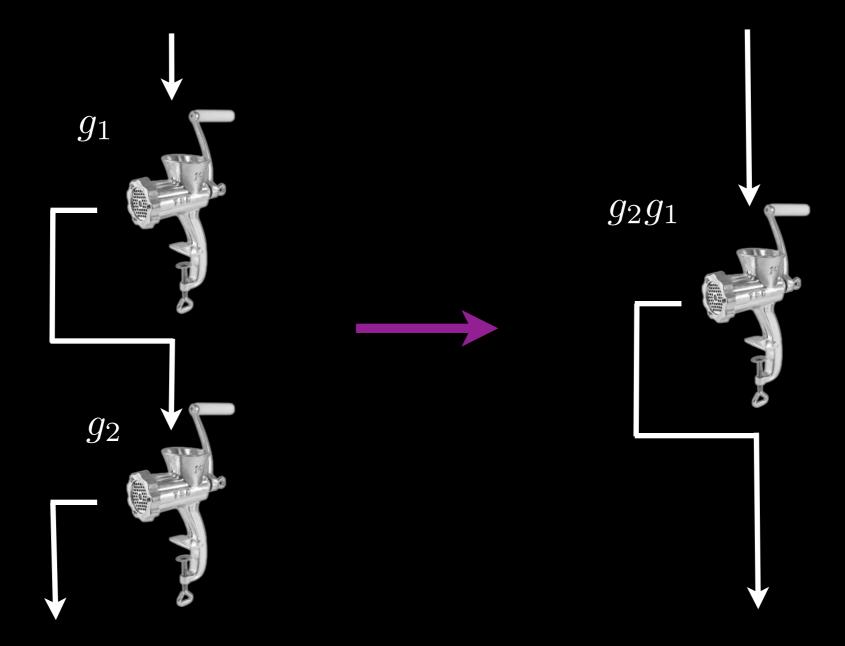
G is a group if for any $x, y, z \in G$

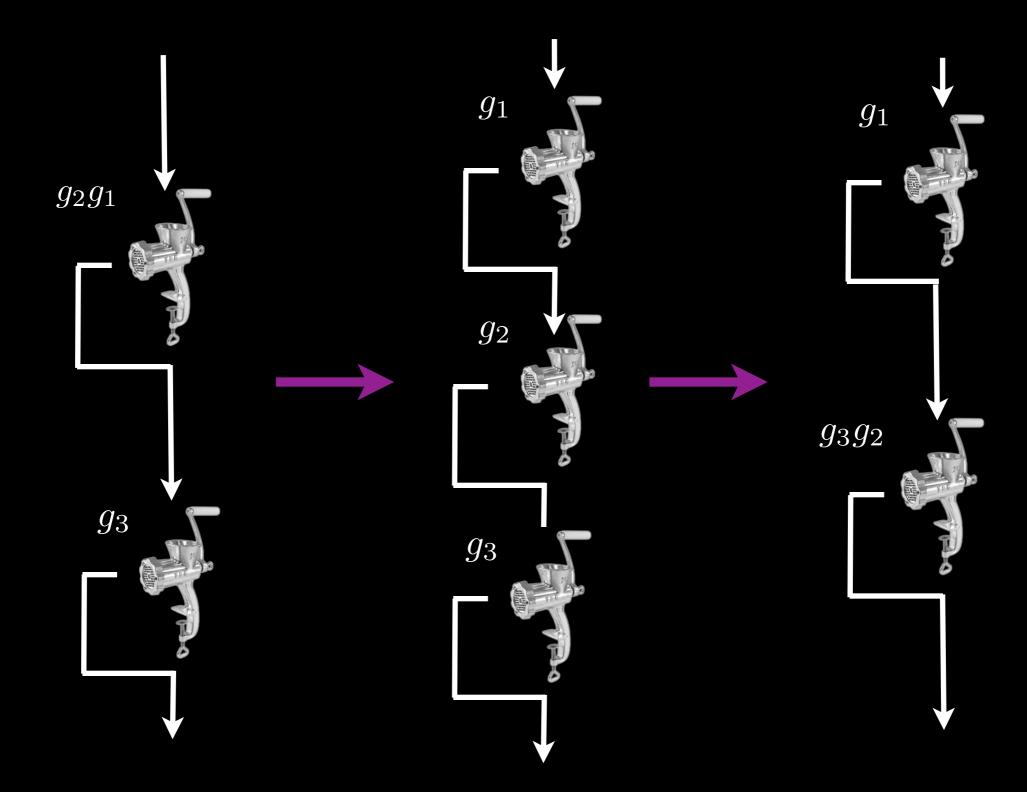
- $1. xy \in G,$
- 2. x(yz) = (xy)z,
- 3. there is an $e \in G$ such that ex = xe = x,
- **4.** there is an $x^{-1} \in G$ such that $xx^{-1} = x^{-1}x = e$.

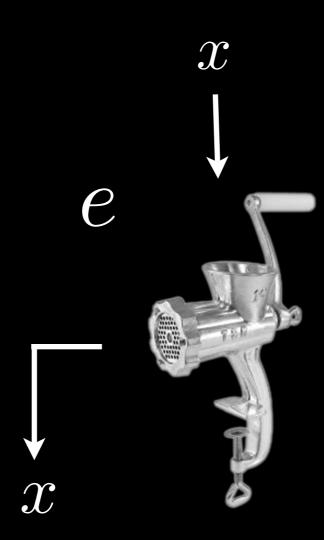
Why should we care?

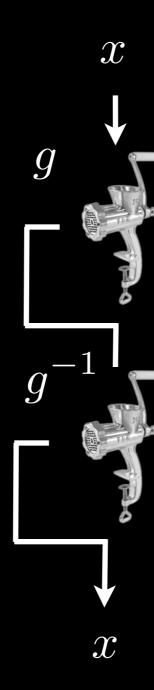












The cyclic group $\mathbb{Z}_n = \{0, 1, 2, \dots, n-1\}$

$$xy = x + y \mod n$$

Klein's Viergruppe $V = \{1, i, j, k\}$

| | 1 | | | | |
|---|---|----------------|----------------|-----------|---|
| 1 | 1 | i | j | k | $V\cong \mathbb{Z}_2	imes \mathbb{Z}_2$ |
| i | i | 1 | k | \dot{j} | $V = 2 \times 2$ |
| j | j | k | 1 | i | |
| k | k | \overline{j} | \overline{i} | 1 | |

The quaternion group $Q = \{1, i, j, k, -1, -i, -j, -k\}$

| | 1 | i | \overline{j} | k | -1 | -i | -j | -k |
|-----------------|----|----------------|-----------------|----|----|----|-----------------|----------------|
| | 1 | | | | | | | |
| $i \mid \mid$ | i | -1 | k | -j | -i | 1 | -k | j |
| $j \mid \mid$ | j | -k | -1 | i | -j | k | 1 | -i |
| $k \mid$ | k | j | -i | -1 | -k | -j | i | 1 |
| $\overline{-1}$ | -1 | -i | $\overline{-j}$ | -k | 1 | i | \overline{j} | k |
| -i | -i | 1 | -k | j | i | -1 | k | -j |
| $-j \parallel$ | -j | \overline{k} | 1 | -i | j | -k | $\overline{-1}$ | \overline{i} |
| | -k | | | | | j | | |

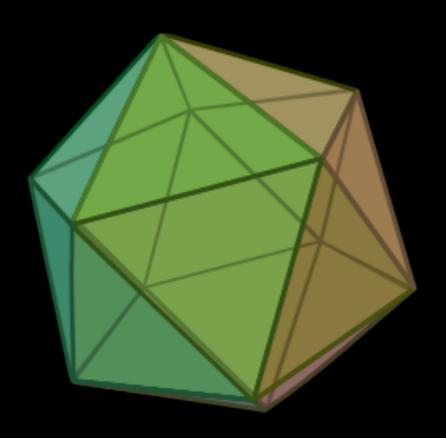
$$-1^{2} = 1$$

$$(-1)a = a(-1) = -a$$

$$i^{2} = j^{2} = k^{2} = -1$$

$$ij = k$$

The icosahedron group $I_h \cong A_5$



The symmetric groups \mathbb{S}_n

group of bijections

$$\sigma \colon \{1, 2, \dots, n\} \to \{1, 2, \dots, n\}$$

i.e., permutations of n objects

The integers \mathbb{Z}

$$xy = x + y$$

The reals $\mathbb R$ and the Euclidean vector spaces $\mathbb R^n$

$$xy = x + y$$

The rotation groups SO(n)

group of $n \times n$ orthogonal matrices of det l

The Euclidean group ${\rm ISO}(n)$ and group of rigid body motions ${\rm ISO}^+(n)$



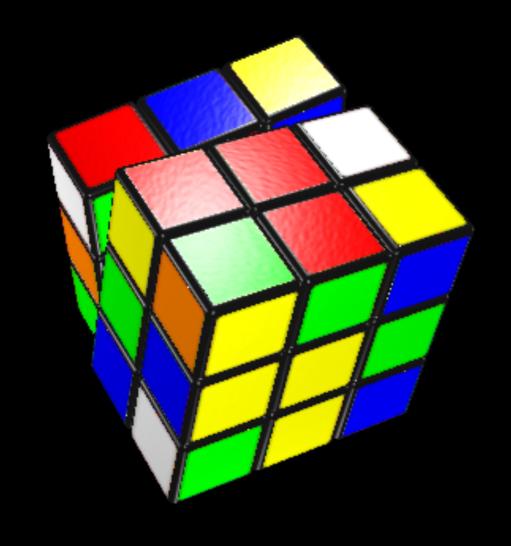
Erlangen program (1872):

"geometry is the study of properties invariant under a group" The special unitary groups SU(n)

group of $n \times n$ unitary matrices of determinant 1

The general linear group GL(n)

group of $n \times n$ invertible matrices



$$G = \left(\mathbb{Z}_3^7 \times \mathbb{Z}_2^{11}\right) \rtimes \left(\left(A_8 \times A_{12}\right) \rtimes \mathbb{Z}_2\right)$$

The Monster group $\,M\,$

```
|M| = 8080174247945128758864599049617... ... 107570057543680000000000
```

| h | # | Abelian | # | non-Abelian | total |
|----|---|---|---|--|-------|
| 1 | 1 | $\langle e \rangle$ | 0 | - | 1 |
| 2 | 1 | C_2 | 0 | - | 1 |
| 3 | 1 | C ₃ | 0 | - | 1 |
| 4 | 2 | C_4 , $C_2 \times C_2$ | 0 | - | 2 |
| 5 | 1 | C ₅ | 0 | - | 1 |
| 6 | 1 | C_6 | 1 | D_3 | 2 |
| 7 | 1 | C7 | 0 | - | 1 |
| 8 | 3 | C_8 , $C_2 \times C_4$, $C_2 \times C_2 \times C_2$ | 2 | D_4 , Q_8 | 5 |
| 9 | 2 | C_9 , $C_3 \times C_3$ | 0 | - | 2 |
| 10 | 1 | C_{10} | 1 | D_5 | 2 |
| 11 | 1 | C_{11} | 0 | - | 1 |
| 12 | 2 | C_{12} , $C_2 \times C_6$ | 3 | A_4 , D_6 , T | 5 |
| 13 | 1 | C_{13} | 0 | - | 1 |
| 14 | 1 | C_{14} | 1 | D_7 | 2 |
| 15 | 1 | C ₁₅ | 0 | - | 1 |
| 16 | 5 | C_{16} , $C_8 \times C_2$, $C_4 \times C_4$, $C_4 \times C_2 \times C_2$, $C_2 \times C_2 \times C_2 \times C_2$ | 9 | $D_8, D_4 \times C_2, Q \times C_2, G_{16}^{(4)}, G_{16}^{(5)}, G_{16}^{(6)}, G_{16}^{(7)}, G_{16}^{(8)}, G_{16}^{(9)}, G_{$ | 14 |
| 17 | 1 | C ₁₇ | 0 | - | 1 |

Finite groups \mathbb{Z}_n V Q M \mathbb{S}_n Infinite groups Countable groups Z Continuous groups Lie groups compact SO(n) SU(n)non-compact \mathbb{R}^n ISO⁺(n)

Closed fields

Fields

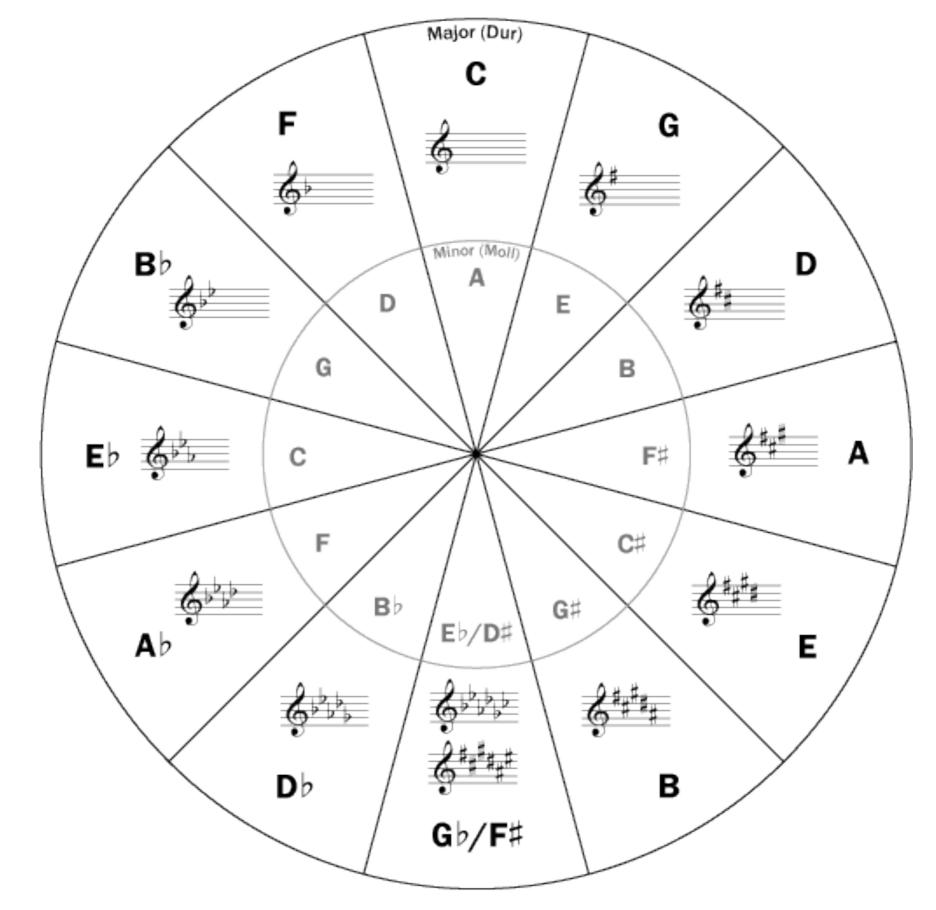
Rings

Groups commutative non-commutative

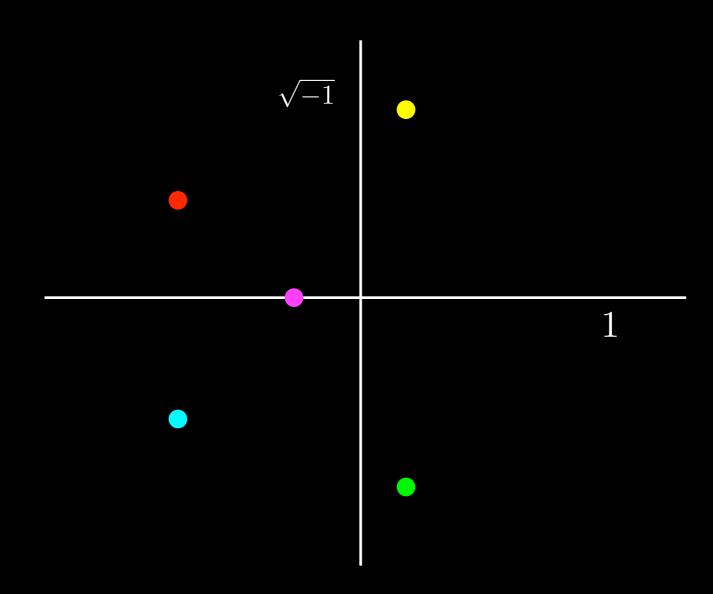
Semigroups

Applications

 \mathbb{Z}_{12}

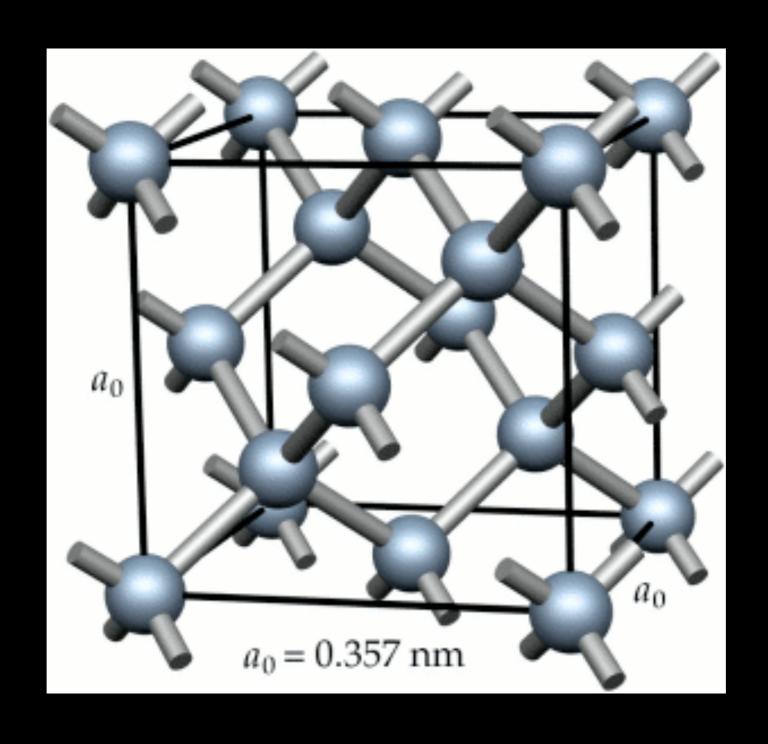


Galois Theory

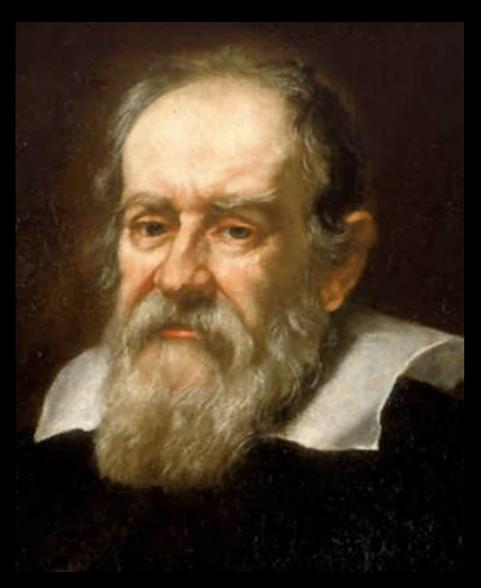


$$ax^5 + bx^4 + cx^3 + dx^2 + ex + f = 0$$

Crystallography



Classical Physics



Galileo Galilei (1564-1642)

The invariance group of classical Physics is

 $ISO(3) \times \mathbb{R}$

Relativity

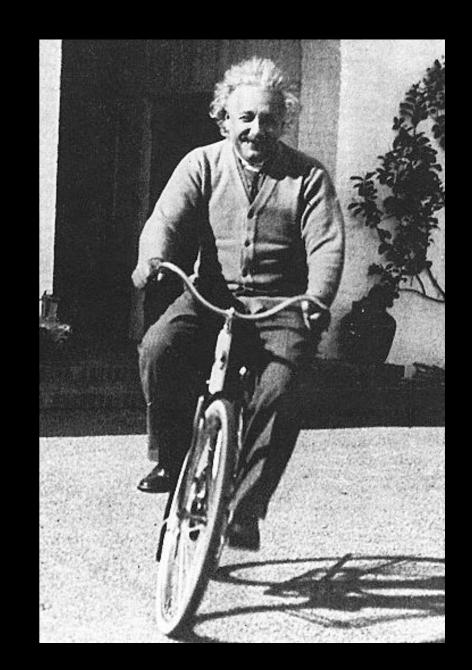
To preserve

$$(\Delta x)^2 + (\Delta y)^2 + (\Delta z)^2 - c^2(\Delta t^2)$$

relativity adopted the Lorentz group $\mathrm{SO}^+(1,3)$

$$\begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \cosh(\beta) & -\sinh(\beta) & 0 & 0 \\ -\sinh(\beta) & \cosh(\beta) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$$

$$\beta = \log\left(\frac{1 + v/c}{\sqrt{1 - v^2/c^2}}\right)$$



Albert Einstein (1879-1955)

Noether's Theorem

Symmetry implies conservation:

$$\frac{dJ}{dt} = -\frac{\partial \mathcal{H}}{\partial \theta}$$

(roughly)

time → energy

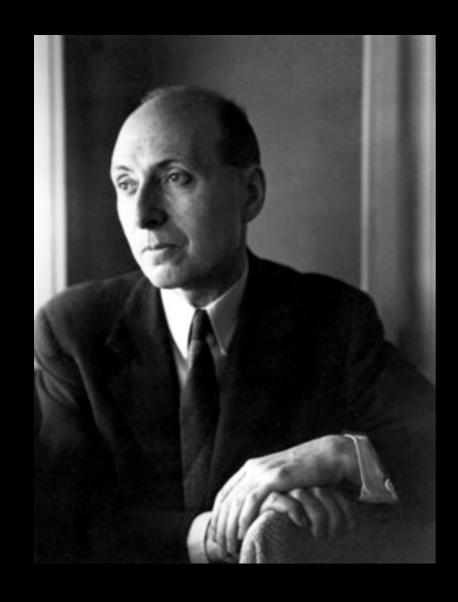
space → momentum

rotation \rightarrow angular mom.



Emmy Noether (1882-1935)

Standard model and beyond



Eugene Wigner (1902-1995)

symmetries → unitary op.

observables → generators

pure states → dimensions of irreps

 $SU(3), SU(6), \dots$

lead to quarks and even stranger animals...

Engineering

Lecture Notes in Computer Science

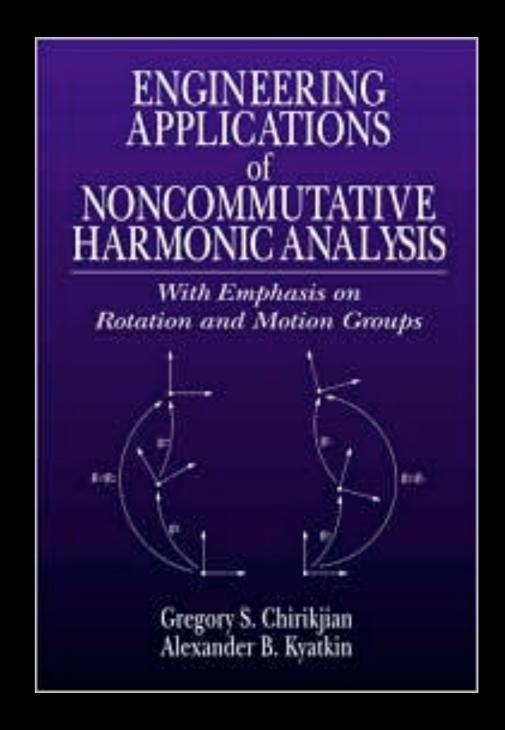
Edited by G. Goos and J. Hartmanis

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Reiner Lenz

Group Theoretical Methods in Image Processing





Machine Learning

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Invariances images, graphs, etc.
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Permutation problems

ranking
multi-object tracking

Search

optimization over combinatorial structures

Structure

Isomorphism

 $G\cong H$ if there is a bijection $\psi\colon G\to H$ s.t.

$$\psi(g_1)\,\psi(g_2) = \psi(g_1g_2)$$

If ψ is only surjective, then it is a homomorphism.

Direct product

$$G \times H = \{ (g,h) \mid g \in G, h \in H \}$$

$$(g_1, h_1)(g_2, h_2) = (g_1g_2, h_1h_2)$$

e.g., \mathbb{Z}_2^n , \mathbb{R}^n

Semi-direct product

If H acts on G (by automorphisms), then

$$G \rtimes H = \{ (x, \Lambda) \mid x \in G, \Lambda \in H \}$$

$$(x', \Lambda')(x, \Lambda) = (x'\Lambda'(x), \Lambda'\Lambda)$$

e.g.,
$$ISO_3^+ \cong \mathbb{R}^2 \rtimes SO(3)$$
 $x \mapsto Rx + b$

Wreath product

If H is a subgroup of \mathbb{S}_n , then

$$G \wr H \cong G^n \rtimes H$$

$$(g'_1, g_2, \dots, g'_n; \sigma')(g_1, g_2, \dots, g_n; \sigma) =$$

 $(g'_1 g_{\sigma^{-1}(1)}, g'_2 g_{\sigma^{-1}(2)}, \dots, g'_n g_{\sigma^{-1}(n)}; \sigma'\sigma)$

Subgroups

 $H \subseteq G$ is a subgroup of G if it is closed wrt. the group operation.

left cosets:
$$xH = \{ xh \mid h \in H \}$$

$$x_1H, x_2H, \ldots, x_kH$$
 partition G

e.g., take $G = \mathbb{Z}$ and $H = 3\mathbb{Z}$

Normal subgroups

$$H \lhd G$$
 if $yH = Hy$ for any $y \in G$

Want to define
$$(xH)(yH) = (xyH)$$
.

If $x' = xh_1$ and $y' = yh_2$ must still get the same coset.

$$xh_1yh_2 = xyh$$
 for some $h \in H$
 $h_1yh_2 = yh$
 $h_1y = yh$
 $y^{-1}h_1y = h$
 $y^{-1}h_1y \in H$

$$\rightarrow \qquad yH=Hy \qquad \text{for any} \qquad y\in G$$

Normal subgroups

$$H \lhd G$$
 if $yH = Hy$ for any $y \in G$

$$\longrightarrow$$
 G/H is also a group

No normal factors — simple group

Jordan-Hölder theorem

Up to permutation of factors the subnormal series

$$1 \triangleleft H_1 \triangleleft \cdots \triangleleft H_k = G$$

is unique for any finite group.

The Enormous Theorem (1983)

Every finite simple group belongs to one of the following classes:

- ullet \mathbb{Z}_p ,
- $A_n \quad (n \geq 5)$,
- simple groups of Lie type,
- the 26 sporadic groups.

| Group | Order (sequence A001228 & in OEIS) | 1SF | Factorized order |
|---------------------------------------|---|----------------------|--|
| F ₁ or M | 80801742479451287588645990496171075700575436800000000 | ≈ 8×10 ⁵³ | $2^{46} \cdot 3^{20} \cdot 5^9 \cdot 7^6 \cdot 11^2 \cdot 13^3 \cdot 17 \cdot 19 \cdot 23 \cdot 29 \cdot 31 \cdot 41 \cdot 47 \cdot 59 \cdot 71$ |
| F ₂ or B | 4154781481226426191177580544000000 | ≈ 4×10 ³³ | $2^{41} \cdot 3^{13} \cdot 5^6 \cdot 7^2 \cdot 11 \cdot 13 \cdot 17 \cdot 19 \cdot 23 \cdot 31 \cdot 47$ |
| Fi ₂₄ ' or F ₃₊ | 1255205709190661721292800 | ≈ 1×10 ²⁴ | $2^{21} \cdot 3^{16} \cdot 5^2 \cdot 7^3 \cdot 11 \cdot 13 \cdot 17 \cdot 23 \cdot 29$ |
| Fi ₂₃ | 4089470473293004800 | ≈ 4×10 ¹⁸ | 2 ¹⁸ · 3 ¹³ · 5 ² · 7 · 11 · 13 · 17 · 23 |
| Fi ₂₂ | 64561751654400 | ≈ 6×10 ¹³ | 2 ¹⁷ · 3 ⁹ · 5 ² · 7 · 11 · 13 |
| F ₃ or Th | 90745943887872000 | ≈ 9×10 ¹⁶ | 2 ¹⁵ · 3 ¹⁰ · 5 ³ · 7 ² · 13 · 19 · 31 |
| Ly | 51765179004000000 | ≈ 5×10 ¹⁶ | $2^8 \cdot 3^7 \cdot 5^6 \cdot 7 \cdot 11 \cdot 31 \cdot 37 \cdot 67$ |
| F ₅ or HN | 273030912000000 | ≈ 3×10 ¹⁴ | 2 ¹⁴ · 3 ⁶ · 5 ⁶ · 7 · 11 · 19 |
| Co ₁ | 4157776806543360000 | ≈ 4×10 ¹⁸ | $2^{21} \cdot 3^9 \cdot 5^4 \cdot 7^2 \cdot 11 \cdot 13 \cdot 23$ |
| Co ₂ | 42305421312000 | ≈ 4×10 ¹³ | 2 ¹⁸ · 3 ⁶ · 5 ³ · 7 · 11 · 23 |
| Co ₃ | 495766656000 | ≈ 5×10 ¹¹ | $2^{10} \cdot 3^7 \cdot 5^3 \cdot 7 \cdot 11 \cdot 23$ |
| O'N | 460815505920 | ≈ 5×10 ¹¹ | $2^9 \cdot 3^4 \cdot 5 \cdot 7^3 \cdot 11 \cdot 19 \cdot 31$ |
| Suz | 448345497600 | ≈ 4×10 ¹¹ | 2 ¹³ · 3 ⁷ · 5 ² · 7 · 11 · 13 |
| Ru | 145926144000 | ≈ 1×10 ¹¹ | $2^{14} \cdot 3^3 \cdot 5^3 \cdot 7 \cdot 13 \cdot 29$ |
| He | 4030387200 | ≈ 4×10 ⁹ | 2 ¹⁰ · 3 ³ · 5 ² · 7 ³ · 17 |
| McL | 898128000 | ≈ 9×10 ⁸ | $2^7 \cdot 3^6 \cdot 5^3 \cdot 7 \cdot 11$ |
| HS | 44352000 | ≈ 4×10 ⁷ | $2^9 \cdot 3^2 \cdot 5^3 \cdot 7 \cdot 11$ |
| J ₄ | 86775571046077562880 | ≈ 9×10 ¹⁹ | $2^{21} \cdot 3^3 \cdot 5 \cdot 7 \cdot 11^3 \cdot 23 \cdot 29 \cdot 31 \cdot 37 \cdot 43$ |
| J₃ or HJM | 50232960 | ≈ 5×10 ⁷ | 2 ⁷ · 3 ⁵ · 5 · 17 · 19 |
| J ₂ or HJ | 604800 | ≈ 6×10 ⁵ | $2^7 \cdot 3^3 \cdot 5^2 \cdot 7$ |
| J ₁ | 175560 | ≈ 2×10 ⁵ | 2 ³ · 3 · 5 · 7 · 11 · 19 |
| M ₂₄ | 244823040 | ≈ 2×10 ⁸ | $2^{10} \cdot 3^3 \cdot 5 \cdot 7 \cdot 11 \cdot 23$ |
| M ₂₃ | 10200960 | ≈ 1×10 ⁷ | $2^7 \cdot 3^2 \cdot 5 \cdot 7 \cdot 11 \cdot 23$ |
| M ₂₂ | 443520 | ≈ 4×10 ⁵ | $2^7 \cdot 3^2 \cdot 5 \cdot 7 \cdot 11$ |
| M ₁₂ | 95040 | ≈ 1×10 ⁵ | 2 ⁶ · 3 ³ · 5 · 11 |
| M ₁₁ | 7920 | ≈ 8×10 ³ | 2 ⁴ · 3 ² · 5 · 11 |

Summary

Groups are the elementary building blocks of structure in mathematics.

Symmetries and systems of transformations always have a group lurking in the background.

Three types of product, subgroups, cosets, normal subgroup, factor group, composition series.

Very powerful and general machinery.

Next time: putting groups to work

- I. Acting on vector spaces
- 2. Representation theory
- 3. Harmonic analysis

