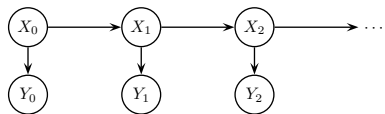


# Particle filtering subject to interaction constraints

Nick Whiteley<sup>\*</sup>, Kari Heine<sup>°</sup>, Anthony Lee<sup>+</sup>

<sup>\*</sup>University of Bristol, <sup>°</sup>UCL, <sup>+</sup>University of Warwick,

# Hidden Markov Model

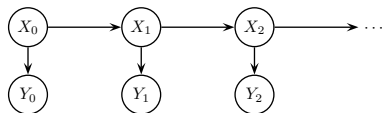


$$X_0 \sim \pi_0$$

$$X_n | X_{n-1} \sim f(X_{n-1}, \cdot)$$

$$Y_n | X_n \sim g(X_n, \cdot)$$

# Hidden Markov Model



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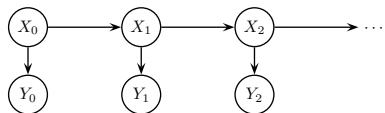
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with  $\mathbb{E}[\cdot]$  w.r.t.  $X_0 \sim \pi_0$ ,  $X_n | X_{n-1} \sim f(X_{n-1}, \cdot)$ ,

$$\begin{aligned} \pi_n(A) &:= \mathbb{P}(X_n \in A | Y_{0:n-1} = y_{0:n-1}) \\ &= \frac{\mathbb{E}[\mathbb{I}[X_n \in A] \prod_{k=0}^{n-1} g(X_k, y_k)]}{\mathbb{E}[\prod_{k=0}^{n-1} g(X_k, y_k)]} \\ &= \frac{\int g(x, y_{n-1}) f(x, A) \pi_{n-1}(dx)}{\int g(x, y_{n-1}) \pi_{n-1}(dx)} = \Phi_n(\pi_{n-1})(A) \end{aligned}$$

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- ▶  $Z_n := \mathbb{E}[\prod_{k=0}^{n-1} g(X_k, y_k)]$
- ▶ write  $g_n(x) := g(x, y_n)$

## Sequential Importance Sampling

---

For  $n = 0$ ,

For  $i = 1, \dots, N$ ,

Set  $W_0^i = 1$ .

Sample  $\zeta_0^i \sim \pi_0$ .

For  $n \geq 1$ ,

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N.B. the  $N$  processes  $(\zeta_n^i; n \geq 0)$ ,  $i = 1, \dots, N$ , are independent.

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$$\pi_n^N := \frac{\sum_i W_n^i \delta_{\zeta_n^i}}{\sum_i W_n^i} \approx \frac{\mathbb{E} [\mathbb{I}[X_n \in \cdot] \prod_{k=0}^{n-1} g_k(X_k)]}{\mathbb{E} [\prod_{k=0}^{n-1} g_k(X_k)]} = \pi_n,$$

$$Z_n^N := \frac{1}{N} \sum_i W_n^i \approx \mathbb{E} \left[ \prod_{k=0}^{n-1} g_k(X_k) \right] = Z_n.$$

## Bootstrap Particle Filter

---

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Recall,

$$\pi_n(A) = \frac{\int g_{n-1}(x) f(x, A) \pi_{n-1}(dx)}{\int g_{n-1}(x) \pi_{n-1}(dx)},$$

so notice

$$\frac{\int g_{n-1}(x) f(x, A) \pi_{n-1}^N(dx)}{\int g_{n-1}(x) \pi_{n-1}^N(dx)} = \frac{\sum_j g_{n-1}(\zeta_{n-1}^j) f(\zeta_{n-1}^j, A)}{\sum_j g_{n-1}(\zeta_{n-1}^j)}$$

N.B. the  $N$  processes  $(\zeta_n^i; n \geq 0)$ ,  $i = 1, \dots, N$ , are *not* independent.

# Convergence and time-uniform convergence

For both SIS and BPF,

1)  $\mathbb{E}[Z_n^N] = Z_n$

2) for bounded  $\varphi : \mathbb{X} \rightarrow \mathbb{R}$  and  $p \geq 1$ ,

$$\sup_{N \geq 1} \sqrt{N} \mathbb{E} \left[ \left| Z_n^N - Z_n \right|^p \right]^{1/p} < +\infty, \quad \sup_{N \geq 1} \sqrt{N} \mathbb{E} \left[ \left| \pi_n^N(\varphi) - \pi_n(\varphi) \right|^p \right]^{1/p} < +\infty,$$

so  $Z_n^N \rightarrow Z_n$  and  $\pi_n^N(\varphi) \rightarrow \pi_n(\varphi)$  as  $N \rightarrow \infty$ , w.p. 1.

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Highly desirable: for sufficiently regular HMM's,

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(Del Moral and Giunnet '01) A sufficient condition is: there exists  $(\delta, \epsilon) \in [1, \infty)^2$  such that

$$f(x, \cdot) \leq \epsilon f(x', \cdot), \quad \forall x, x', \quad \text{and} \quad \sup_{n \geq 0} \sup_{x, x'} \frac{g_n(x)}{g_n(x')} \leq \delta.$$

## Sequential Importance Sampling - quick calculation

---

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$$\sqrt{N} [\pi_n^N(\varphi) - \pi_n(\varphi)] = \sqrt{N} \left[ \frac{\sum_i W_n^i \varphi(\zeta_n^i)}{\sum_i W_n^i} - \pi_n(\varphi) \right] = \frac{\frac{1}{\sqrt{N}} \sum_i W_n^i [\varphi(\zeta_n^i) - \pi_n(\varphi)]}{\frac{1}{N} \sum_i W_n^i}$$

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► Numer. obeys CLT, denom. converges a.s. to  $\mathbb{E}[\prod_{k=0}^{n-1} g_k(X_k)]$ , so

$$\sqrt{N} [\pi_n^N(\varphi) - \pi_n(\varphi)] \xrightarrow[N \rightarrow \infty]{d} \mathcal{N}(0, \sigma_n^2), \quad \sigma_n^2 = \frac{\mathbb{E} [(\varphi(X_n) - \pi_n(\varphi))^2 \prod_{k=0}^{n-1} g_k(X_k)^2]}{\mathbb{E} [\prod_{k=0}^{n-1} g_k(X_k)]^2}.$$

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► If  $f(x, \cdot) = \pi_0(\cdot)$ , and  $g_k = g$ , then

$$\sigma_n^2 = \text{Var}_{\pi_0}(\varphi) \left( \frac{\pi_0(g^2)}{\pi_0(g)^2} \right)^n.$$



# Overview

- ▶ Part I: analysis of a “distributed” particle filter
  - ▶ Bolić et al., *Resampling Algorithms and Architectures for Distributed Particle filters*, IEEE Trans. Sig. Proc. 2005.
  - ▶ Heine and W., *ArXiv imminent*
  
- ▶ Part II: how much interaction is enough?
  - ▶ *On the role of interaction in sequential Monte Carlo algorithms*. W, Lee and Heine. Bernoulli. To appear.

## Part I: analysis of a distributed particle filter

## Local exchange particle filter (Bolić et al., 2005)

- ▶  $N = Mm$  particles in total,  $m \equiv$  no. of “machines”
  - ▶  $\theta \in \{1, \dots, M - 1\}$  is a parameter
  - ▶ write  $y \bmod^* x = y - \lfloor (y - 1)/x \rfloor x$ .
- 

For  $n = 0$ ,

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Set  $W_0^i = 1$  and sample  $\zeta_0^i \sim \pi_0$

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For  $k = 1, \dots, m$

Set  $G_k = \{(k - 1)M + 1, \dots, (k - 1)M + M\}$

For  $n \geq 1$ ,

For  $k = 1, \dots, m$ ,

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Sample  $\zeta_n^i \sim (W_n^i)^{-1} \sum_{j \in G_k} W_{n-1}^{L^j} g_{n-1}(\zeta_{n-1}^{L^j}) f(\zeta_{n-1}^{L^j}, \cdot)$

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---

► N.B.  $W_n^i = W_n^j$  for all  $i, j \in G_k$ , and

$$\mathbb{P}(\zeta_n^i \in \cdot | \zeta_0, \dots, \zeta_{n-1}) = \frac{\sum_{j \in G_k} g_{n-1}(\zeta_{n-1}^j) f(\zeta_{n-1}^j, \cdot)}{\sum_{j \in G_k} g_{n-1}(\zeta_{n-1}^j)}.$$

## A general algorithm - $\alpha$ SMC

- ▶  $\alpha$  is a  $N \times N$  row-stochastic matrix

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# LEPF and IBPF as $\alpha$ SMC

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$$\left( \begin{array}{cccccccccc} 0 & 1/3 & 1/3 & 1/3 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1/3 & 1/3 & 1/3 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1/3 & 1/3 & 1/3 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1/3 & 1/3 & 1/3 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1/3 & 1/3 & 1/3 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1/3 & 1/3 & 1/3 & 0 & 0 & 0 \\ 1/3 & 0 & 0 & 0 & 0 & 0 & 0 & 1/3 & 1/3 & 1/3 \\ 1/3 & 0 & 0 & 0 & 0 & 0 & 0 & 1/3 & 1/3 & 1/3 \\ 1/3 & 0 & 0 & 0 & 0 & 0 & 0 & 1/3 & 1/3 & 1/3 \end{array} \right) \left( \begin{array}{cccccccccc} 1/3 & 1/3 & 1/3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1/3 & 1/3 & 1/3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1/3 & 1/3 & 1/3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1/3 & 1/3 & 1/3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1/3 & 1/3 & 1/3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1/3 & 1/3 & 1/3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1/3 & 1/3 & 1/3 & 1/3 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1/3 & 1/3 & 1/3 & 1/3 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1/3 & 1/3 & 1/3 & 1/3 \end{array} \right)$$

$m = M = 3$ . left:  $\alpha$  for LEPF with  $\theta = 1$ , right:  $\alpha$  for IBPF.

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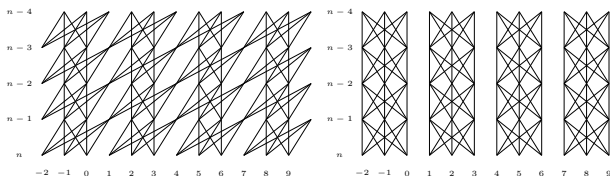
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---



$M = 3$ . left:  $\alpha$  for LEPF with  $\theta = 1$ , right:  $\alpha$  for IBPF.

# Convergence and CLT

---

**Thm.** The following hold for the LEPF and IBPF

- 1) For any  $M, m \geq 1$ ,  $\mathbb{E}[Z_n^{Mm}] = Z_n$
- 2) for bounded  $\varphi : \mathbb{X} \rightarrow \mathbb{R}$  and  $p \geq 1$ ,

$$\sup_{M, m \geq 1} \sqrt{Mm} \mathbb{E} \left[ \left| Z_n^{Mm} - Z_n \right|^p \right]^{1/p} < +\infty$$

$$\sup_{M, m \geq 1} \sqrt{Mm} \mathbb{E} \left[ \left| \pi_n^{Mm}(\varphi) - \pi_n(\varphi) \right|^p \right]^{1/p} < +\infty$$

so  $Z_n^{Mm} \rightarrow Z_n$  and  $\pi_n^{Mm}(\varphi) \rightarrow \pi_n(\varphi)$ , w.p. 1. both:

- ▶ with  $m$  fixed and  $M \rightarrow \infty$ , and
- ▶ with  $M$  fixed and  $m \rightarrow \infty$

- 3) for bounded  $\varphi : \mathbb{X} \rightarrow \mathbb{R}$  and any  $M \geq 2$ ,

$$\sqrt{Mm} \left( \pi_n^{Mm}(\varphi) - \pi_n(\varphi) \right) \xrightarrow[m \rightarrow \infty]{d} \mathcal{N}(0, \sigma_n^2),$$

with  $\sigma_n^2$  depending on  $\varphi$ ,  $M$  (and  $\theta$  in the case of the LEPF)

## Time-uniform convergence

---

**Thm.** The following hold for the IBPF and LEPF

1) If there exists  $(\delta, \epsilon) \in [1, \infty)^2$  such that

$$f(x, \cdot) \leq \epsilon f(x', \cdot), \quad \forall x, x', \quad \text{and} \quad \sup_{n \geq 0} \sup_{x, x'} \frac{g_n(x)}{g_n(x')} \leq \delta, \quad (1)$$

then for any  $m \geq 1$ ,  $p \geq 1$  and bounded  $\varphi : \mathbb{X} \rightarrow \mathbb{R}$ ,

$$\sup_{M \geq 1} \sup_{n \geq 0} \sqrt{M} \mathbb{E} \left[ \left| \pi_n^{Mm}(\varphi) - \pi_n(\varphi) \right|^p \right]^{1/p} < +\infty$$

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2) but, there exist models satisfying (1) such that for any  $\varphi$  such that  $\text{Var}_{\pi_0}(\varphi) > 0$ , and any  $M \geq 1$  and  $p \geq 1$ ,

$$\limsup_{m \rightarrow \infty} \sup_{n \geq 0} \sqrt{m} \mathbb{E} \left[ \left| \pi_n^{Mm}(\varphi) - \pi_n(\varphi) \right|^p \right]^{1/p} = +\infty.$$

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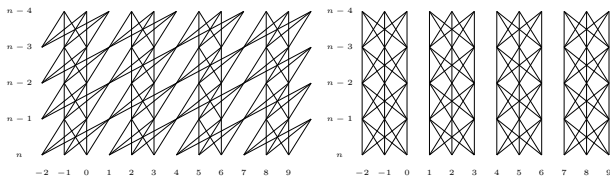
to establish 2), it turns out to be sufficient to construct a model such that

$$\lim_{n \rightarrow \infty} \sigma_n^2 = +\infty \dots$$

## Asymptotic variance in a simplified case

- Introduce the “limiting”  $\alpha$  matrix for the LEPF (for IBPF set  $\theta = 0$ ):

$$\alpha_{\infty}^{ij} := M^{-1} \mathbb{I}[\lfloor (i-1)/M \rfloor = \lfloor (j-\theta-1)/M \rfloor], \quad i, j \in \mathbb{Z}$$



- Let  $(I_k, J_k)_{0 \leq k \leq n}$  be the bi-variate, backward Markov chain:

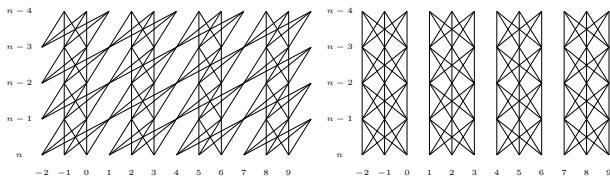
$$(I_n, J_n) \sim \delta_0 \otimes \delta_0, \quad \mathbb{P}(I_k = i_k, J_k = j_k | I_{k+1} = i_{k+1}, J_{k+1} = j_{k+1}) = \alpha_{\infty}^{i_{k+1}i_k} \alpha_{\infty}^{j_{k+1}j_k},$$

- Define the collision count:  $Z_n = \sum_{k=0}^{n-1} \mathbb{I}[I_k = J_k]$

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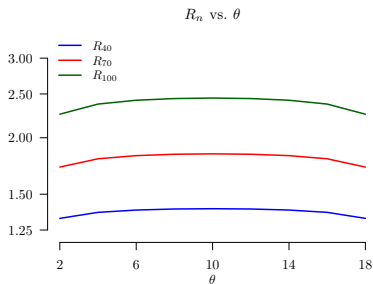
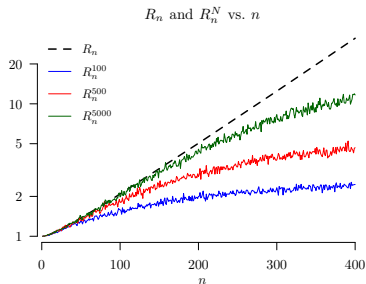
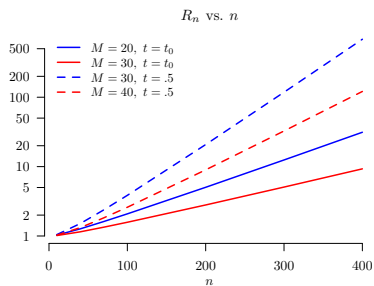
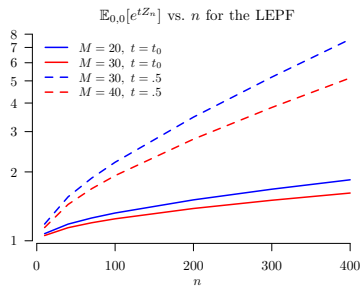
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- Define the collision count:  $Z_n = \sum_{k=0}^{n-1} \mathbb{I}[I_k = J_k]$
- Assume  $f(x, \cdot) = \pi_0(\cdot)$  and  $g_n = g$ , then

$$\sigma_n^2 = \text{Var}_{\pi_0}(\varphi) \mathbb{E}_{0,0} \left[ e^{tZ_n} \right], \quad t := \log \frac{\pi_0(g^2)}{\pi_0(g)^2}.$$

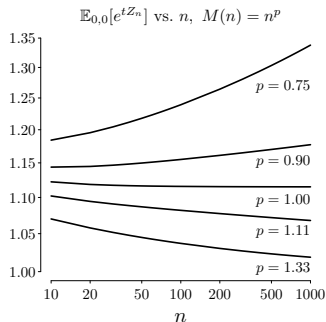
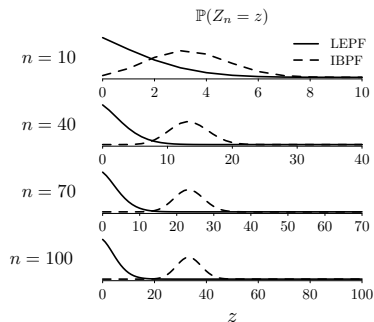
# Numerical comparisons



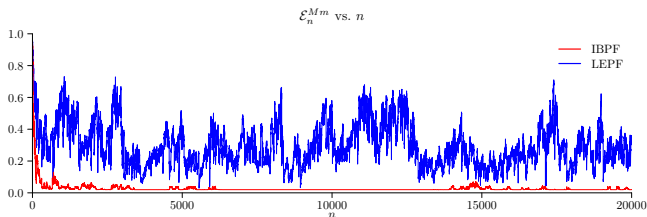
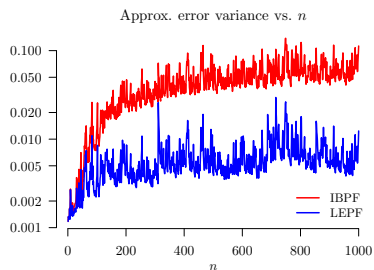
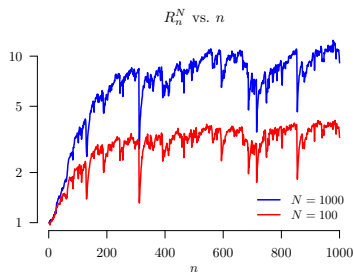


# Numerical comparisons

- ▶  $Z_n = \sum_{k=0}^{n-1} \mathbb{I}[I_k = J_k]$
- ▶ For the IBPF,  $Z_n \sim \text{Binomial}(n, M^{-1})$
- ▶  $\sigma_n^2 = \text{Var}_{\pi_0}(\varphi) \mathbb{E}_{0,0} [e^{tZ_n}]$ ,  $t := \log \frac{\pi_0(g^2)}{\pi_0(g)^2}$ .



# Simulation example



$$\mathcal{E}_n^N = \frac{\left(N^{-1} \sum_{i=1}^N W_n^i\right)^2}{N^{-1} \sum_{i=1}^N (W_n^i)^2} \in [0, 1],$$

$$\pi_n^N = \frac{\sum_{i=1}^N W_n^i \delta_{\zeta_n^i}}{\sum_{i=1}^N W_n^i}.$$

## Part II: how much interaction is enough?

## $\alpha$ SMC - a general algorithm

Let  $\mathbb{A}_N$  be a set of Markov transition matrices, each of size  $N \times N$

---

For  $n = 0$ ,

For  $i = 1, \dots, N$ ,

Set  $W_0^i = 1$

Sample  $\zeta_0^i \sim \pi_0$

For  $n \geq 1$ ,

Select  $\alpha_{n-1}$  from  $\mathbb{A}_N$  according to some given functional of  $\{\zeta_0, \dots, \zeta_{n-1}\}$

For  $i = 1, \dots, N$ ,

Set  $W_n^i = \sum_j \alpha_{n-1}^{ij} W_{n-1}^j g_{n-1}(\zeta_{n-1}^j)$

Sample  $\zeta_n^i \sim \frac{\sum_j \alpha_{n-1}^{ij} W_{n-1}^j g_{n-1}(\zeta_{n-1}^j) f(\zeta_{n-1}^j, \cdot)}{W_n^i}$

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- ▶ If  $\mathbb{A}_N = \{Id\}$ ,  $\alpha$ SMC  $\equiv$  sequential importance sampling
- ▶ If  $\mathbb{A}_N = \{\mathbf{1}_{1/N}\}$ ,  $\alpha$ SMC  $\equiv$  bootstrap particle filter

( $\mathbf{1}_{1/N}$  is the matrix with  $1/N$  as every entry)

## Adaptive Resampling PF (Liu and Chen '95) as $\alpha$ SMC

- ▶ Adaptive Resampling PF is an instance of  $\alpha$ SMC with  $\tau \in (0, 1]$  a threshold,  $\mathbb{A}_N = \{Id, \mathbf{1}_{1/N}\}$ , and

$$\alpha_{n-1} := \begin{cases} \mathbf{1}_{1/N}, & \text{if } \frac{\left(N^{-1} \sum_i W_{n-1}^i g_{n-1}(\zeta_{n-1}^i)\right)^2}{N^{-1} \sum_i \left(W_{n-1}^i g_{n-1}(\zeta_{n-1}^i)\right)^2} < \tau. \\ Id, & \text{otherwise.} \end{cases}$$

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$$\mathcal{E}_n^N := \frac{(N^{-1} \sum_i W_n^i)^2}{N^{-1} \sum_i (W_n^i)^2} = \frac{(N^{-1} \sum_i \sum_j \alpha_{n-1}^{ij} W_{n-1}^j g_{n-1}(\zeta_{n-1}^j))^2}{N^{-1} \sum_i (\sum_j \alpha_{n-1}^{ij} W_{n-1}^j g_{n-1}(\zeta_{n-1}^j))^2} \in [0, 1]$$

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- ▶ So ARPF can be viewed as **enforcing**:

$$\inf_n \mathcal{E}_n^N \geq \tau$$

## Convergence of $\alpha$ SMC

**(A)** - the entries of the  $\mathbb{A}_N$ -valued random matrix  $\alpha_{n-1}$  are measurable w.r.t.  $\mathcal{F}_{n-1} = \sigma(\zeta_0, \dots, \zeta_{n-1})$

**(B)** - every member of  $\mathbb{A}_N$  is doubly stochastic

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## Uniform-convergence of $\alpha$ SMC

(C) There exists  $(\delta, \epsilon) \in [1, \infty)^2$  such that

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**Thm.** Assume (A), (B) and (C). Then there exist finite constants,  $c_1$  and for each  $p \geq 1$ ,  $c_2(p)$ , such that for any  $\tau \in (0, 1]$ ,  $N \geq 1$ , and bounded  $\varphi : \mathbb{X} \rightarrow \mathbb{R}$

$$\inf_{n \geq 0} \mathcal{E}_n^N \geq \tau \quad \Rightarrow \quad \left\{ \begin{array}{l} \sup_{n \geq 1} \mathbb{E} \left[ \left( \frac{Z_n^N}{Z_n} \right)^2 \right]^{1/n} \leq 1 + \frac{c_1}{N\tau}, \\ \text{and} \\ \sup_{n \geq 0} \mathbb{E} [ |\pi_n^N(\varphi) - \pi_n(\varphi)|^p ]^{1/p} \leq \|\varphi\| \frac{c_2(p)}{\sqrt{N\tau}}. \end{array} \right.$$

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---

**Cor.**

$$\inf_{n \geq 0} \mathcal{E}_n^N \geq \tau \quad \text{and} \quad N\tau \geq nc_1 \quad \Rightarrow \quad \mathbb{E} \left[ \left( \frac{Z_n^N}{Z_n} - 1 \right)^2 \right] \leq \frac{2nc_1}{N\tau}.$$

## Design of $\alpha$ SMC

	SIS	PF	Adaptive Resampling PF	new instances of $\alpha$ SMC
$\mathbb{A}_N$	$\{Id\}$	$\{\mathbf{1}_{1/N}\}$	$\{Id, \mathbf{1}_{1/N}\}$	a matter of design
$\alpha_n$ chosen from $\mathbb{A}_N$ according to some function of $\{\zeta_0, \dots, \zeta_n\}$	✓	✓	✓	easy to verify
$\mathbb{A}_N$ contains only doubly stochastic matrices	✓	✓	✓	easy to verify
$\inf_{n \geq 0} \mathcal{E}_n^N > 0$ enforced	×	✓	✓	a matter of design

## Example of adaptive interaction

- ▶ assume  $N = 2^m$ ,  $m \in \mathbb{N}$  and let

$$\mathbb{A}_N = \{Id, a(1), \dots, a(m-1), \mathbf{1}_{1/N}\},$$

with

$$a(k) = \begin{bmatrix} \mathbf{1}_{1/2^k} & \mathbf{0} & \cdots & \mathbf{0} \\ \mathbf{0} & \mathbf{1}_{1/2^k} & \cdots & \mathbf{0} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{0} & \mathbf{0} & \cdots & \mathbf{1}_{1/2^k} \end{bmatrix}, \quad k = 0, \dots, m,$$

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- ▶ A simple adaptation rule:
  - ▶ at each time-step, increase  $k_n$  until  $\alpha_n = a(k_n)$  satisfies  $\mathcal{E}_n^N \geq \tau$
  - ▶ overall serial complexity is  $O(N)$

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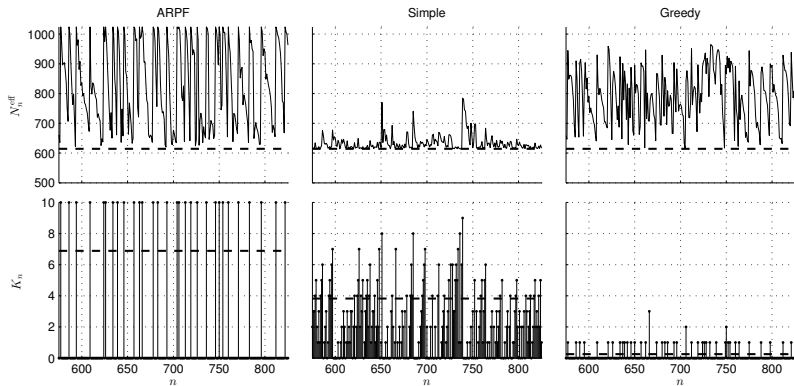
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  - ▶ overall serial complexity is  $O(N)$
- ▶ A greedy adaptation rule:
  - ▶ as above, but make pairs, pairs-of pairs, etc. by matching big weights with small weights
  - ▶ overall worst case serial complexity is  $O(N \log_2 N)$

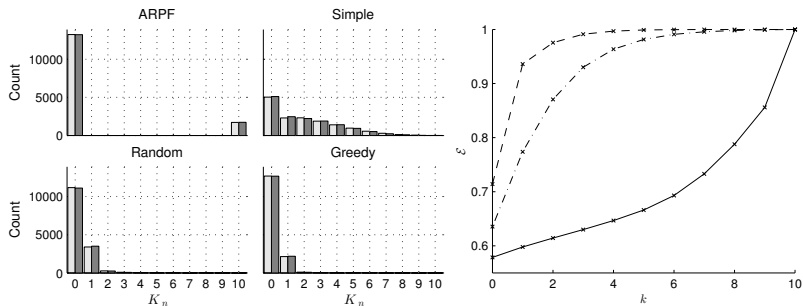
# Numerical illustrations for SV model, $N = 1024$ , $\tau = 0.6$



Top:  $N_n^{\text{eff}} = N\mathcal{E}_n^N$  vs. time.

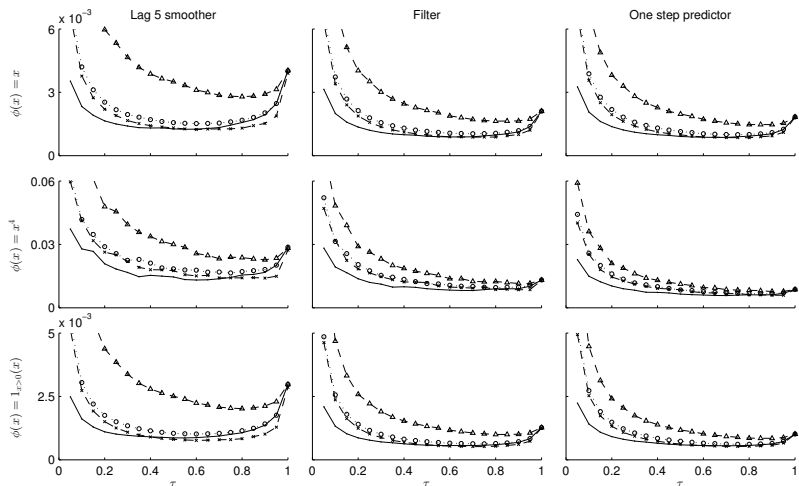
Bottom:  $K_n$  vs. time. (degree of interaction is  $2^{K_n}$ )

# Numerical illustrations for SV model, $N = 1024$ , $\tau = 0.6$



Left: histograms of  $K_n$  over time steps  $0$  to  $15 \times 10^3$  and  $15 \times 10^3$  to  $3 \times 10^4$   
Right: solid=simple, dash-dot=random, dash=greedy

# Numerical illustrations for SV model, $N = 1024$



time-averaged mean square filtering errors vs.  $\tau$

Right:  $\triangle$  =simple,  $\circ$  =random,  $\times$  =greedy