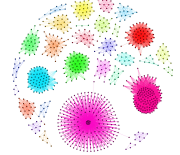
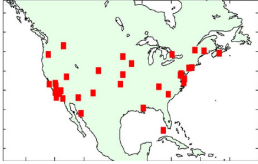


Optimal Regression on Sets

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- ▶ Example: aerosol prediction \Rightarrow regression on labelled bags.



- ▶ Bag-of-objects representation: experimental design, computer vision, NLP, networks.

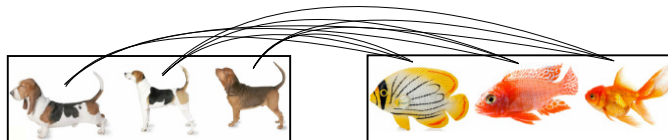
- ▶ Problem formulation:

- Labelled training bags: $\hat{\mathbf{z}} = \{(\hat{P}_i, y_i)\}_{i=1}^\ell$. Test bag: \hat{P} . $N := |\hat{P}_i|$.
- Estimator, prediction:

$$f_{\hat{\mathbf{z}}}^\lambda = \arg \min_{f \in \mathcal{H}(K)} \frac{1}{\ell} \sum_{i=1}^\ell \left[f(\underbrace{\mu_{\hat{P}_i}}_{\text{feature of } \hat{P}_i}) - y_i \right]^2 + \lambda \|f\|_{\mathcal{H}}^2,$$

$$\hat{y}(\hat{P}) = \mathbf{g}^T (\mathbf{G} + \ell \lambda \mathbf{I})^{-1} \mathbf{y}, \quad \mathbf{g} = [K(\mu_{\hat{P}}, \mu_{\hat{P}_i})], \quad \mathbf{G} = [K(\mu_{\hat{P}_i}, \mu_{\hat{P}_j})], \quad \mathbf{y} = [y_i].$$

- Similarity of distributions: $K(P, Q) = \mathbb{E}_{a \sim P, b \sim Q} k(a, b) = \left\langle \underbrace{\mathbb{E}_a \varphi(a)}_{\text{feature of distribution } P =: \mu_P}, \mathbb{E}_b \varphi(b) \right\rangle$.



- Quality of estimator: $\mathcal{R}(f) = \mathbb{E}_{(\mu_P, y) \sim \rho} [f(\mu_P) - y]^2$, $f_\rho =$ best regressor.

- ▶ Known: assuming $f_\rho \in \mathcal{H}$

- best/achieved rate: $\mathcal{R}(f_{\hat{\mathbf{z}}}^\lambda) - \mathcal{R}(f_\rho) = \mathcal{O}\left(\ell^{-\frac{bc}{bc+1}}\right)$,
- b – size of the input space, c – smoothness of f_ρ .

- ▶ **Our result:**

- With $N = \tilde{\mathcal{O}}(\ell^a)$ and $2 \leq a$, $f_{\hat{\mathbf{z}}}^\lambda$ has the **best achievable rate**; $a = \frac{b(c+1)}{bc+1} < 2 : \checkmark$
- \Rightarrow Regression with set kernel is consistent (17-year-old open problem).
- Practical: state-of-the-art aerosol prediction.

- ▶ Details (JMLR submission), code (in ITE):

<http://arxiv.org/abs/1411.2066>, <https://bitbucket.org/szzoli/ite/>

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