Assignment 1 Theoretical Neuroscience [Gatsby]

TAs:

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1. Subthreshold neurons

As we saw in class, the membrane potential, V, of a totally passive neuron (with external input) obeys the equation

$$\tau \frac{dV}{dt} = -(V - \mathcal{E}_L) + V_{in}(t) \tag{1}$$

where $V_{in}(t)$ is the external input. Show that this has the solution

$$V(t) = \mathcal{E}_L + (V(t_0) - \mathcal{E}_L)e^{-(t-t_0)/\tau} + \int_{t_0}^t \frac{dt'}{\tau} e^{(t'-t)/\tau} V_{in}(t').$$
 (2)

Show that under the change of variables t' = t - s, this becomes

$$V(t) = \mathcal{E}_L + (V(t_0) - \mathcal{E}_L)e^{-(t-t_0)/\tau} + \int_0^{t-t_0} \frac{ds}{\tau} e^{-s/\tau} V_{in}(t-s).$$
 (3)

This has an especially nice form in the limit $t_0 \to -\infty$,

$$V(t) = \mathcal{E}_L + \int_0^\infty \frac{ds}{\tau} e^{-s/\tau} V_{in}(t-s).$$
(4)

2. The Hodgkin-Huxley neuron

Numerically integrate the Hodgkin-Huxley equations with matlab (or your favorite package). If you're using matlab, it's a good idea to use the Matlab ode45 function, or if you're using Python, scipy.solve_ivp. The equations are:

$$C\frac{dV}{dt} = -\overline{g}_{Na}m^{3}h(V - E_{Na}) - \overline{g}_{K}n^{4}(V - E_{K}) - \overline{g}_{L}(V - E_{L}) + I_{stim}$$

$$\frac{dx}{dt} = \alpha_{x}(1 - x) - \beta_{x}x \quad \text{where } x \text{ is } m, n \text{ or } h$$

$$\alpha_{n}(V) = 0.01(V + 55)/[1 - \exp(-(V + 55)/10)]$$

$$\beta_{n}(V) = 0.125 \exp(-(V + 65)/80)$$

$$\alpha_{m}(V) = 0.1(V + 40)/[1 - \exp(-(V + 40)/10)]$$

$$\beta_{m}(V) = 4 \exp(-(V + 65)/18)$$

$$\alpha_{h}(V) = 0.07 \exp(-(V + 65)/20)$$

$$\beta_{h}(V) = 1/[\exp(-(V + 35)/10) + 1]$$

Let $C=10~\mathrm{nF/mm^2}$, $\overline{g}_L=.003~\mathrm{mS/mm^2}$, $\overline{g}_K=0.36~\mathrm{mS/mm^2}$, $\overline{g}_{Na}=1.2~\mathrm{mS/mm^2}$, $E_K=-77~\mathrm{mV}$, $E_L=-54.387~\mathrm{mV}$, and $E_{Na}=50~\mathrm{mV}$. Use an integration time step of 0.1 ms.

Remember to keep your units consistent. F/S = Farad/Siemens = 1 second.

- (a) Run the simulations with $I_{stim} = 200 \text{ nA/mm}^2$. Plot the membrane potential (V) and gating variables (m, h, and n) versus time.
- (b) Write down expressions for the equilibrium values of the gating variables $(m_{\infty}, h_{\infty}, \text{ and } n_{\infty})$, and plot them versus voltage.
- (c) Plot the firing rate versus I_{stim} , up to a firing rate of 50 Hz. The firing rate should jump suddenly from zero to a non-zero value. This is called a type II behavior. Type I behavior is when the firing rate begins at zero and increases continuously without any jumps.
- (d) What happens to the plot of firing rate versus I_{stim} as you decrease \overline{g}_K ?
- (e) Spikes are initiated at the axon hillock, where the axon meets the soma. This is because \overline{g}_{Na} is very high there. What happens to the plot of firing rate versus I_{stim} as you increase \overline{g}_{Na} ?

3. The linear integrate and fire neuron

An approximate treatment of spiking neurons is to think of them as passively integrating input and, when the voltage crosses threshold, emitting a spike. This leads to the linear integrate and fire neuron (sometimes called the leaky integrate and fire neuron, and often abbreviated LIF), which obeys the equation

$$C\frac{dV}{dt} = -g_L(V - \mathcal{E}_L) + I_0.$$

This is just the "linear integrate" part. To incorporate spikes, when the voltage gets to threshold (V_t) , the neuron emits a spike and the voltage is reset to rest (V_r) .

(a) Compute the firing rate of the neuron as a function of I_0 . This firing rate will be parameterized by three numbers: \mathcal{E}_L , V_t , and V_r .

Hint #1: The firing rate is the inverse of the time it takes to go from V_r to V_t .

Hint # 2: Changing variables, and defining new quantities, almost always makes life easier. For example, you might let $v = V - \mathcal{E}_L$ and define $V_0 \equiv I_0/g_L$ and $\tau \equiv C/g_L$.

- (b) Let $I(t) = g_L V_0 \sin(\omega t)$, $V_r = \mathcal{E}_L$, $V_t = \mathcal{E}_L + \Delta V$, and define $C/g_L \equiv \tau$. Start with $V_0 = 0$ and integrate for a long enough time that the neuron equilibrates. Then increase V_0 very slowly compared to the time constant, τ . Show that the neuron will start spiking repetitively when $V_0 > (1 + \tau^2 \omega^2)^{1/2} \Delta V$.
- 4. Warmup nullclines. Consider a model that is bound to come up again, in one form or another,

$$\tau_x \frac{dx}{dt} = -x + \tanh(\beta(x - y))$$
$$\tau_y \frac{dy}{dt} = -y + \alpha x.$$

For all questions, assume $\alpha > 0$ and $\beta > 1$.

- (a) Draw the nullclines for an α and β of your choice.
- (b) What are the conditions on α and β for there to be three fixed points?
- (c) Assume α and β are such that there are three fixed points. Determine the stability of each of them. Draw trajectories starting near x = y = 0.
- (d) Assume α and β are such that there is one fixed point. Determine its stability. Draw trajectories starting near x = y = 0.
- 5. And more nullclines. Assume that the x and y nullclines are given by

$$y = a_x x$$
 x-nullcline (7a)

$$y = a_y x$$
 y-nullcline. (7b)

The nullclines cross at x = y = 0, so that's a fixed point (the only one). Its stability depends on the dynamics. Define

$$s_x \equiv \left. \frac{dx}{dt} \right|_{x > 0} \tag{8a}$$

$$s_x \equiv \frac{dx}{dt} \Big|_{x>0}$$

$$s_y \equiv \frac{dy}{dt} \Big|_{y>0} .$$
(8a)

There are four main possibilities:

$$(s_x, s_y) = (\text{positive, positive}), (\text{positive, negative}), (\text{negative, positive}), (\text{negative, negative}).$$
 (9)

For each of these, determine, if possible, the sign of the trace and determinant of the linear dynamics, and thus the number of positive and negative eigenvalues, for:

1.
$$a_x > 0$$
 and $a_y < 0$ (10a)

2.
$$a_x < a_y < 0$$
 (10b)

3.
$$a_y < a_x < 0$$
. (10c)

Note the "if possible" part – that's because in some cases the trace and/or determinant can have either

There are 12 possible cases, which seems like a lot, but you'll quickly see patterns.

6. Hodgkin-Huxley nullclines. Consider a simplified Hodgkin-Huxley type model,

$$\tau \frac{dV}{dt} = -(V - \mathcal{E}_L) - hm(V)V$$

$$\tau_h \frac{dh}{dt} = h_\infty(V) - h$$

$$m(V) = \frac{1}{1 + \exp(-(V - V_t)/\epsilon_m)}$$

$$h_\infty(V) = \frac{1}{1 + \exp(+(V - V_h)/\epsilon_h)}$$

with parameters

$$\begin{split} \mathcal{E}_L &= -65 \text{ mV} \\ V_t &= -50 \text{ mV} \\ \epsilon_h &= 10 \text{ mV} \\ \epsilon_m \ll 1 \text{ mV} \,. \end{split}$$

The remaining parameter, V_h , will be specified as needed (it will take on a range of values).

- (a) Sketch the nullclines in V-h space for $V_h = -60, -50$ and -40 mV. Put voltage on the x-axis and h on the y-axis. For each equilibrium, tell us whether it is stable or unstable, or hard to tell without a detailed stability analysis.
- (b) Find the condition on V_h that guarantees more than one equilibrium.
- (c) For a value of V_h (which you choose) such that there is more than one equilibrium, sketch the trajectories starting at V slightly greater than V_t and h = 1.

7. Green functions

Consider the equation

$$\tau \frac{\partial G(x,t)}{\partial t} = \lambda^2 \frac{\partial^2 G(x,t)}{\partial x^2} - G(x,t) + \delta(x)\delta(t).$$

Assume G(x,t) satisfies this equation. Now consider a second equation,

$$\tau \frac{\partial U(x,t)}{\partial t} = \lambda^2 \frac{\partial^2 U(x,t)}{\partial x^2} - U(x,t) + i_e(x,t)r_m.$$

Show that

$$U(x,t) = \int dx'dt' G(x-x',t-t')i_e(x',t')r_m.$$

G(x,t) is known as the Green function, and it's occasionally very useful. As in the next problem.

8. Dendrites.

As you'll recall from lecture notes (see also http://www.gatsby.ucl.ac.uk/ \sim pel/tn/notes/biocables.pdf), the passive cable equation is

$$\tau \frac{\partial u(x,t)}{\partial t} = \lambda^2 \frac{\partial^2 u(x,t)}{\partial x^2} - u(x,t) + i_e(x,t)r_m$$

where u(x,t) is the membrane potential relative to rest, $i_e(x,t)$ is the injected current density, and r_m is the specific membrane resistance (it's proportional to actual resistance times area).

Let's assume that $i_e(x,t)$ is produced by a fast synapse – like AMPA. Because of the "fast" part, we'll approximate the current density by

$$i_e(x,t) = \alpha e^{-x^2/2d^2} \delta(t)$$

where $\delta(t)$ is the Dirac delta function. Write down an expression for u(0,t).