### Interpretable comparison of distributions and models

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NeurIPS, Vancouver, 2019

### A motivation: comparing two samples

Given: Samples from unknown distributions P and Q.
Goal: do P and Q differ?



A motivation: comparing a sample and a model

Given: Sample from unknown Q, model P
Goal: do P and Q differ?



### A real-life example: two-sample tests

- Have: Two collections of samples X, Y from unknown distributions P and Q.
- **Goal:** do P and Q differ?





#### MNIST samples

Samples from a GAN

### Significant difference in GAN and MNIST?

T. Salimans, I. Goodfellow, W. Zaremba, V. Cheung, A. Radford, Xi Chen, NIPS 2016 Sutherland, Tung, Strathmann, De, Ramdas, Smola, G., ICLR 2017.

### Outline

#### Divergence measures

- Integral probability metrics
- $\phi$ -divergences (f-divergences)

#### Statistical hypothesis testing

- Using integral probability metrics
- Learned features for powerful tests
- Relation of testing and classification

#### Linear-time features and model criticism

- Interpretable, linear time features for testing
- Stein's method for model evaluation

## Divergence measures





#### Divergences



#### Divergences: integral probability metrics



Are P and Q different?



Are P and Q different?



Integral probability metric:

Find a "well behaved function" f(x) to maximize

#### $\mathbf{E}_{P}f(X) - \mathbf{E}_{Q}f(Y)$



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#### The MMD: an integral probability metric

Maximum mean discrepancy: smooth function for P vs Q

$$egin{aligned} MMD(P,oldsymbol{Q};F) := \sup_{\|f\|\leq 1} \left[ \mathbf{E}_P f(X) - \mathbf{E}_{oldsymbol{Q}} f(Y) 
ight] \ (F = ext{unit ball in RKHS } \mathcal{F}) \end{aligned}$$

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Functions are linear combinations of features:

$$f(x) = \langle f, \varphi(x) \rangle_{\mathcal{F}} = \sum_{\ell=1}^{\infty} f_{\ell} \varphi_{\ell}(x) = \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ \vdots \end{bmatrix}^{\mathsf{T}} \begin{bmatrix} \varphi_1(x) & \uparrow & \uparrow \\ \varphi_2(x) & \uparrow & \uparrow \\ \varphi_3(x) & \uparrow & \downarrow \\ \varphi_3(x) & \uparrow & \downarrow \\ \vdots & \downarrow \end{bmatrix}$$
$$\|f\|_{\mathcal{F}}^2 := \sum_{i=1}^{\infty} f_i^2 \le 1$$

Infinitely many features using kernels

Kernels: dot products of features

Feature map  $\varphi(x) \in \mathcal{F}$ ,

$$arphi(x) = [\dots arphi_i(x) \dots] \in \ell_2$$

For positive definite k,

$$k(x,x')=\langle arphi(x),arphi(x')
angle_{\mathcal{F}}$$

Infinitely many features  $\varphi(x)$ , dot product in closed form!

### Infinitely many features using kernels

Kernels: dot products of features

Exponentiated quadratic kernel

$$k(x,x') = \exp\left(-\gamma \left\|x-x'
ight\|^2
ight)$$



Features: Gaussian Processes for Machine learning, Rasmussen and Williams, Ch. 4. 15/34

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For characteristic RKHS  $\mathcal{F}$ , MMD(P, Q; F) = 0 iff P = Q

Other choices for witness function class:

Bounded continuous [Dudley, 2002] Bounded varation 1 (Kolmogorov metric) [Müller, 1997] Lipschitz (Wasserstein distances) [Dudley, 2002]

Energy distance is a special case [Sejdinovic, Sriperumbudur, G. Fukumizu, 2013] 16/34

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ight] \ (F = ext{unit ball in RKHS } \mathcal{F}) \end{aligned}$$

Expectations of functions are linear combinations of expected features

$$\mathbf{E}_{P}(f(X)) = \langle f, \mathbf{E}_{P} arphi(X) 
angle_{\mathcal{F}} = \langle f, oldsymbol{\mu}_{P} 
angle_{\mathcal{F}}$$

(always true if kernel is bounded)

The MMD:

 $egin{aligned} & MMD(P, \, oldsymbol{Q}; \, F) \ &= \sup_{\| f \| \leq 1} \left[ \mathbf{E}_P f(X) - \mathbf{E}_{oldsymbol{Q}} f(\, Y) 
ight] \end{aligned}$ 



#### The MMD:

#### use

MMD(P, Q; F)

- $= \sup_{\|f\|\leq 1} \left[ \mathbf{E}_{P} f(X) \mathbf{E}_{\mathcal{Q}} f(Y) 
  ight]$
- $= \sup_{\|f\|\leq 1} ig\langle f, \mu_P \mu_Q ig
  angle_{\mathcal{F}}$

 $\mathbf{E}_{P}f(X) = \langle \boldsymbol{\mu}_{P}, f \rangle_{\mathcal{F}}$ 

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#### The MMD:

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- $= \sup_{\|f\|\leq 1} \langle f, \mu_P \mu_Q 
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- $= \|\mu_P \mu_Q\|$

#### IPM view equivalent to feature mean difference (kernel case only)









Recall the witness function expression

 $f^* \propto \mu_P - \mu_Q$ 

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The empirical feature mean for P

$$\widehat{\mu}_P := rac{1}{n}\sum_{i=1}^n arphi(x_i)$$

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The empirical witness function at v

$$egin{aligned} &f^*(v) = \langle f^*, arphi(v) 
angle_\mathcal{F} \ &\propto \langle \widehat{\mu}_P - \widehat{\mu}_{\mathcal{Q}}, arphi(v) 
angle_\mathcal{F} \end{aligned}$$

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The empirical feature mean for P

$$\widehat{\mu}_P := rac{1}{n}\sum_{i=1}^n arphi(x_i)$$

The empirical witness function at v

$$egin{aligned} f^*(v) &= \langle f^*, arphi(v) 
angle_{\mathcal{F}} \ &\propto \langle \widehat{\mu}_P - \widehat{\mu}_Q, arphi(v) 
angle_{\mathcal{F}} \ &= rac{1}{n} \sum_{i=1}^n k(oldsymbol{x}_i, v) - rac{1}{n} \sum_{i=1}^n k(oldsymbol{y}_i, v) \end{aligned}$$

Don't need explicit feature coefficients  $f^* := \begin{bmatrix} f_1^* & f_2^* & \dots \end{bmatrix}$ 

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# IPMs in practice

### How do the IPMs behave?

• A simple setting: distributions with disjoint support, Q approaches P



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#### How does the Wasserstein-1 behave?



$$W_1(P, oldsymbol{Q}) = \sup_{\|f\|_L \leq 1} E_P f(X) - E_oldsymbol{Q} f(Y). \ \|f\|_L \coloneqq \sup_{x 
eq y} |f(x) - f(y)| / \|x - y\|$$

 $W_1 = 0.88$ 



M. Cuturi, J. Solomon, NeurIPS tutorial (2017)

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 $W_1 = 0.65$ 



Santambrogio, Optimal Transport for Applied Mathematicians (2015, Section 5.4)G Peyré, M Cuturi, Computational Optimal Transport (2019)M. Cuturi, J. Solomon, NeurIPS tutorial (2017)



MMD with a broad kernel:  $MMD(P, Q) = \sup_{||f||_{\mathcal{F}} \leq 1} E_P f(X) - E_Q f(Y).$ 

MMD=1.8





MMD with a broad kernel::  $MMD(P, Q) = \sup_{||f||_{\mathcal{F}} \leq 1} E_P f(X) - E_Q f(Y)$ 

MMD=1.1





MMD(P, Q) with a narrow kernel.

#### MMD=0.64





MMD(P, Q) with a narrow kernel.

#### MMD=0.64



### The $\phi$ -divergences



#### The $\phi$ -divergences

Define the  $\phi$ -divergence(*f*-divergence):

$$D_{\phi}(P,Q) = \int \phi\left(rac{dP}{dQ}
ight) dQ = \int \phi\left(rac{p(x)}{q(x)}
ight) q(x) dx$$

where  $\phi$  is convex, lower-semicontinuous,  $\phi(1) = 0$ .

**Example:**  $\phi(x) = -\log(x)$  gives reverse KL divergence,

$$D_{KL}(oldsymbol{Q},P) = \int \log\left(rac{q(x)}{p(x)}
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### How do $\phi$ -divergences behave?



#### Simple example: disjoint support, revisited.

Goodfellow et al. (NeurIPS 2014), Arjovsky and Bottou [ICLR 2017]





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Case of the reverse KL

$$D_{KL}(oldsymbol{Q},P) = \int oldsymbol{q}(z) \log\left(rac{oldsymbol{q}(z)}{oldsymbol{p}(z)}
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Nguyen, Wainwright, Jordan, IEEE Transactions on Information Theory (2010); Nowozin, Cseke, Tomioka, NeurIPS (2016)

Case of the reverse KL

$$egin{aligned} D_{KL}(oldsymbol{Q},oldsymbol{P}) &= \int oldsymbol{q}(z)\log\left(rac{oldsymbol{q}(z)}{oldsymbol{p}(z)}
ight)dz \ &\geq \sup_{f < 0, f \in \mathcal{H}} \mathbf{E}_{P}f(X) + \mathbf{E}_{oldsymbol{Q}} \underbrace{\log\left(-f(oldsymbol{Y})
ight) + 1}_{-\phi^*(f(oldsymbol{Y}))} \end{aligned}$$

Nguyen, Wainwright, Jordan, IEEE Transactions on Information Theory (2010); 27/34 Nowozin, Cseke, Tomioka, NeurIPS (2016)

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ight) + 1 \end{aligned}$$

Bound tight when:

$$f^\diamond(z) = -rac{m{q}(z)}{m{p}(z)}$$



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ight) + 1 & x_i \stackrel{ ext{i.i.d.}}{\sim} P \ &y_i \stackrel{ ext{i.i.d.}}{\sim} Q \ &lpha \sup_{f < 0, f \in \mathcal{H}} \left[rac{1}{n}\sum_{j=1}^n f(x_i) + rac{1}{n}\sum_{i=1}^n \log(-f(y_i))
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This is a

 $\mathbf{K}\mathbf{L}$ 

Approximate

Lower-bound

Estimator.

Case of the reverse KL

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ight) + 1 \ &pprox \sup_{f < 0, f \in \mathcal{H}} \left[rac{1}{n}\sum_{j=1}^n f(x_i) + rac{1}{n}\sum_{i=1}^n \log(-f(y_i))
ight] + 1 \end{split}$$

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 $\mathbf{K}$ 

 $\mathbf{A}$ 

 $\mathbf{L}$ 

 $\mathbf{E}$ 

Case of the reverse KL

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ight) + 1 \ &pprox \sup_{f < 0, f \in \mathcal{H}} \left[rac{1}{n}\sum_{j=1}^{n}f(x_{i}) + rac{1}{n}\sum_{i=1}^{n}\log(-f(oldsymbol{y}_{i}))
ight] + 1 \end{split}$$

#### The KALE divergence

Nguyen, Wainwright, Jordan, IEEE Transactions on Information Theory (2010); 27/34 Nowozin, Cseke, Tomioka, NeurIPS (2016)



$$egin{aligned} & ext{KALE}(oldsymbol{Q}, P) = \sup_{f < 0, f \in \mathcal{H}} E_P f(X) + E_oldsymbol{Q} \log\left(-f(Y)
ight) + 1 \ & f = -\exp\left\langle w, \phi(x) 
ight
angle_{\mathcal{F}} \ & \|w\|_{\mathcal{F}}^2 \quad ext{penalized} : \end{aligned}$$



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ight) + 1 \ & f = -\exp\left\langle w, \phi(x) \right\rangle_{\mathcal{F}} \ & \|w\|_{\mathcal{F}}^2 \quad ext{penalized} : \operatorname{KALE} \operatorname{smoothie} \ & \operatorname{KALE}(\mathcal{Q}, \mathcal{P}) = 0.18 \end{aligned}$$





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ight
angle_{\mathcal{F}} \ & \|w\|_{\mathcal{F}}^2 \quad ext{penalized}: \operatorname{KALE} \operatorname{smoothie} \ & \operatorname{KALE}(\mathcal{Q}, \mathcal{P}) = 0.12 \end{aligned}$$



#### The KALE smoothie and "mode collapse"

Two Gaussians with same means, different variance



### WAE-GAN Kale and WAE-MMD

#### The Wasserstein Autoencoder:



Tolstikhin, Bousquet, Gelly, Schölkopf (2018). New version with parameter sweep from 2019: see arxiv.

### WAE-GAN Kale and WAE-MMD

The Wasserstein Autoencoder:

Celeb-A performance (FID):

- WAE-MMD: 37
- WAE-GAN: 35
- Variational autoencoder: 45

WAE-GAN Kale and WAE-MMD

The Wasserstein Autoencoder:



FID Distribution for CelebA

Sweep over: architectures of the Encoder and Decoder (DCGAN or ResNet50v2), regularization coefficient, learning rates, kernel width,...Parameters in both in WAE-MMD and WAE-GAN (i.e. 31/34 learning rate, regularization coeff, etc) had the same ranges for both.

#### Divergences







Sriperumbudur, Fukumizu, G, Schoelkopf, Lanckriet, EJS (2012)

## References and further reading

#### Wasserstein distances:

- Peyré, Cuturi. Computational Optimal Transport (2019)
- Santambrogio. Optimal Transport for Applied Mathematicians (2015)

#### ■ The Maximum Mean Discrepancy:

- Gretton, Borgwardt, Rasch. Schölkopf, Smola. A kernel two-sample test. (2012)
- Arbel, Sutherland, Binkowski, Gretton. Gradient regularization for MMD GANS (2018)

#### ■ Variational estimates of *φ*-divergences:

- Nguyen, Wainwright, Jordan. Estimating Divergence Functionals and the Likelihood Ratio by Convex Risk Minimization (2010)
- Nowozin, Cseke, Tomioka. F-GAN: Training Generative Neural Samplers using Variational Divergence Minimization (2016)

#### Divergences and generative models:

- Arora, Ge, Liang, Ma, Zhang. Generalization and Equilibrium in Generative Adversarial Nets (GANs) (2017)
- Tolstikhin, Bousquet, Gelly, Schölkopf. Wasserstein Auto-encoders (2019 version)
- Huang, Berard, Touati, Gidel, Vincent, Lacoste-Julien. Parametric Adversarial Divergences are Good Task Losses for Generative Modeling (2018)
- Bottou, Arjovsky, Lopez-Paz, Oquab. Geometrical Insights for Implicit Generative Modeling (2018)

#### Bound for Jensen-shannon

Case of the Jensen Shannon divergence

$$egin{split} D_{JS}(oldsymbol{Q},P)\ &=rac{1}{2}\int p(z)\log\left(rac{2p(z)}{p(z)+q(z)}
ight)dz+rac{1}{2}\int q(z)\log\left(rac{2q(z)}{p(z)+q(z)}
ight)dz \end{split}$$

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ight)dz+rac{1}{2}\int q(z)\log\left(rac{2q(z)}{p(z)+q(z)}
ight)dz\ &\geq \sup_{f<0,f\in\mathcal{H}}\left\{\mathbf{E}_{P}f(X)\ &-\mathbf{E}_{oldsymbol{Q}}\left[-(f(oldsymbol{Y})+1)\log\left(rac{f(oldsymbol{Y})+1}{2}
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